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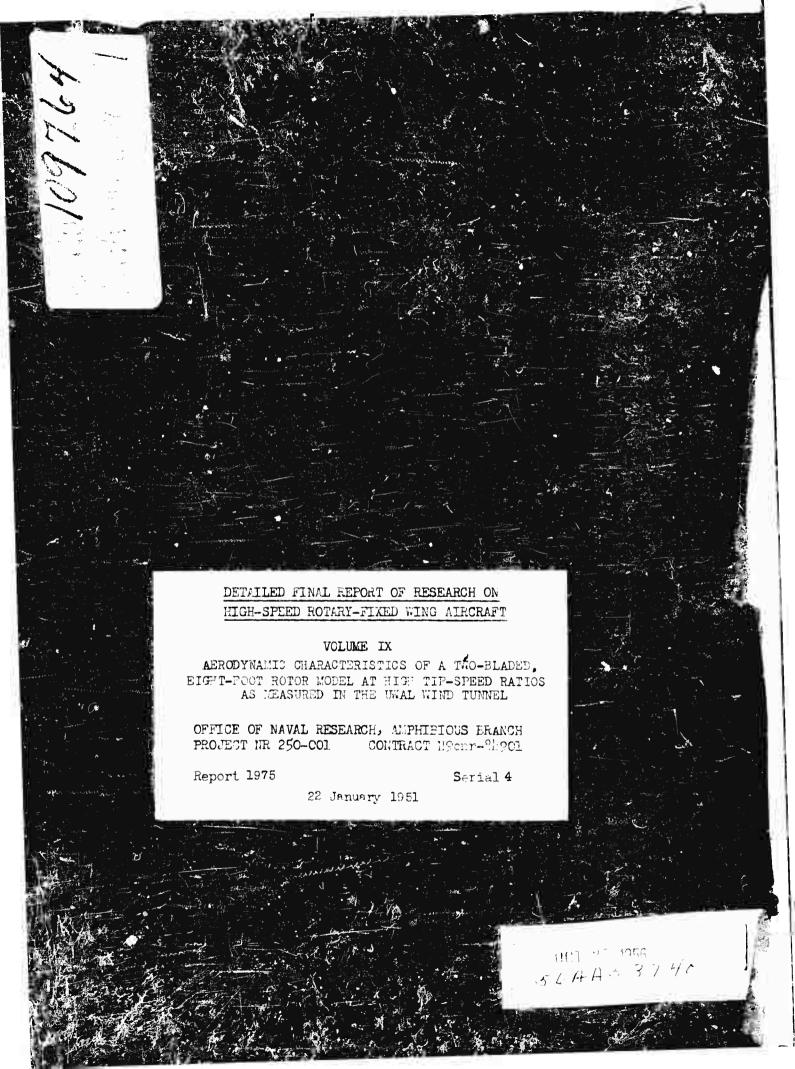


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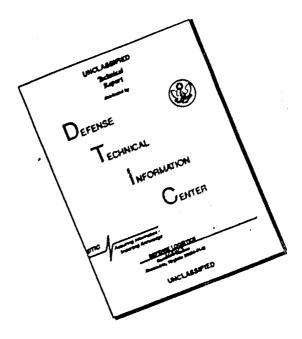




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MAC 273 (REV. 2-24-90)

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MCDONNELL Corporation
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DETAILED FINAL FILORT OF RESEARCH ON HIGH SPEED ROTARY-FIXED WING AIRCRAFT

#### ACTOWE IX

ANRODYNAL O CHAPACTURISTICS OF A TWO-BLADED.

EIGHT-POOP ROTOR LUDEL AT HIGH TIP-SPEED RATIOS

AS LEASURED IN THE EWAL WIND TURNEL.

SUBMITTED UNDER C stract N9c Ol to the Office of Naval Research, Amphibious Branch, Project NR 250-001

PREPARED BY\_ P.E. Head U. d. Holchemier

n. 1. hohenemser

APPROVED BY. C. H. Hurkamp

of charge

CONTENTIAL

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#### 1.0 SUMMARY

The results of two model test progress investigating the aerodynamic characteristics of a two bladed, see-saw rotor in the range of very high tip-speed ratios are presented in this report. This experimental work was done under contract for the Office of Naval Research and is the first portion of a broad program for investigating the characteristics of a rotor-fixed wing type of aircraft.

This report presents data for the rotor operating in the range of advance ratios from M = 0.5 to M = 3.0.

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#### 2.0 INTRODUCTION

Early in 1949 a contract was entered into by the Office of Naval
Research and NoDomnell Aircraft Corporation for research into the problem
of the rotor-fixed wing aircraft configuration. It was held that in order
to accomplish high level flight speed of the order of 300 to 400 miles per
hour, it would be necessary to have the rotor operate at tip-speed ratios
very much higher than are conventionally used in helicopters and autogyros.

Consequently, the test program reported herewith was undertaken.

The rotor model used was a two-bladed, see-saw type of rotor which was built from a salvaged rotor of the XE-20, "Little Henry", believpter. The diameter of rotor was reduced and a special hub mounting was devised for mounting the rotor in the twelve foot UWAL wind tunnel at the University of Washington, Seattle, Washington. The prototype rotor was postulated as a pressure-jet type of rotor having burners at the blade tips. To simulate the drag of such tip-burners, small spheres of various sizes were attached to the tips of the model blades.

The first series of tests with this rotor during July, 1949, clearly demonstrated the possibility of using a rotor at very high advance ratios where the efficiency of the rotor is eensiderably improved over the low advance ratio operation. However, it also because clear that the rotor was quite sensitive to small changes in rotor attitude.

After this first series of tests, the model was medified to eliminate most of the drag of the blade hub fittings which proved objectionable in the previous tests. This entailed reducing the dismeter of the rotor slightly and constructing a lens-shaped fairing for the rotor hub. Further, a device

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was designed for automatic control of the rotor attitude which was to govern the speed of the rotor.

The second series of tests was then conducted in the UNAL wind tunnel during Outgoon, 1949. These tests covered the high range of tip-speed ratios 1 2.5) and a large range of blade pitch angles ( @ =4-3.0° - A first enteretation and for both accelerating and decelerating tore applied to the retor. The serodynamic characteristics of the rotor as determined by these tests were in reasonable agreement with the characteristics as determined theoretically in Reference 1.

The governor, while capable of stabilizing the rotor speed for small attitude changes, would require major modifications in order to correct larger attitude changes.

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3.0 BINCUSTICM

2.1 Respose of the fests - The purpose of the first series of tests one to investigate the feasibility of operating a roter at unconventionally high advance ratios and to provide preliminary data required for a later and more emplete test progress.

The second series had the following purposes:

- a, Check the sporation of the automatic rotor attitude control.
- b. Determine the aerodynamic characteristics of the medified roter model without high fairing.
- e. Determine the influence of the long-shaped hab fairing.
- 8.2 Tost Reniment -
- 3.2.1 The Model -
- Soluted First Series of North The rotor model work in the first series of tests was a rotor which had been salvaged from the X5-20 Livile Sample beliespter and modified for use in the wind turned (See Figures 1 and 3). The outer partiess of the blades were removed to refuse the diameter to eight feet. Provision was made for mounting small-spinuse do the tips of the blades to simulate the effect of tip-jet units (See Figure 5). The lab was modified to allow the installation of a small electric motor for providing accelerating and decelerating torques to the rotors; an absorbe taches term generator was also incorporated. Figure 4 shows the lab mechanism and the reter control panel is shown in Figure 5.

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3.2.1.2 Second Series of Tests - For the second series of tests the model was modified somewhat. The hub fittings for the blades were greatly reduced in size to eliminate most of their drag (See Figure 6 and 7). This necessitated reducing the rotor diameter from eight feet for the original model to 7.58 feet. A lens-shaped fairing was designed to cover the blade hub fittings (See Figures 6 and 7).

A rotor attitude control governor was incorporated for a tabilizing the rotor in the high advance ratio range. This governor was a modified Curtiss electric propeller governor which was driven by a flexible shaft from the rotor and stabilized the rotor speed by energizing an electric linear actuator which varied the rotor attitude in the wind tunnel. The model with the governor and the necessary control equipment is shown in Figure 8.

#### 5.2.1.3 Model Data

	First Series	Second Series
Rotor diameter, feet	8.00	7.58
Mumber of blades	2	2
Blade chord, inches	6.2	6.2
Blade planform	Rectangular (extends from 1.4 ft. radius to 4.0 ft. radius)	Rectangular (extends from 0.54 ft. radius to 3.79 ft. radius.)
Solidity Ratio	.082	.087
Blade Twist	None	None
Airfoil section	NACA 0013	NACA 0013
Rotor type	See-saw blades	\$30-saw blades

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Solo Betrapentation

& Seed a Standard Wind Tennal Instrumentation - The standard wind instrumentation was used to measure three semponents in addition to the terest speeds

- a. lift
- . your moment (a measure of the terron of the rotor)
- is the instrumentation on the photo-pagel for the times balance system. The balance is eapshle of measuring six companents but only the three listed above were of interest in those tests. The instruments shown in Plante 9 are as follows:
- . 1. Beter RM indicator, showing double reter RFM
  - In lagle of attack of reter,
  - S. Clock
  - Carrie of your, was sero for all tests
  - To Mar feres, writch on left side indicates sign of drag force, grad on right side gives the total range of instrument scale in pounds
  - 6. Last force, switches to lest and right some as before
  - 7. Side ferce, positive if to the right, soon in upwind direction. switches to left and right came as before
  - 8. Pitching mement positive if tail heavy, around the mement center, which is 5.8" below the hab center. Switches to left and right same as before, except that switch on right side gives the total range of instrument scale in fach pounds.
  - 9. Rolling moment, switches to left and right some as before

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10. Eawing moment, positive if clockwise seen from above, which is an accelerating air moment for the rotor, switches to left and right same as before.

- 11. Rysamic pressure deviation from Q value as indicated in the upper right corner of the panel.
- 12. Air temperature indicator
- 15. Barces tris pressure indicater
- 3.2.2.2 Special Instrumentation for the Rotor Model Extra instruments were required for the rotor model. These were:
  - a. reter speed indicator (indicated 2.x.23 and was connected in parallel with the tachqueter on the photo pane).
  - b. retor driving motor ammeter

These instruments were located on the rotor control panel shown in Figure 5.

In addition, a special protractor was employed to measure the rotor tip-path plane angle of inclination. This angle was observed visually using the device shown in Figure 10.

- 5.8 Operating Limitations -
- 3.5.1 First Series of Tests -
- 5.5.1.1 Sec-cew Angle Limitation (approximately ± 12°) Under some by t conditions this limitation was difficult to observe and the blades hit the stops several times, leading to heavy vibrations and to destruction of safety flammes in the terms | balance system.
- 8.8.1.2 Reter Angle of Attack Limitation The upper limit of roter ongle of attack was given by interference with the fairing around the center

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portion of the model, approximately +15°. The lower limit of a was given by operational limitations and varied with reter pitch angle from  $\pm 2^{\circ}$  to  $\pm 6^{\circ}$ .

5.5.1.5 Terque Limitation .The accelerating or decelerating torque limit was given by the electric motor and by the gears between rotor shaft and electric motor, approximately 20 inch pounds. Termes of +12 and -15 insh peumds, corresponding to \$10 smps. in the armature of the electric motor sould be maintained continuously throughout the tests.

5.5.1.4 RFM Limitations ... A severe resonance of the model supports and balance existen was encountered at about 600 RFM. Replacing the netal ring around the leave shaft bearing by a saft subbar ring lessand the resonance frequency somewhat, but running through the resonance range caused severe vibrations and the breaking of safety flexures in the balance system. The original metal ring was, therefore, reinstalled and the operating rotor RM was limited to 500 RPM.

5.5.1.5 Tip Speed Limitation - The highest RFM for safe operation was 500 RPM which serresponded to a maximum tip speed of AR = 210 ft./sec.

5.5.1.6 Advance Ratio Limitation . The highest advance ratio which was measured was ALE 5.0. With increasing advance ratios the rotor became increasingly unstable and it was not possible to obtain steady conditions for high advance ratios.

3.3.1.7 Blade Pitch Angle Limitation - The instability mentioned before increased with blade pitch angle. The highest blade pitch angle for which

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fairly steady conditions could be reached up to  $\mu$  2.0 ms. The limitation in negative blade pitch angle was  $\theta$  = .6° and we given by the maximum flapping angle of  $bl2^\circ$  of the blades which impresses with blade pitch angle and with advance ratio ,  $\mu$  . The senfiguration with  $\theta$  = .6° accord, for this reason, only be measured up to an advance ratio of  $\mu$  = lo5. Within the measured blade pitch angle range from + 8° to -6° no difficulties were enscantered in starting the roter.

those described above except for the RFM limitations were about the same as those described above except for the RFM limitation. The severe resonance which was observed for the first model at 600 RPM was reduced to 450 RFM because of the greater elasticity of the blade root section. Next of the tests were conducted at below resonance roter speeds. Same of the tests at above resonance roter speeds and some tests which were inadvertently run in the resonance range resulted in breaking the flexures in the terms! balance system.

#### 8.4 Test Presidere

- 5.4.1 Piret Series of Tests After a few preliminary runs to check out the apparatus, the following test precedure was adopted:
  - a. Set the blade pitch angle.
  - b. Install the tip-drag spheres if required for the particular test.
  - .. Betablish a nominal rotor speed of \$75 rgm.
  - d. Establish the proper tunnel speed to obtain the desired advance ratio.
  - e. Take photo-panel picture and simultaneously observe and record the tip-path plane angle of attack.

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f. httrodaus an accelerating or decelerating torque as required and repeat (e), (d) and (e) above.

#### 8.4.2 Becand Series of Tests

\$.4.2.1 Tests Without Automatic Roter Attitude Control - The procedure for these tests was as follows:

- a. Set the blade pitch angle.
- b. Install the tip-drag spheres if required for the particular test.
- e. Retablish a nominal roter speed and tunnel speed in accordance with the following table:

·· µ	.5	.75	1.0	1,25	1.5	2.0	2.5
SIR.	149	128	112	29.5	89.5	74.5	. 64
V. aga	74.5	96	112	124	· 134	143	160
Q. Mark	34	23.5	32	39.5	46	56.5	65 ′
RIM	<b>55</b> 0	475	415	470	550	<b>27</b> 5	23 5

The RFM was different for each advance ratio so as to obtain a constant tip speed at the advancing blade rather than a constant RFM as in the first test series. The constant tip speed tests give a more realistic picture of the reter characteristics since the actual aircraft probably will operate under the same conditions. The tip speed at the advancing blade was sheem as 225 mgh.

- d. Take photo-panel picture and simultaneously observe and record the tip-path plane angle of attack.
- 2. Introduce an accolerating or decolerating tarque as required and repeat (e) and (d) above.

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5.4.2.2 Tests With Automatic Rotor Attitude Central - The procedure for these governor tests was as follows:

- a. Set zero blade pitch angle
- b. Establish rotor and tunnel speeds in accordance with (e) of Section 3.4.2.1.
- c. Apply a sudden one degree rotor attitude disturbance.
- d. Cheerve the amplitude of the RPM oscillations and the time required for the disturbance to subside.

#### 3.5 Test Results

S.5.1 First Series of Tosts - The first series of tests was intended mainly as a preliminary investigation of the feasibility of operating a roter at the conventionally high advance ratios. It was demonstrated that advance ratios of the order of 2.5 to 5.0 were possible so the second test series described below was planned to fully investigate the high advance ratio range.

We quantitative data are given for the first test series because they are of doubtful value as a result of the poorly designed and which increased the drag of the rotor considerably and contributed essentially to lift.

- 3.5.2 Second Series of Tests -
- 5.5.2.1 Corrections to Photo-Panel Data -
- a. CC Correction:

The indicated values of of were within 0.10 of being identical with the actual values and no correction was necessary. The wind

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tunnel wall correction of and was in the order of Oul and, therefore, megligible.

#### b. Lift Cerrection -

The lift was corrected for the lab lift which was determined by tests without blades. The hab lift is approximately independent of the angle of attack of the reter and of the rotor RPM and only dependent on the tunnel speed. The following values were used:

where LH (1b.) = for q (1b./ft²) = 0<sub>0</sub>5 14 1.5 1.9 56.5 65

The wind tunnel wall correction for the lift is negligible because of the small lift coefficient (maximum C<sub>T. 00</sub> 0.02).

#### e. Drag Correction -

The drag was corrected for the hub drag as determined by tests without blades. The hub drag is appreximately independent of the angle of attack of the rotor and of the rotor RFM and only dependent on the tunnel speed. The following values were used:

where DH (1b.) a for q (1b./ft.) 7.7

The wind tunnel wall correction for the drag is negligible as for OC and for the lift.

#### Torque Cerrection -

The yearing moment, My, is appreximately equal to the rotor torque, since the shaft axis was inclined only a few degrees with respect to the vertical axis. The targue was corrected for the hab torque. The following values were used:

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#### . Lift to Drag Ratio Correction -

The lift to drag ratio of the rotor was corrected for rotor torque by using instead of the drag, D', the value:

= roter rading)

is the equivalent lift to drag ratio and is usually looked upon as an appropriate efficiency figure for a roter.

3.5.2.2 Transfer of Data to Scofficient Form - The force and moment measurements were converted into coefficient form by the following equations:

12, mph = 0.135 RPM

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#### \$.5.5 Sample Plots of Bata

5.5.3.1 Thrust Coefficient - Figure 11 shows the thrust esofficient,  $G_T$ , against C for zero tip drag and for a blade pitch angle,  $C = -1.5^{\circ}$ . The slope of the  $C_T - C$  curve becomes very steep at higher advance ratios, C. The blade loadings, C (C ) values up to 0.35 were measured. The autoretation curve indicates clearly the instability at higher advance ratios. Above C 1.25 this curve is nearly vertical and small changes in C have a very large affect on the equilibrium advance ratio, C ; that is, on the equilibrium RFM. Below C 2 C 10 autoretation is possible.

5.5.3.2 Terque Coefficient - Figure 12 shows the torque coefficient,  $C_Q$ , pletted against 65 for zero tip drag and for a blade pitch of  $\Theta$  = -1.5°. Positive  $C_Q$  corresponds to power input into the retor, negative  $C_Q$ , to power output from the rotor. The dotted line refers to the autorotation with hab, and the ordinates of this curve represent the hab torque which was subtracted from the measured torque. The  $C_Q$  -  $C_Q$  curves also become very steep at higher advance ratios, M.

3.5.3.5 Tip-Path Plane Angle of Attack - Pigure 13 shows the rotor plane angle of attack,  $\alpha_R$ , pletted against  $\alpha_R$  for sere tip drag and for a blade pitch of  $\alpha_R = 1.5^\circ$ . The  $\alpha_R = \alpha_R$  curves increase their slepe with  $\alpha_R$ , indicating a high sensitivity to small  $\alpha_R$  changes.

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5.5.5.4 Or & and Con As Functions of M - Figure 14 shows Cy C, and CR pletted against 1 fer G : 1.5° in autoretation. The flat Cl-12 curve for higher 12 again indicates the exetable charactor of these conditions. ( $\alpha_{e}$ - $\alpha$ ) is the flapping angle of the blades which is quite moderate for  $\Theta$  = -1.5°.

8.5.3.8 Drag, Lift, and Lift-to-Drag Ratio A Penetian of M - Figure 15 shows the lift to drag ratio, L/D, (called L'/D in Section 5.5.2) the lift esefficient, CL; and the drag scefficient, Cn, of the roter without hub plotted against advance ratio, M., for G . -1.50 in autoretation. The increasing L/D values and the decreasing CI values with higher edvance ratios indicate that from a point of view of performance at high speed large advance ratios are desirable.

5.5.5.6 Torque Coefficient For Various Blade Pitch Angles - Figure 16 shows the torque coefficient, on plotted against of fer various blade pitch angles,  $\theta$ , and for an advance ratio of  $\mu$  = 1.5. Note that a decrease in blade pitch in this region increases the decelerating terms, which is opposite to the effect of blade pitch changes in the helicopter flight some dition. The reter is less sensitive to a changes (more simble) at lawer blade pitch angles.

5.5.5.7 Refeet of Blade Angle on Op, 65, and 65 - Figure 17 shows the effect of blade pitch engle,  $\Theta$  , on thrust coefficient,  $C_{T}$ , on C, and on Ag for M = 1.5, in autoretation. The flapping angle (Ag - A) is sero for  $\theta$  = -2.5° and increases rapidly with negative  $\theta$  .

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5.5.3.8 Riffect of Blade Ample on (L/D),  $C_L$  and  $C_{D^{co}}$  Pigure 18 shows the effect of blade pitch angle,  $\Theta$ , on lift-to-drag ratio, L/D, on  $C_L$ , and on  $C_D$ . While  $C_L$  and  $C_D$  decrease with negative  $\Theta$ , the L/D ratio has a flat optimum at about  $\Theta$  = -1.5°.

5.5.4 Tests With the Automatic Roter Attitude Central - Because of several delays and required modifications of the test equipment the governor tests were reduced somewhat in sceps. The tests were made for only one blade pitch setting,  $\theta=0^{\circ}$ , and for sere torque. Advance ratios of 0.5, 1.0, 1.5, and 2.0 were investigated.

It was found that the RFM oscillations damped out after two to three oscillation periods after a sudden one degree rotor attitude disturbance. But while the oscillations damped out quickly, the maximum RFM error was such too high ( +25% for  $+1^{\circ}$  attitude change and -4% for  $-1^{\circ}$  attitude change).

3.5.5 Experimental Data - The complete data assumulated during the second series of tests is presented in Section 7.0.

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#### 4.0 CONCLUSIONS

The execut series of tests confirmed the results of the first series that auteretation of the VTO rotor at high advance raties is very advantageous from a point of view of blade lesses. The drag coefficient of the blade without hab, referred to the rotor disc area, is only 0,001 at #2.0. This means that a 50-feet rotor, suitable for a 20,000 pound rotor-fixed wing aircraft, would only represent the equivalent of two square feet parasite drag area. This drag is not totally parasitio because the rotor also produces a lift force up to 15 times greater than this drag. The over-sensitiwity of all roter characteristics with respect to roter angle of attack changes should be mitigated because otherwise even mederate gusts would cause excossive flapping of the blades. These tests have been extended up to an advence ratio of 2.5, which corresponds to a flight speed of 390 mph with a tip systed at the advencing blade of 800 ft./sec. or to 540 mph with a tip speed of 700 ft./ese.

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#### 5.0 MEPERSHURS

1. Mead, R. B.

The Results of an Analytical Study of the Aerodynamic Roter Cheresteristies at High Tip-Speed Batics. MAC Report No. 1686, 12 May 1950. MAC 231C (REV. 6-6-49)

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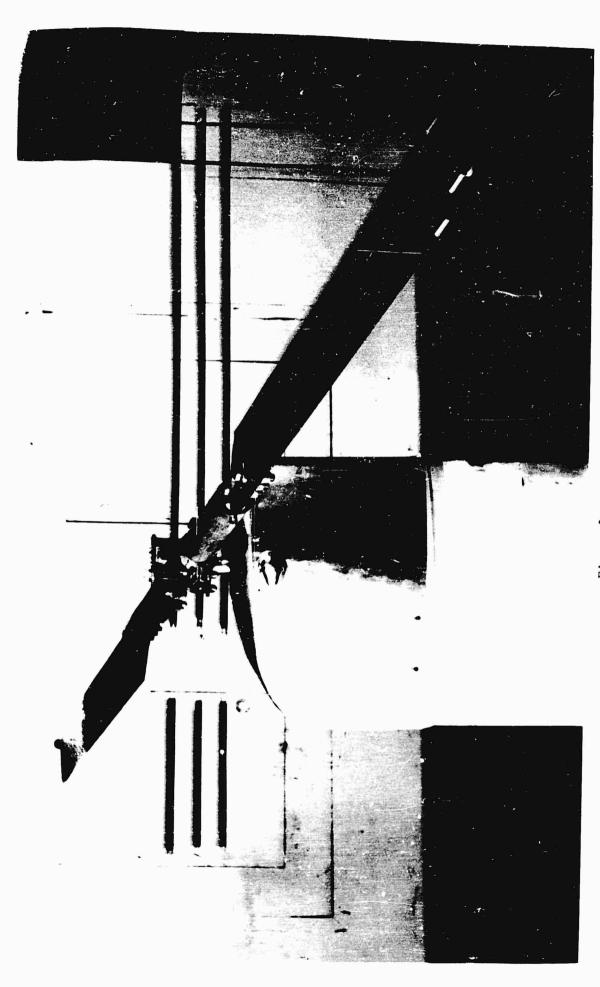
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6.0 PHOTOGRAPHS AND SELECTED
TEST RESULT GRAPHS

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Figure 1 Side View of Model as Installed in the Wind Tunnel (First Series of Tests)

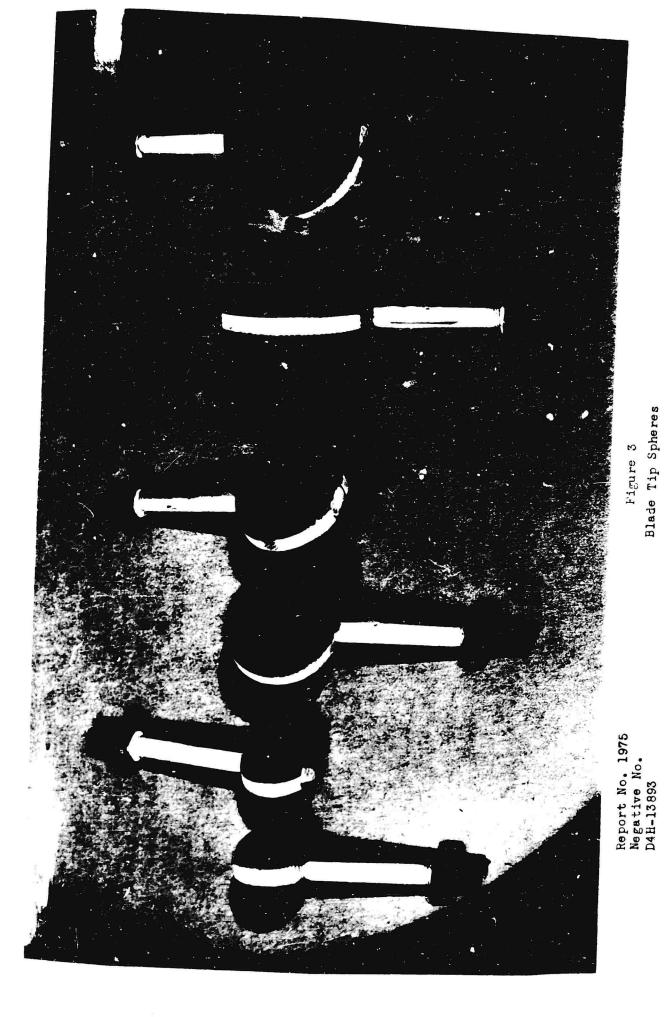
Figure 2

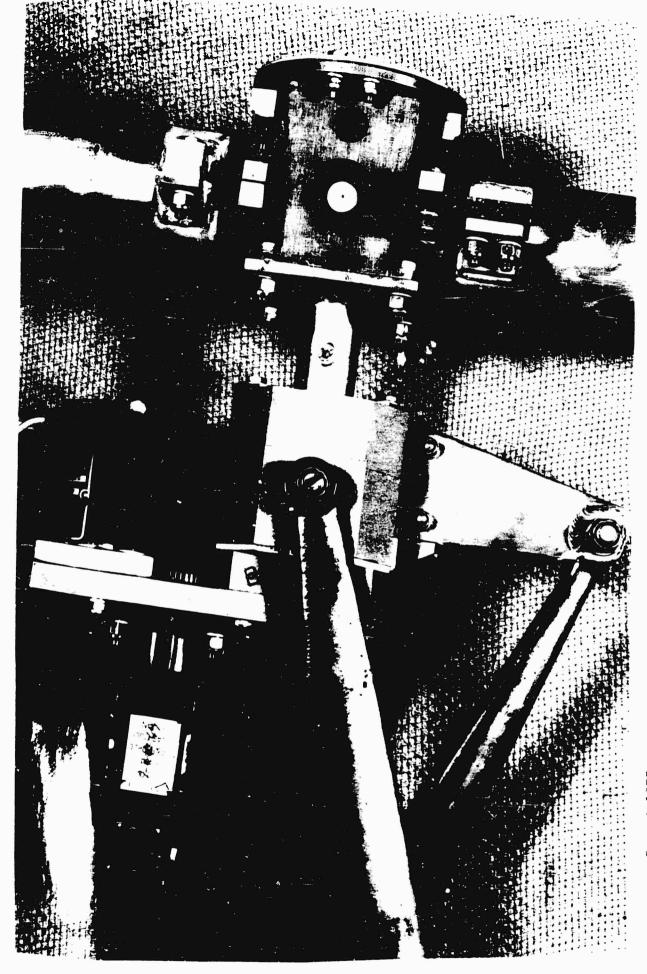
Front View of Acdel as Installed by the Wind Tunnel (First Series of Tests)

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Center Portion of Model Including Fork and Pitch Arm of Tunnel Equipment (First Series of Tests) Figure 4

Report 1975 Negative No. D4H-13896

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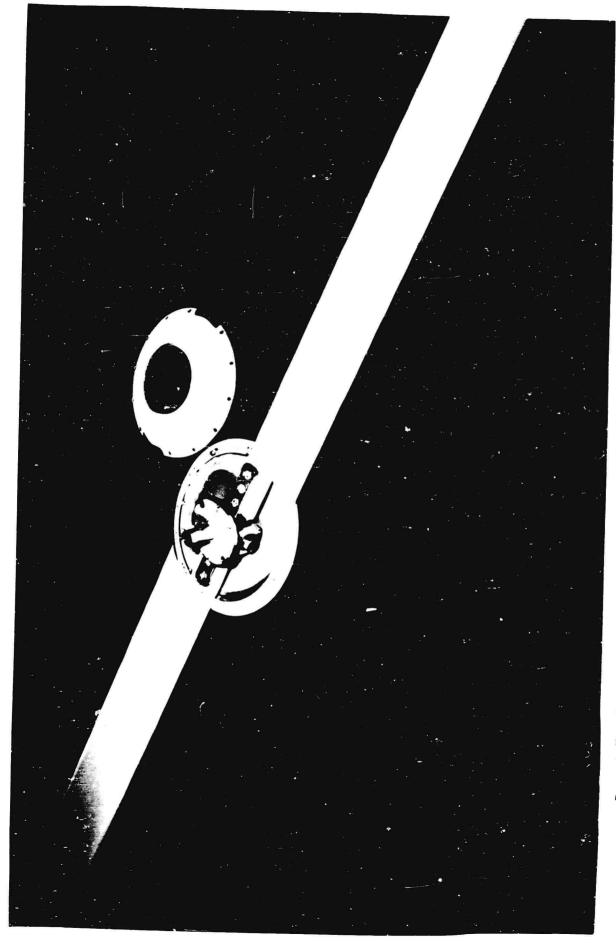
25 Page



REPORT 1975 NEGATIVE D48-15435

FIGURE 6 - REVISED ROTOR MODEL WITH HUB-FAIRING (SECOND SERIES OF TESTS)
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PAGE 26



Report No. 1975 Negative No. D4R-15436

Figure 7
Revised Rotor Model With One Section of Hub Fairing Removed (Second Series of Tests)

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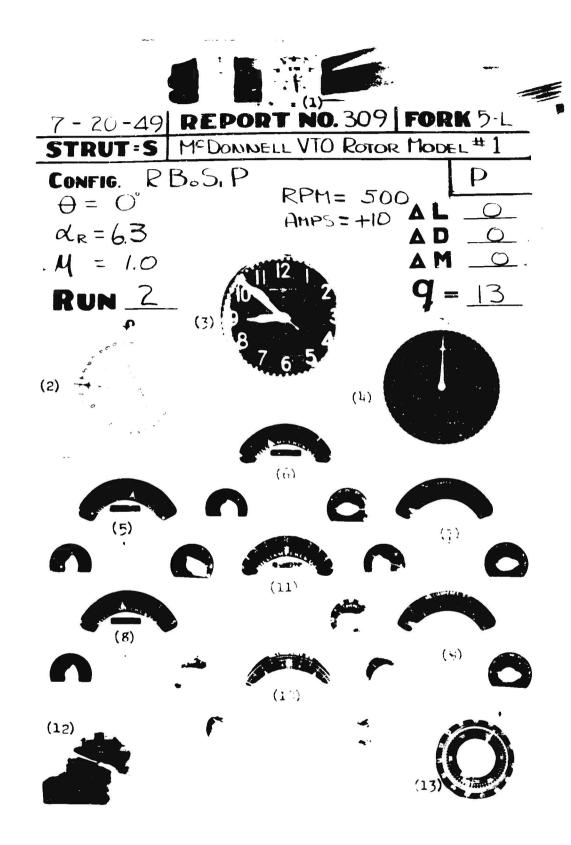


FIGURE 9. TYPICAL PHOTO-PANEL PHOTOGRAPH CONFIDENTIAL

Figure 10 Device for Measuring the Attitude of the Rotor Tip Path Plane

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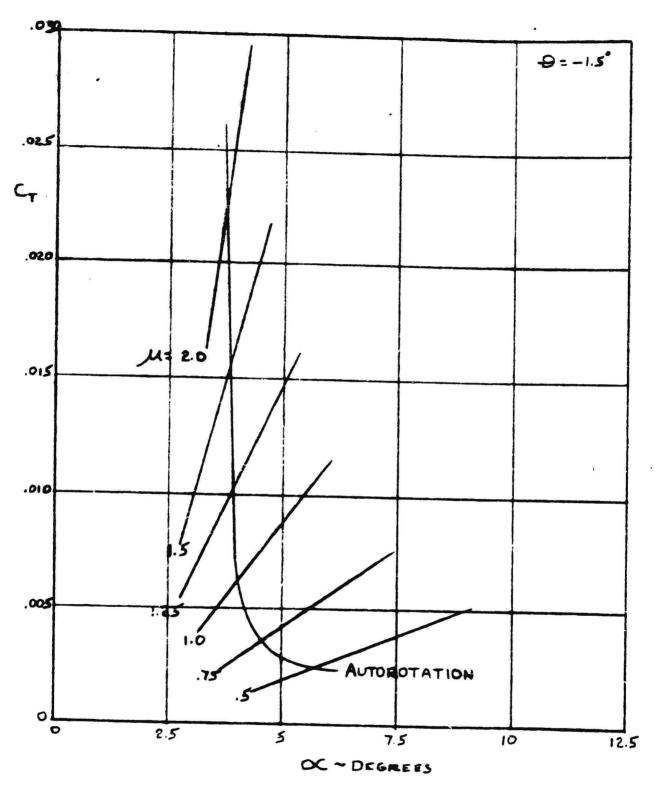


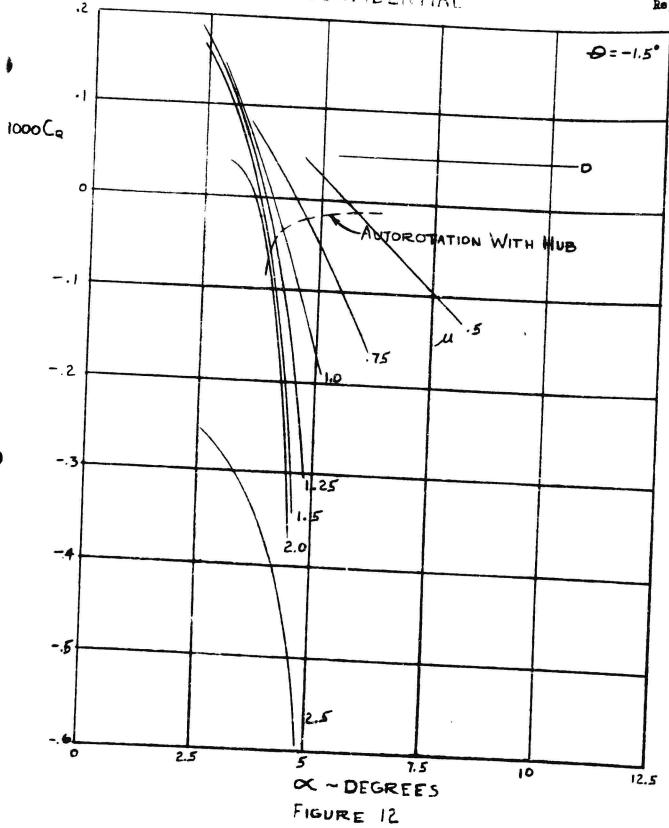
FIGURE 11

THRUST COEFFICIENT C. PLOTTEDAGAINST OC FOR ZERO TIP DRAG AND FOR BLADE PITCH 8: -1.5°

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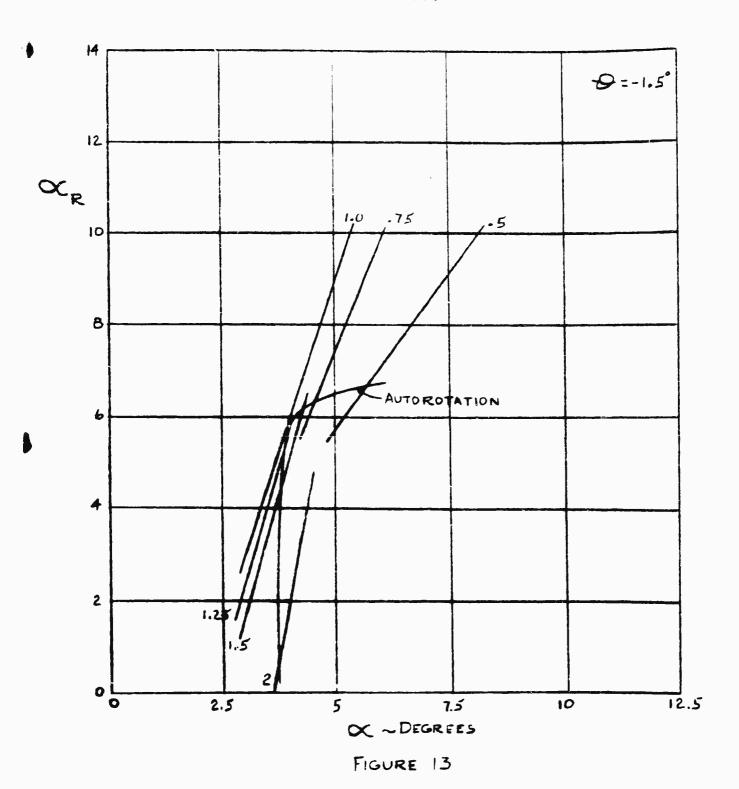


Page 32 Report 1975



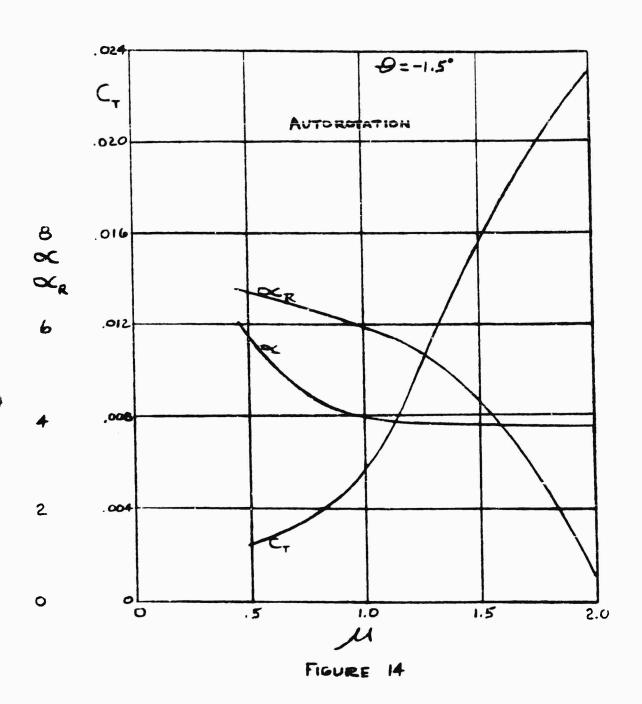
TORQUE COEFFICIENT CQ PLOTTED AGAINST & FOR ZERO TIP DRAG

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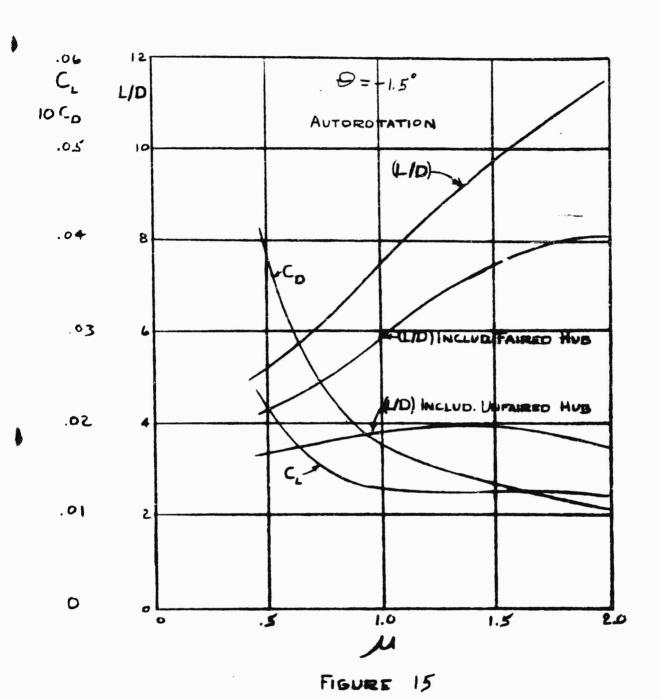
ROTOR PLANE POSITION OCR PLOTTED AGAINST OC FOR ZEROTIP DRAG AND BLADE PITCH &=-1.5°

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THRUST COEFFICIENT CT , POSITION OF CONTROL PLANE OF AND POSITION OF PLANE OF ROTATION OR PLOTTED AGAINST ADVANCE RATIO U FOR BLADEPITCH \$2 -1.5° IN AUTOROTATION

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LIFT TO DRAG RATIO (L/D), LIFT COSFFICIENT C. AND DRAG COFFFICIENT C. PLOTTED AGAINST ADVANCE RATIO M FOR BLADE PITCH --1.5° IN AUTOROTATION

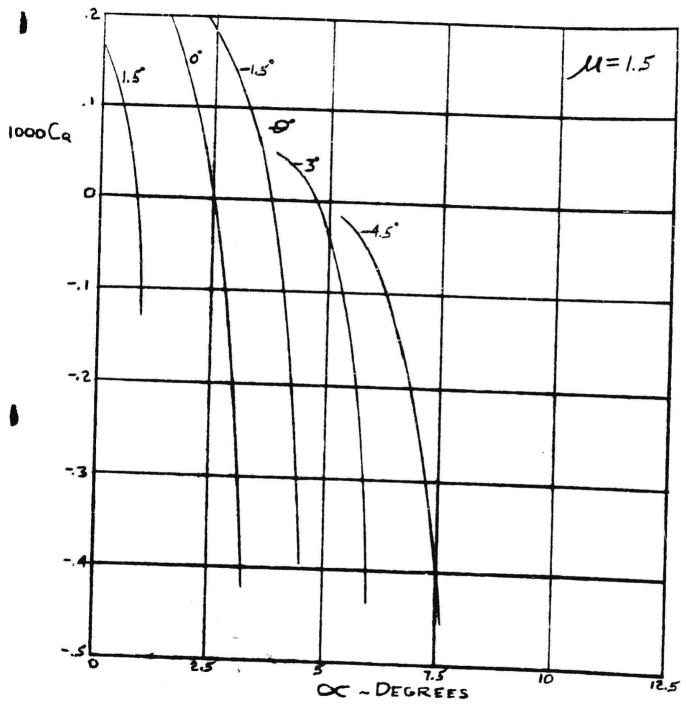
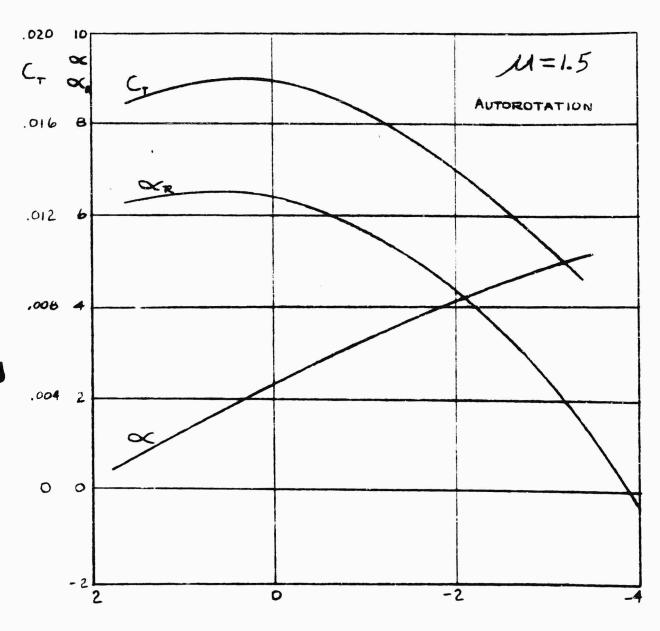


FIGURE 16

TORQUE COEFFICIENT CQ PLOTTED AGAINST OF FOR ZERO
TIP DRAG AND ADVANCE RATIO ME 1.5



O ~ DEGREES FIGURE 17

THRUST COEFFICIENT CT , Position OF CONTROL PLANE OC AND POSITION OF PLANE OF ROTATION OR PLOTTED AGAINST BLADE PITCH & FOR ADVANCE RATIO M=1.5 IN AUTOROTATION

## CONFIDENTIAL

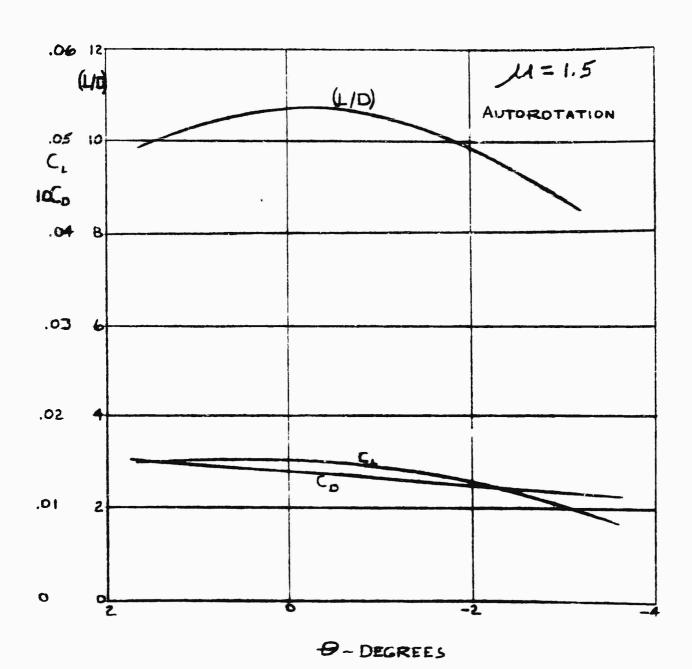


FIGURE 18

LIFT TO DRAG RATIO (L/D), LIFT COEFFICIENT C. AND

DRAG COEFFICIENT CD PLOTTED AGAINST BLADE PITCH

ANGLE & FOR ADVANCE RATIO M=1.5 IN AUTOROTATION

CONFIDENTIAL

DATE 22 January 1951 MCDONNELL Single Coperation ST. 1888 3, Missouri CONFIDENTIAL MODEL

7.0 TEST RESULTS IN GRAPHS

CONFIDENTIAL

MAC 281C (REV 6-6-49)

DATE 22 January 1951

MCDONNELL Strongt Corporation
ST. LOUIS 3, MISSOURI

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REVISED\_\_\_

REPORT 1975

MODEL

REVISED... CONFIDENTIAL

## SYMBOLS

·a <sub>1</sub>	Longitudinal Tilt of Tip Path Plane
₿ <sub>o</sub>	Configuration Without Tip Balls
B <sub>1</sub>	Configuration With Small Tip Balls
D <sub>2</sub>	Configuration With Large Tip Balls
$c_{\mathbf{D}}$	Drag Coefficient
$c_{\mathtt{L}}$	Lift Coefficient
CQ	Torque Coefficient
C <sub>T</sub>	Thrust Coefficient
D	Drag in Pounds
L	Lift in Pounds
Q	Torque in Foot-Founds
F	Dynamic Pressure, Lbs./Ft.2
R	Retor hadius, Feet
(L/D)	Lift to Drag hatio
X	Rotor Control Plane Angle
0	Collective Fitch of hotor Blades
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Page 4/ Report 1975 Measured Extrapolated Constant Co +30 - 1 + 0001

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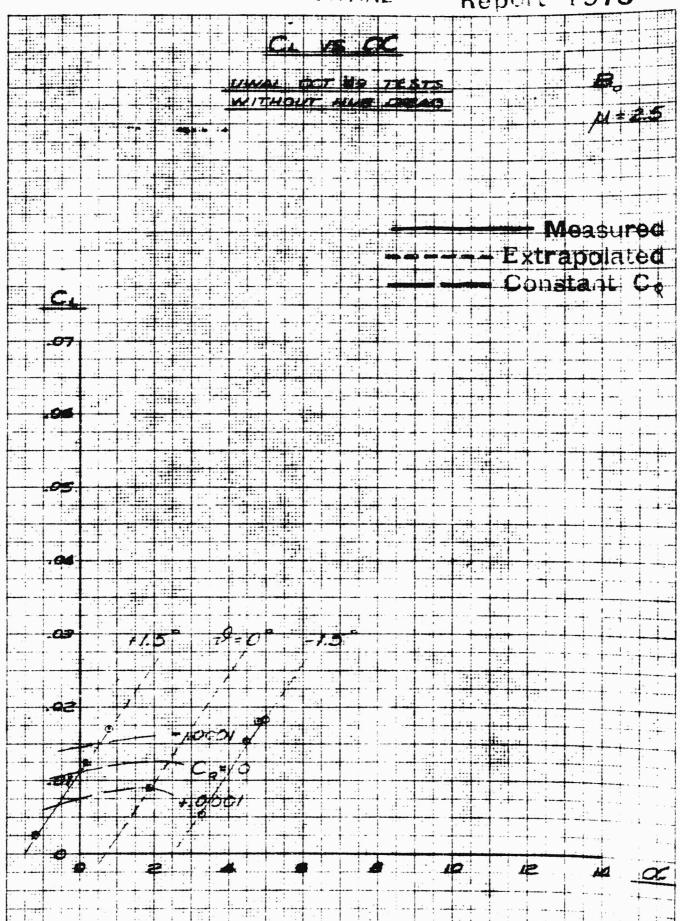
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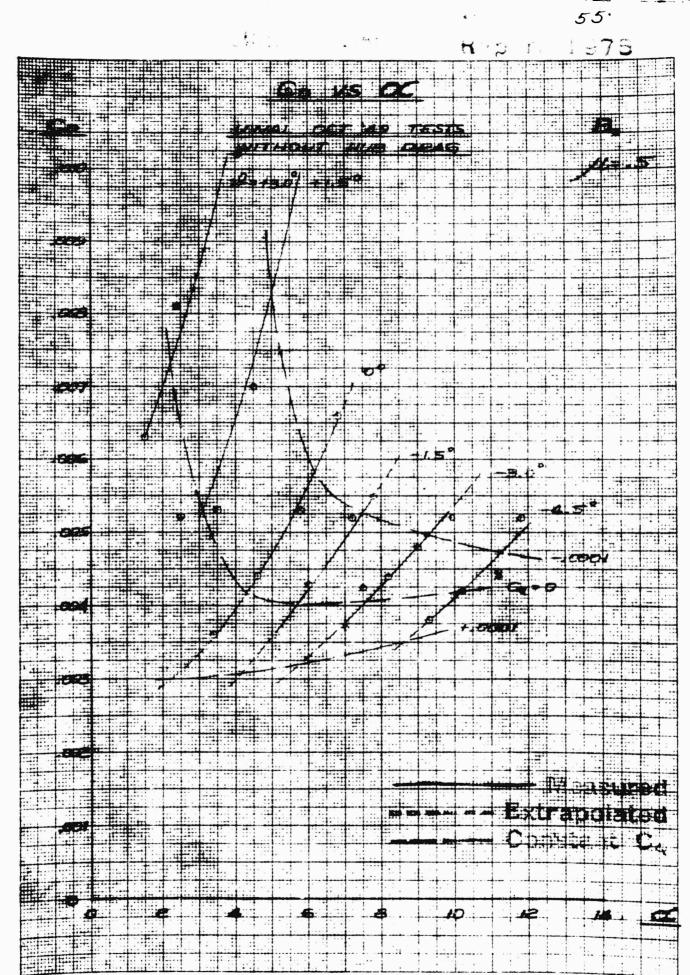
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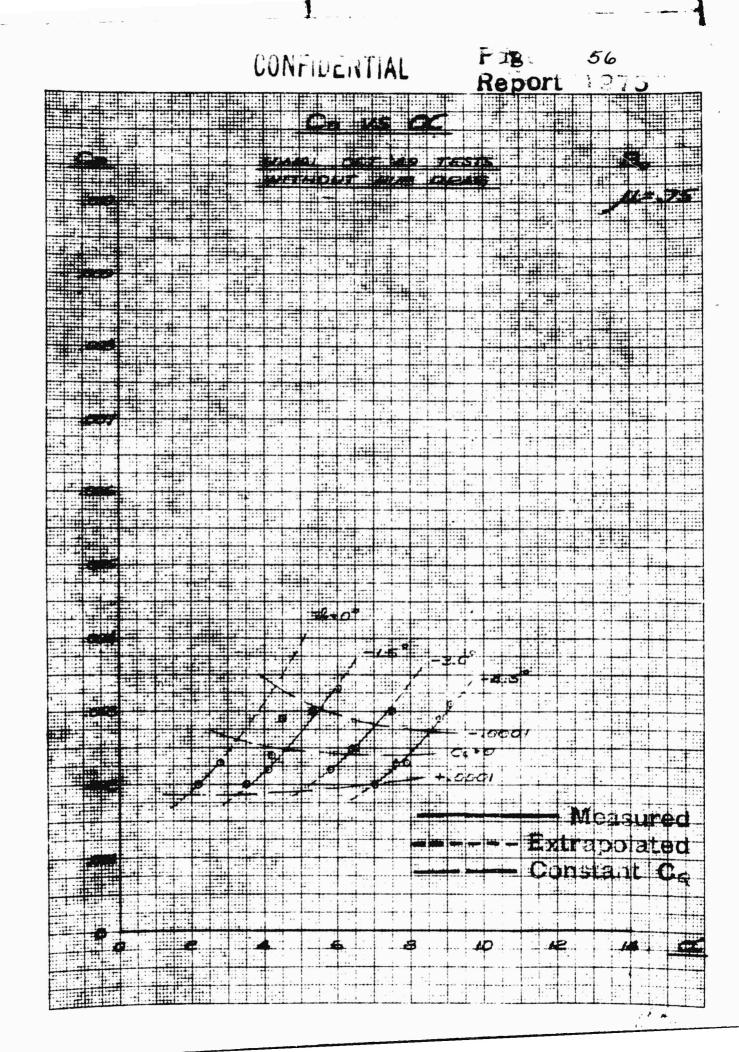
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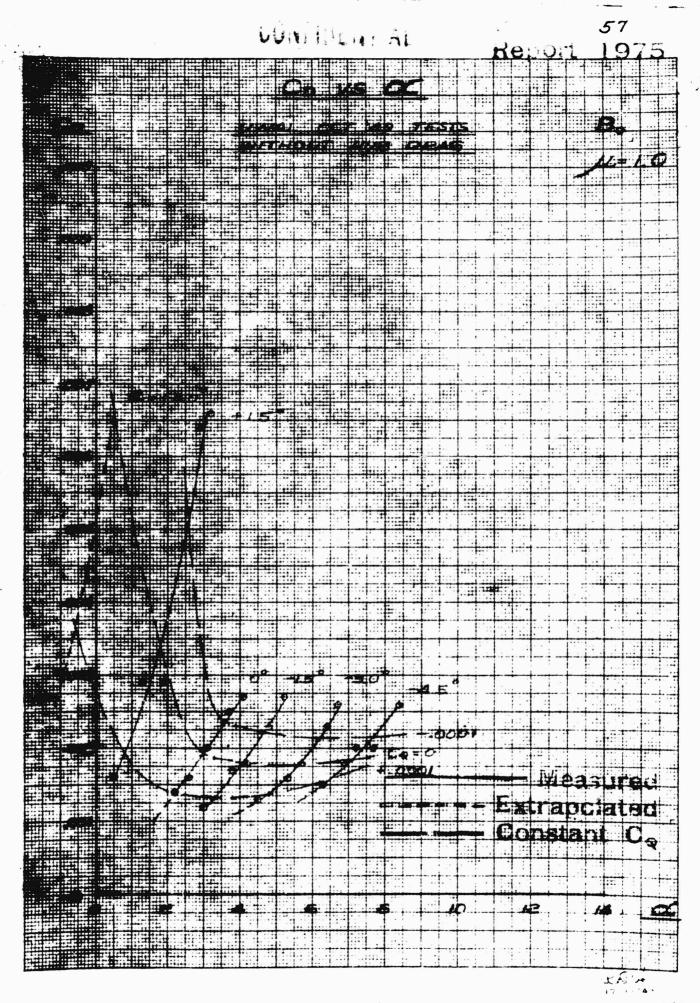
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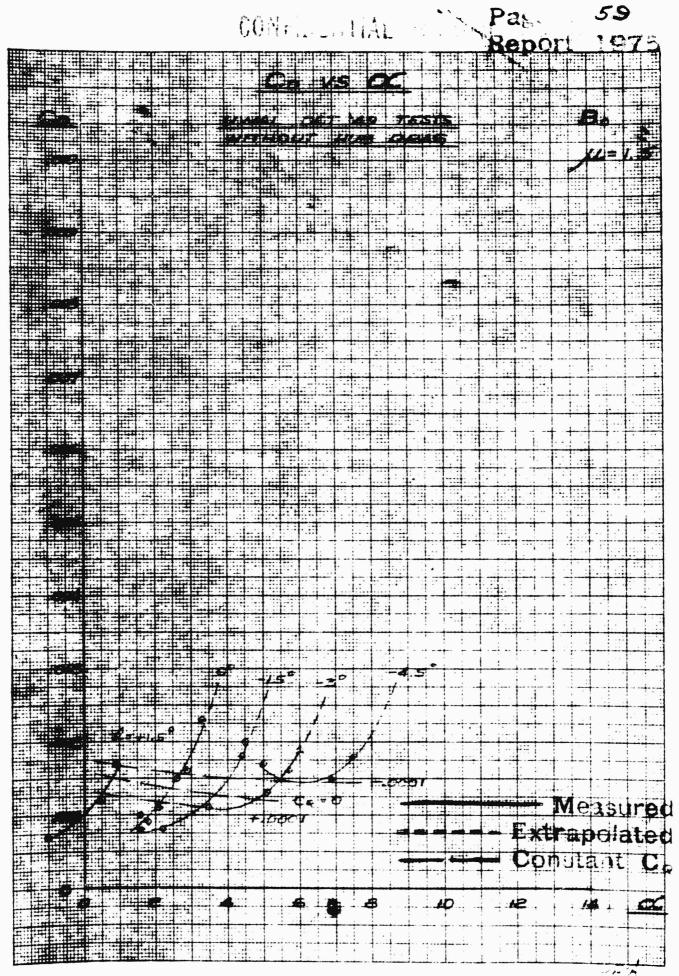




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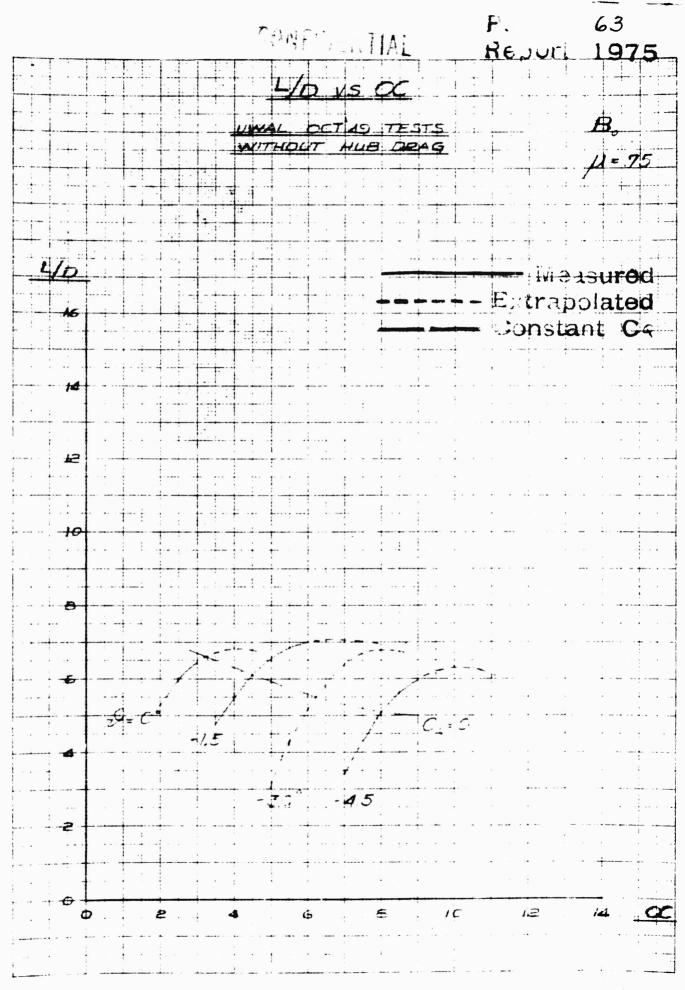
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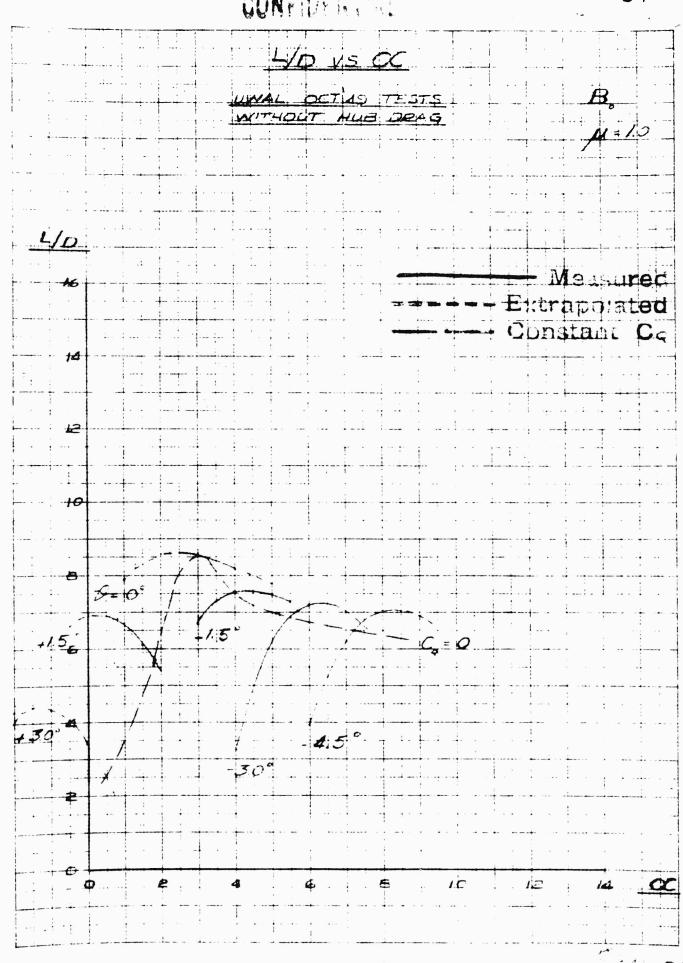
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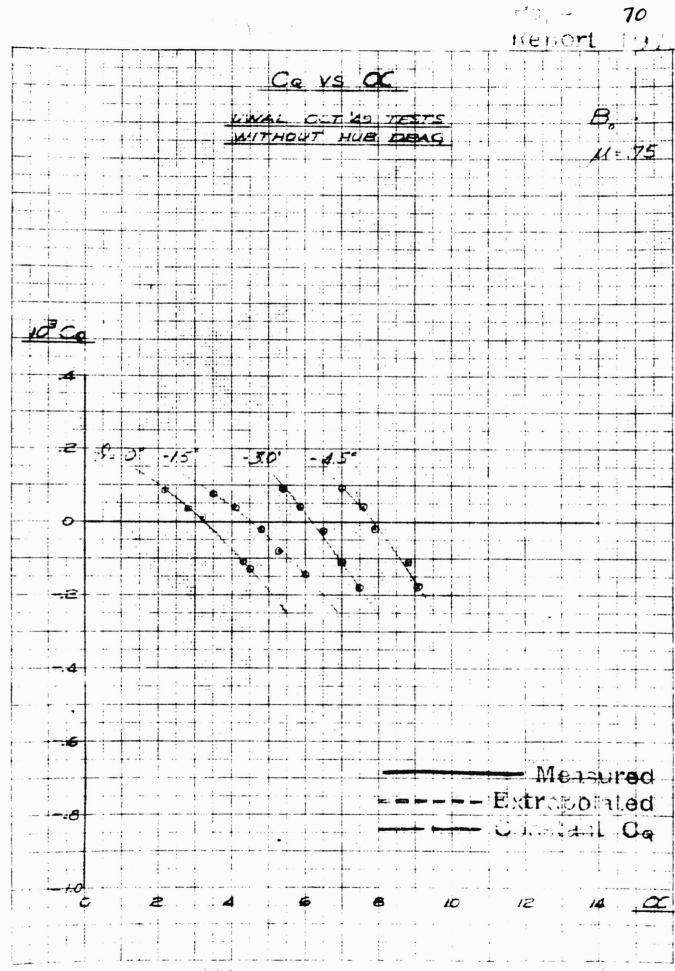
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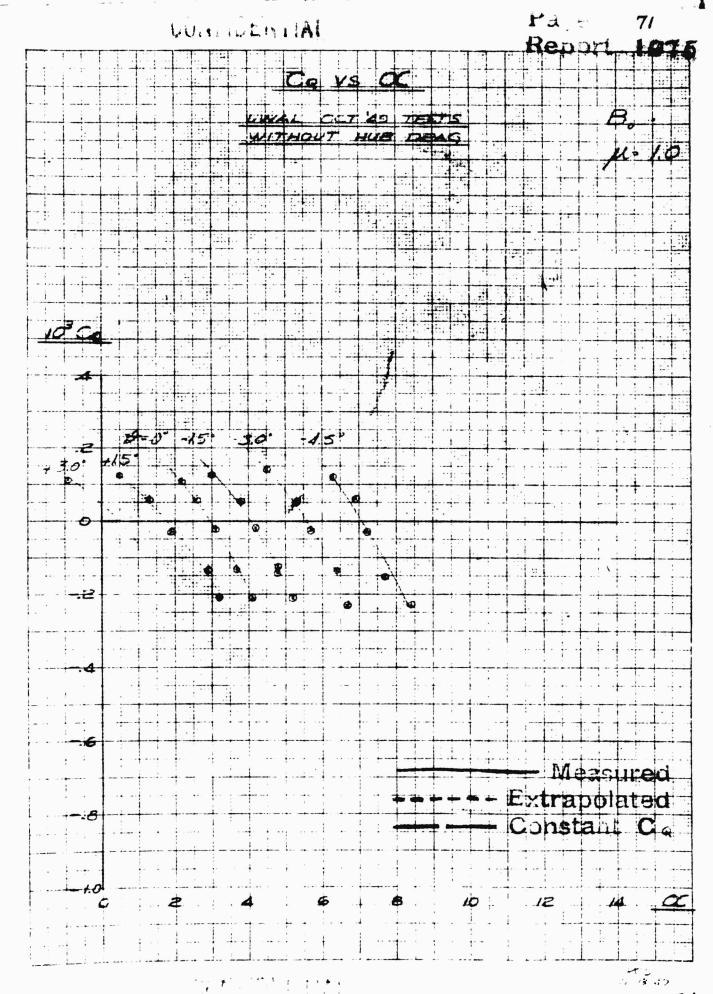


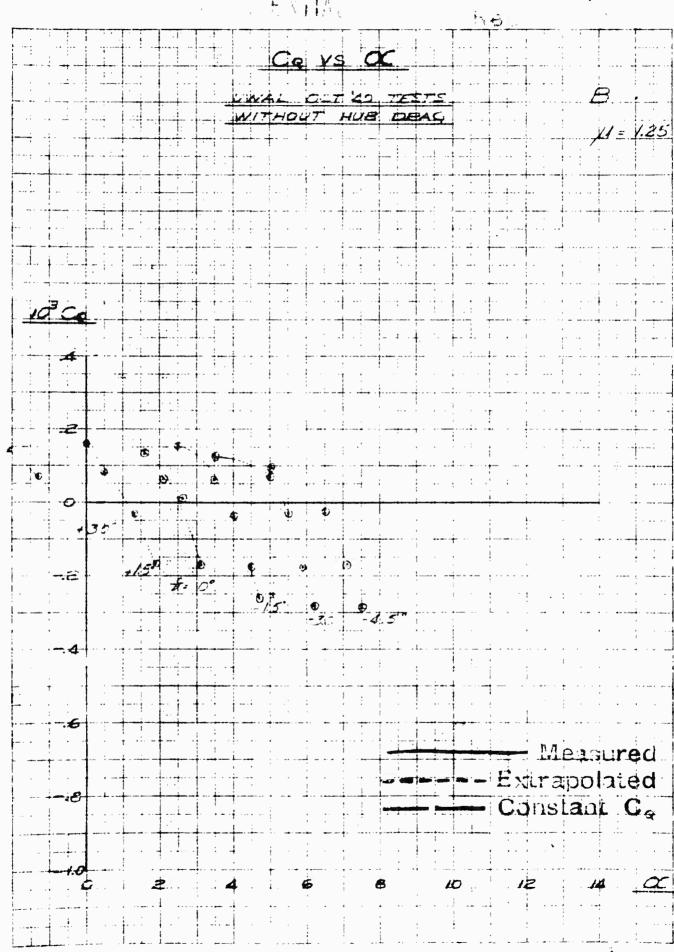


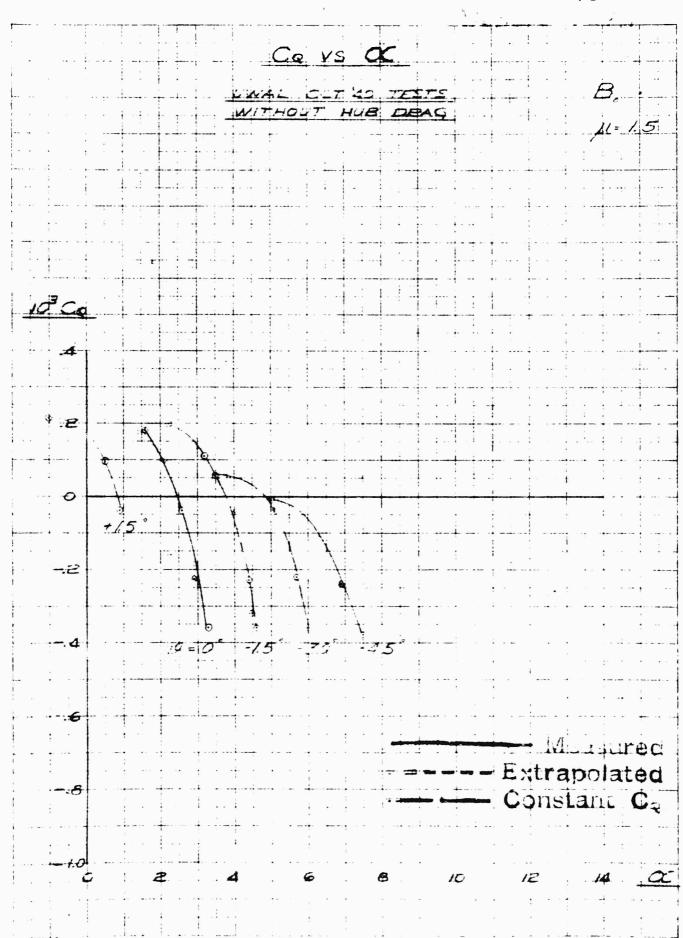
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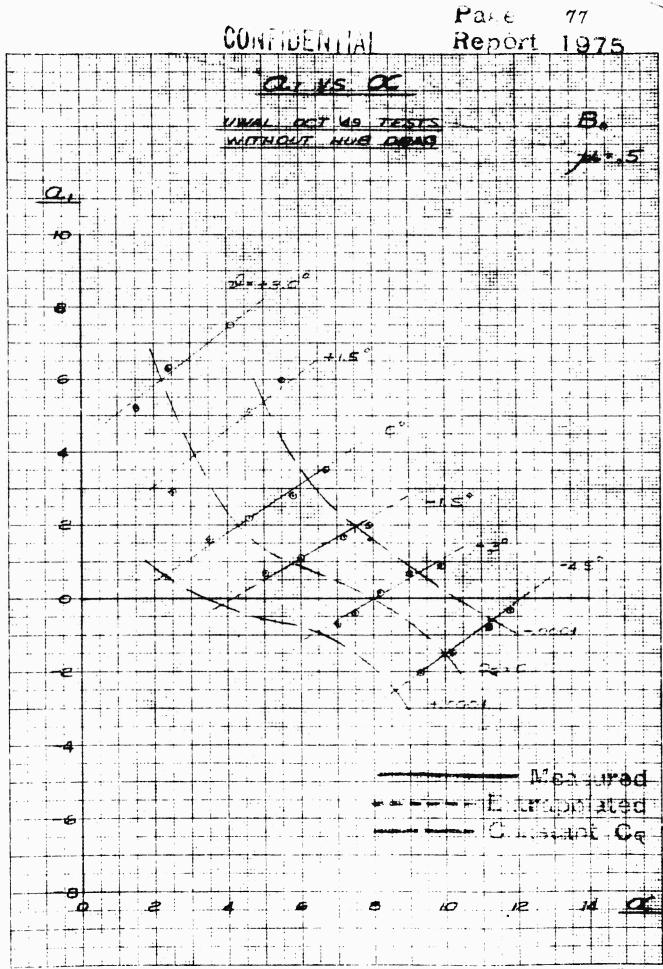


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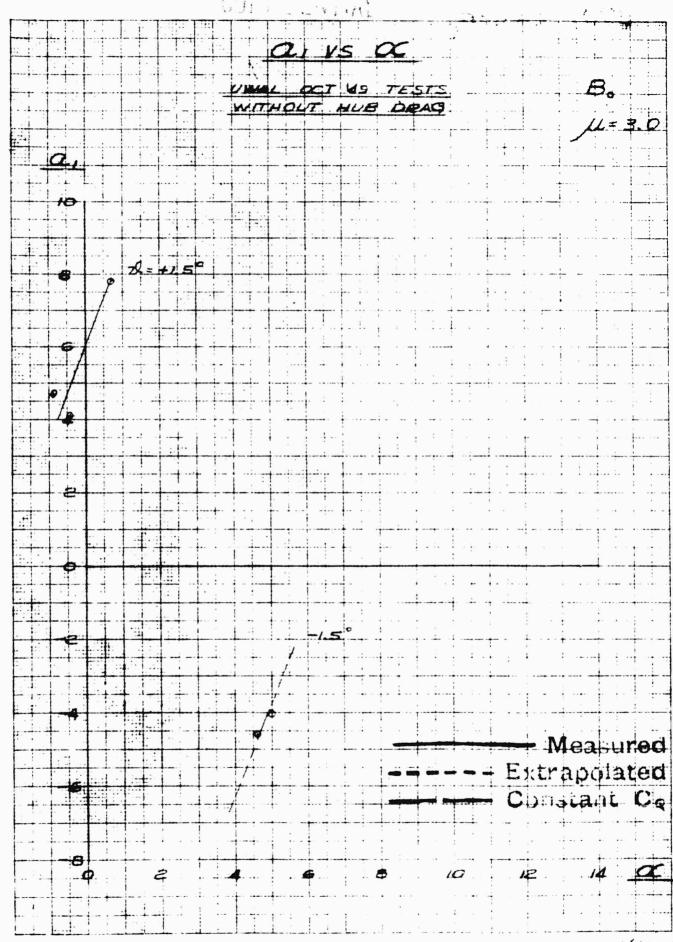
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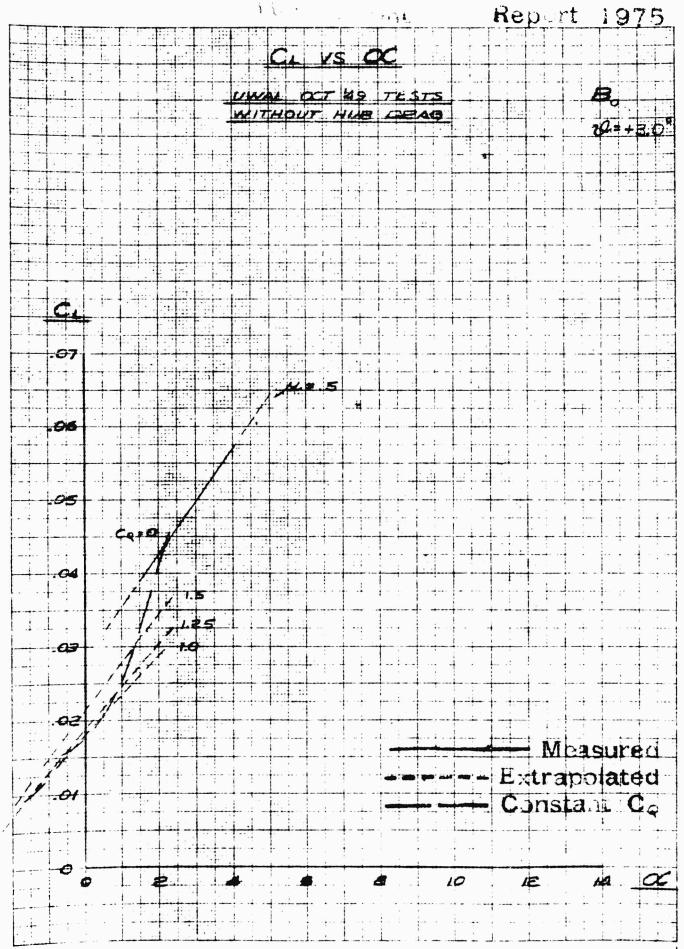
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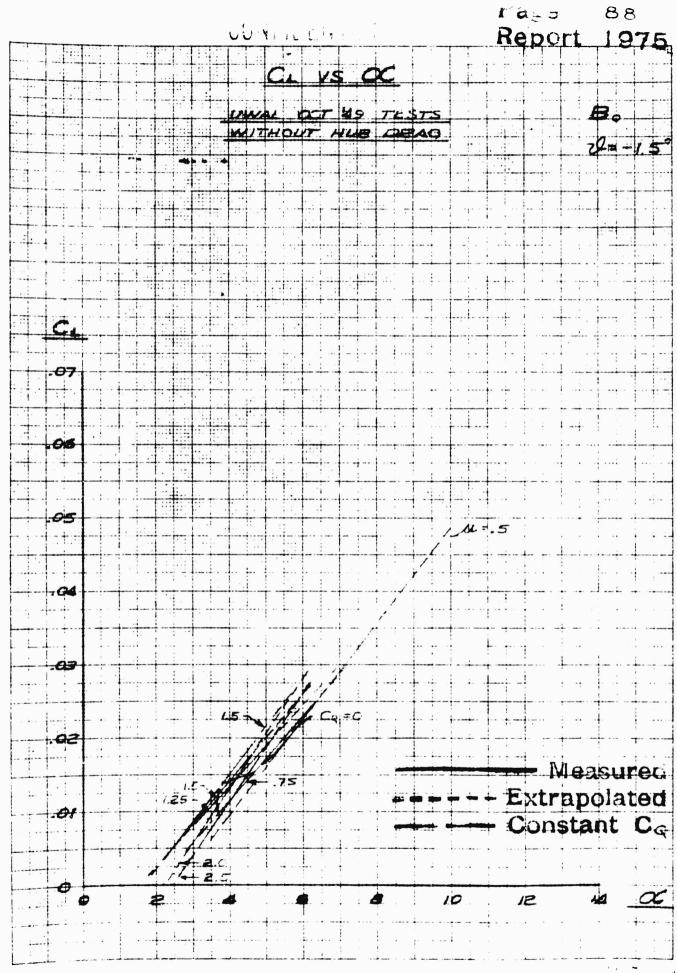
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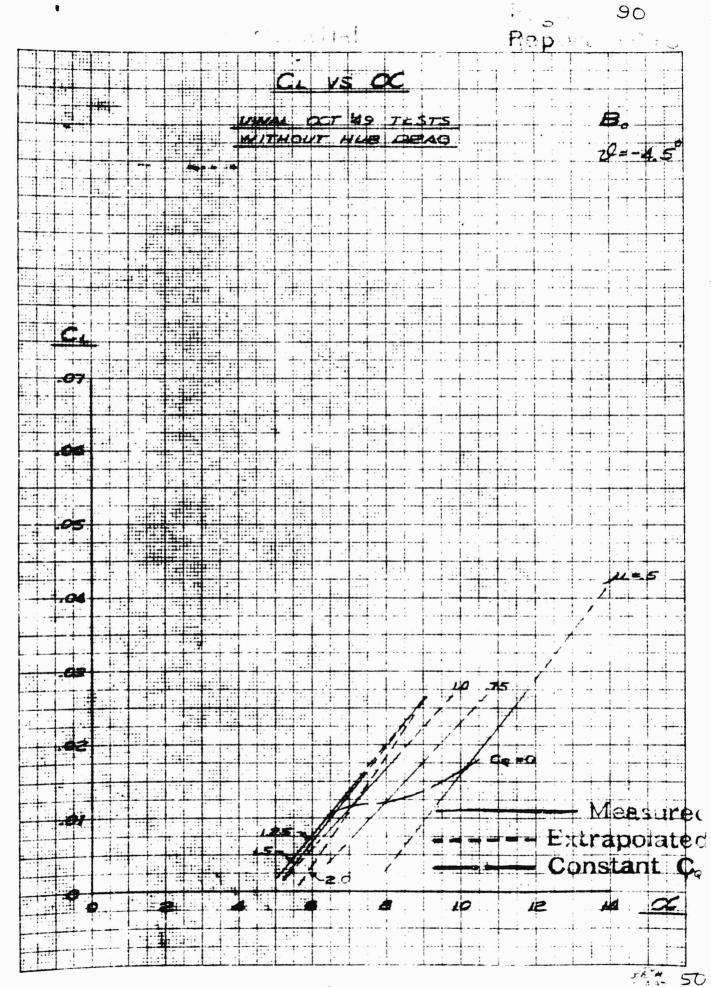
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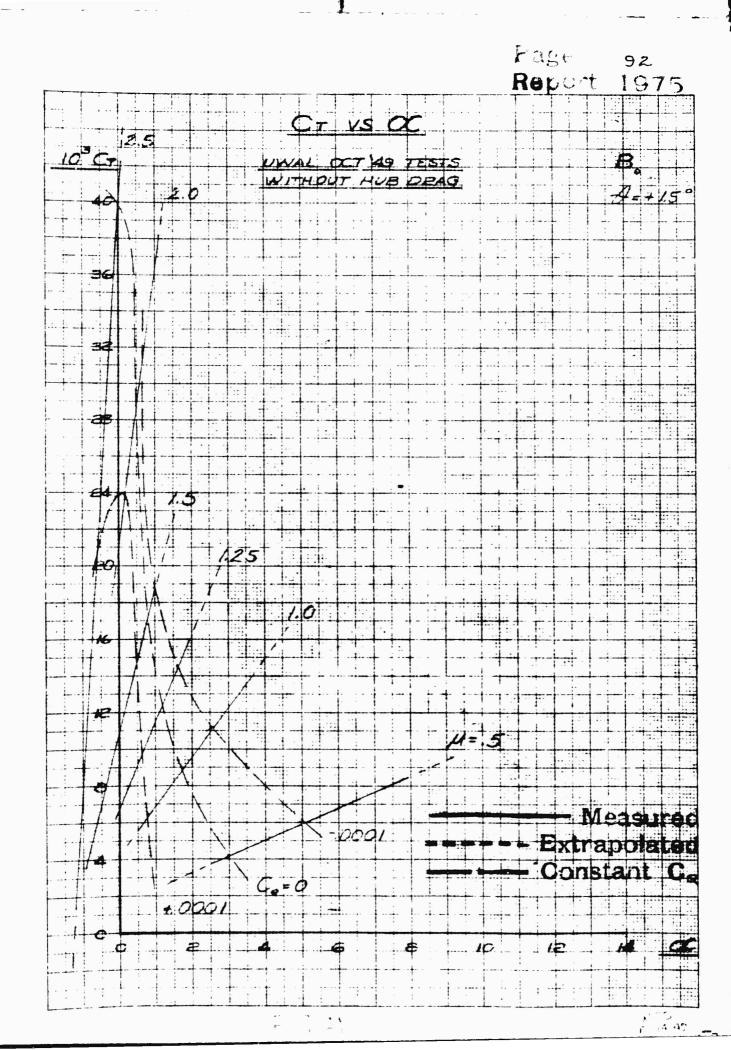
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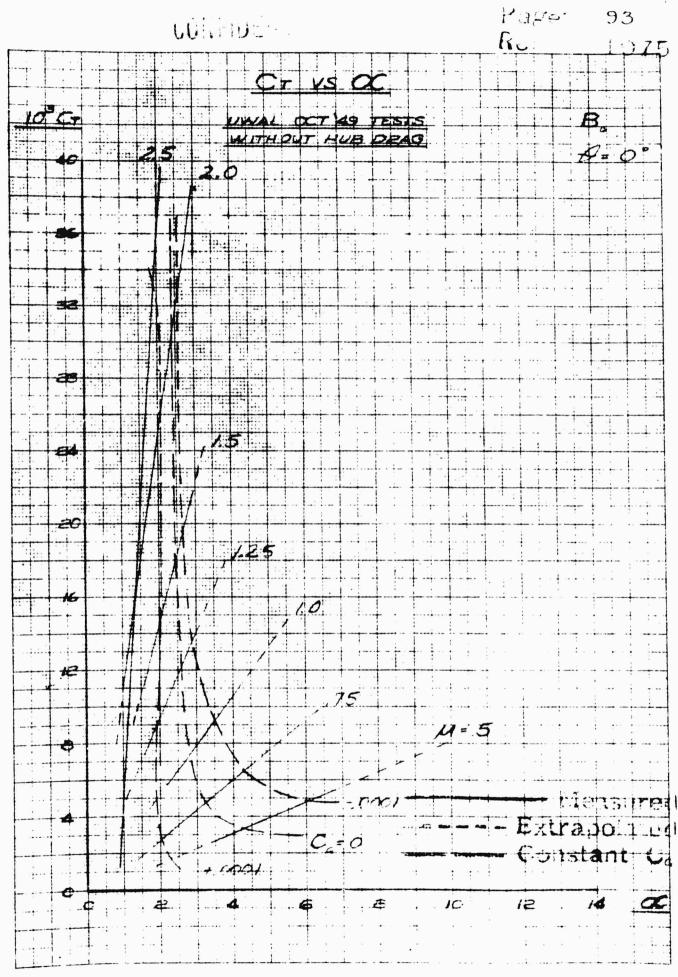
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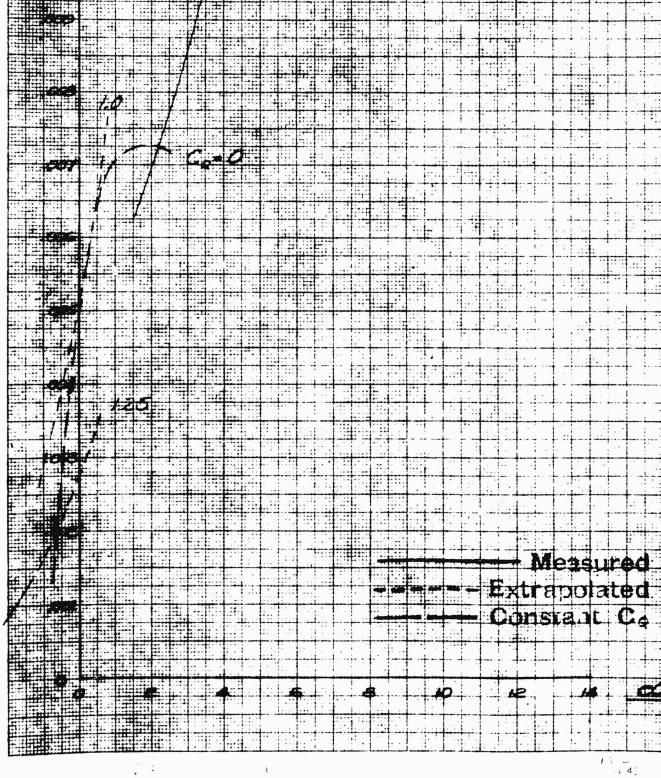


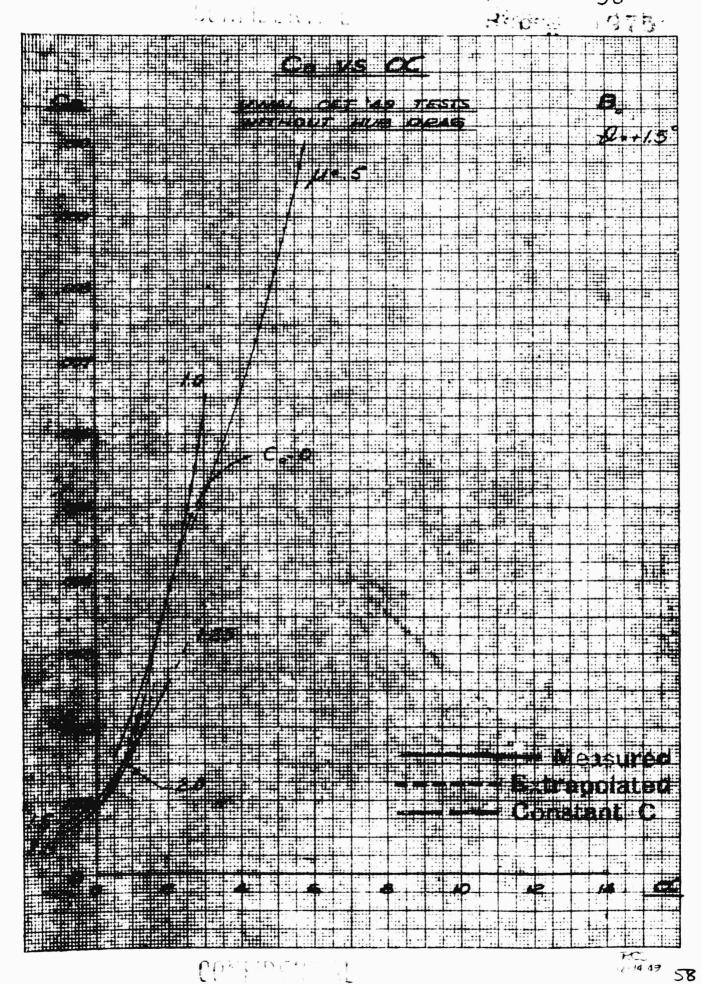
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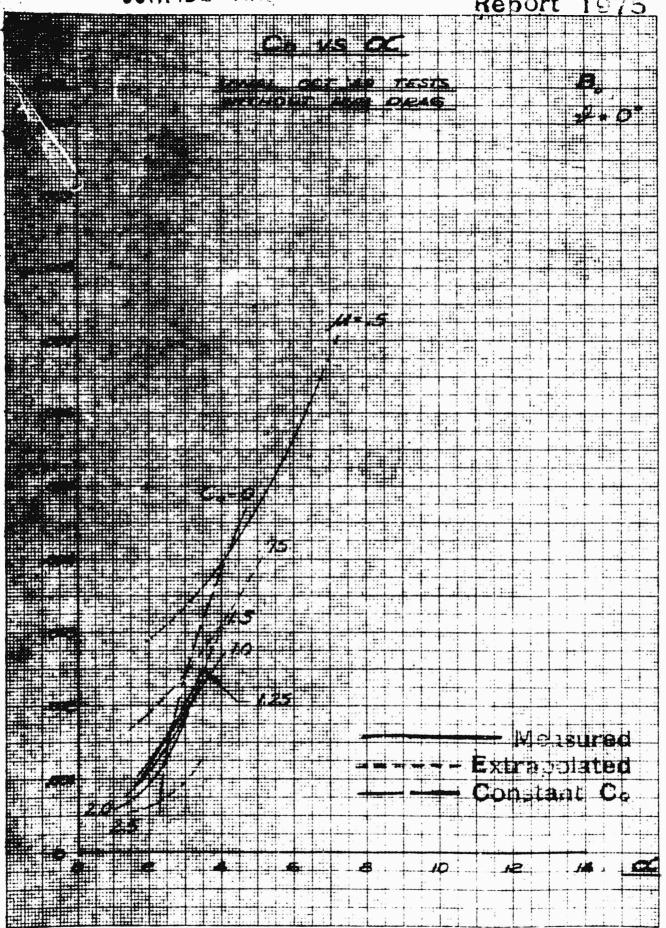
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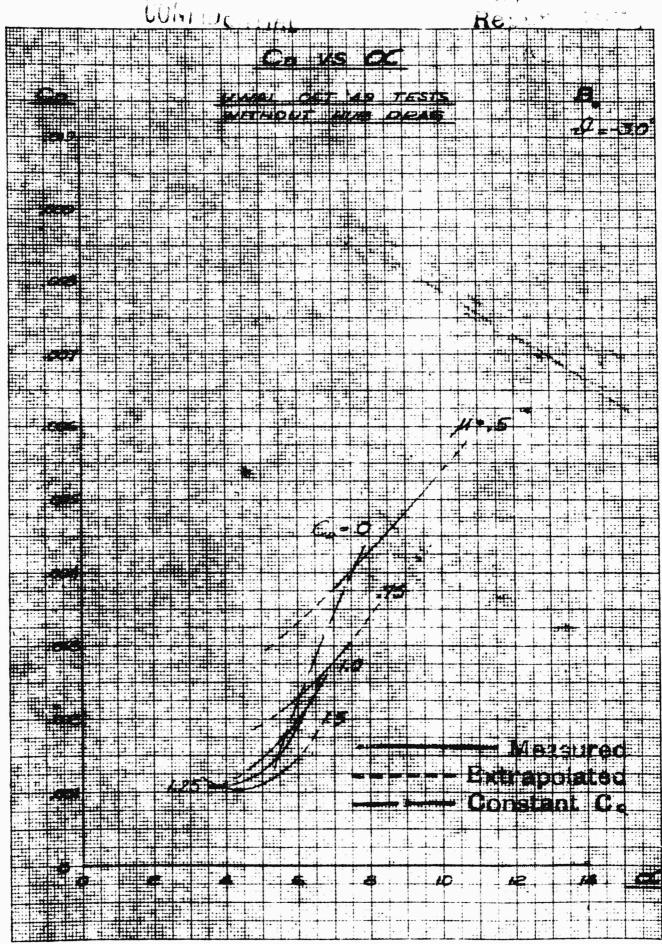




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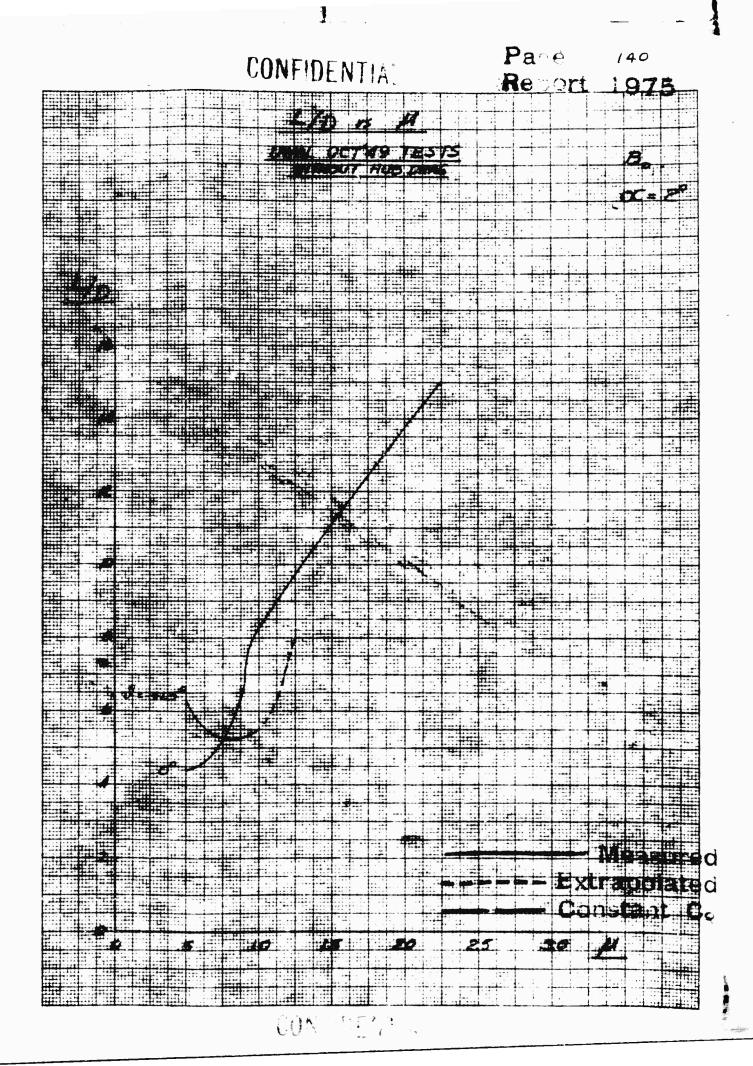
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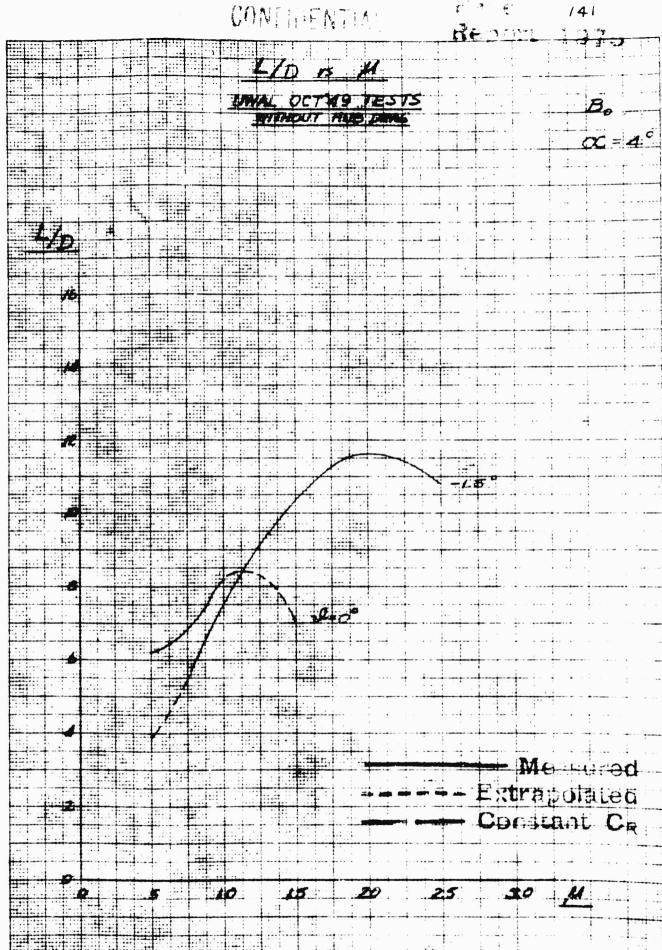
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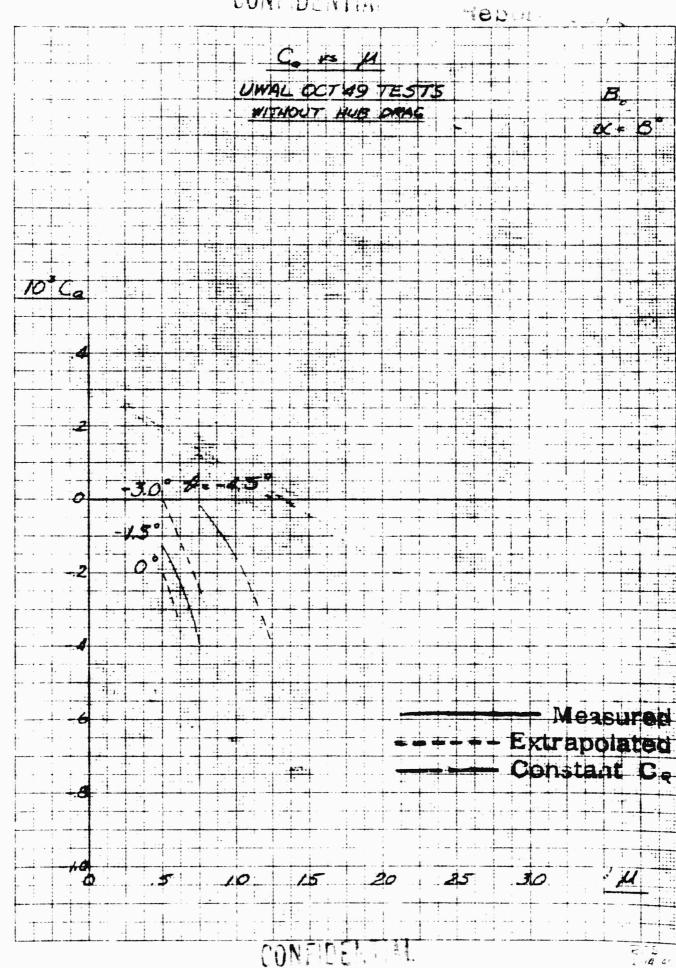
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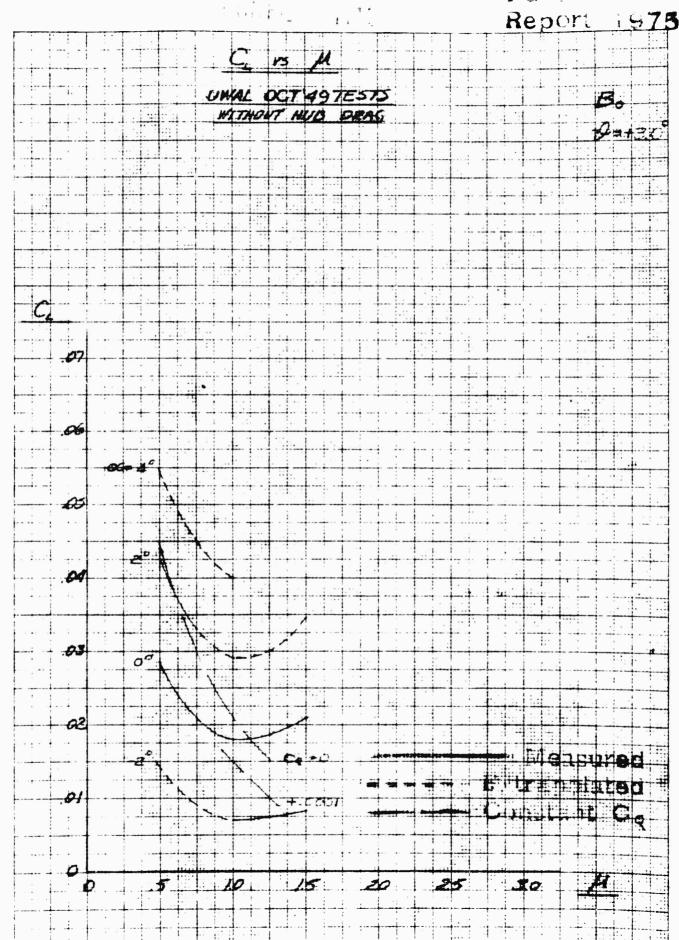
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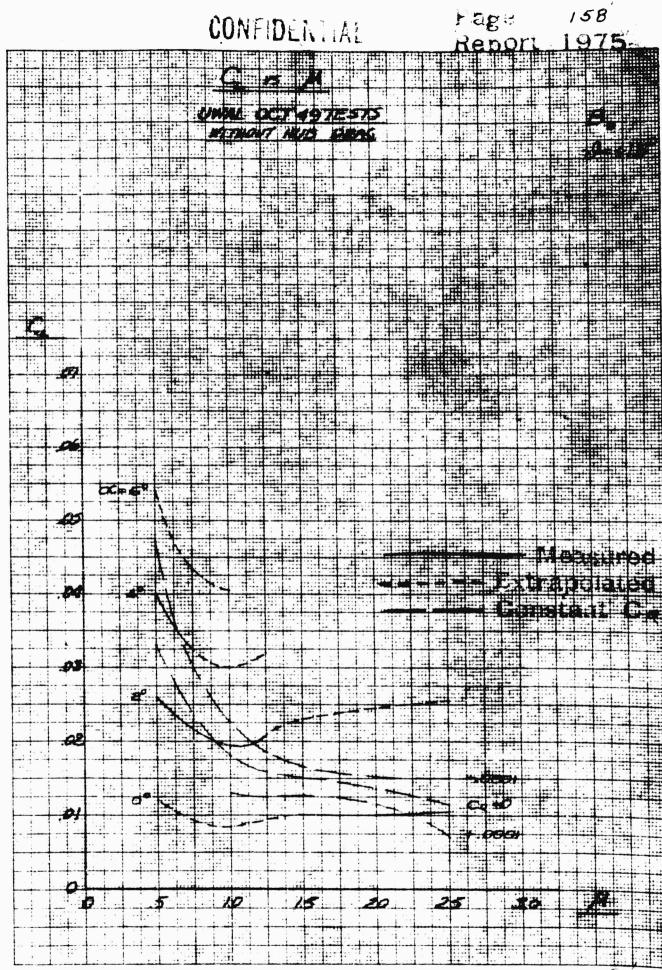
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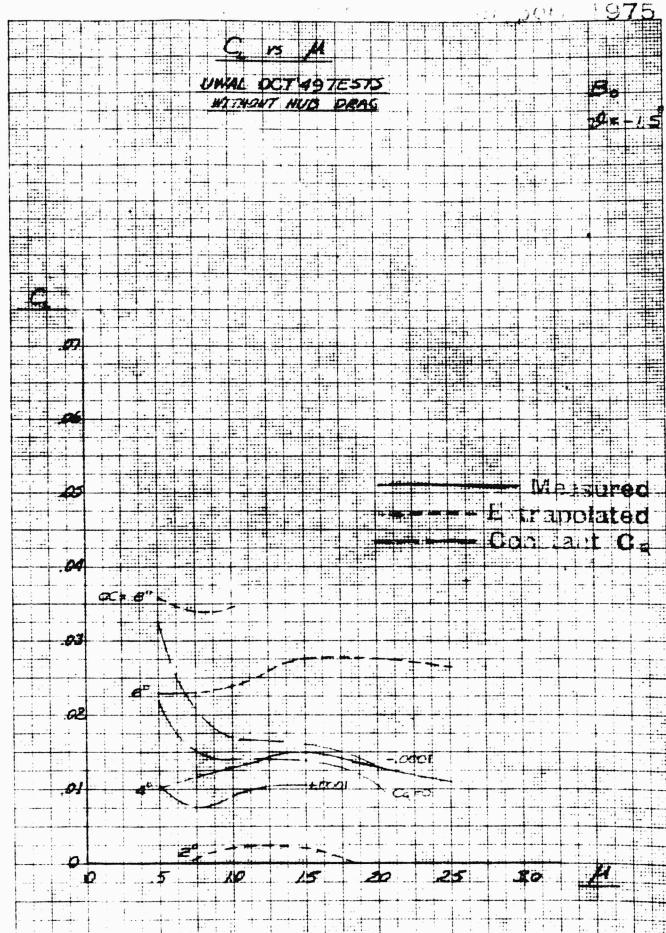
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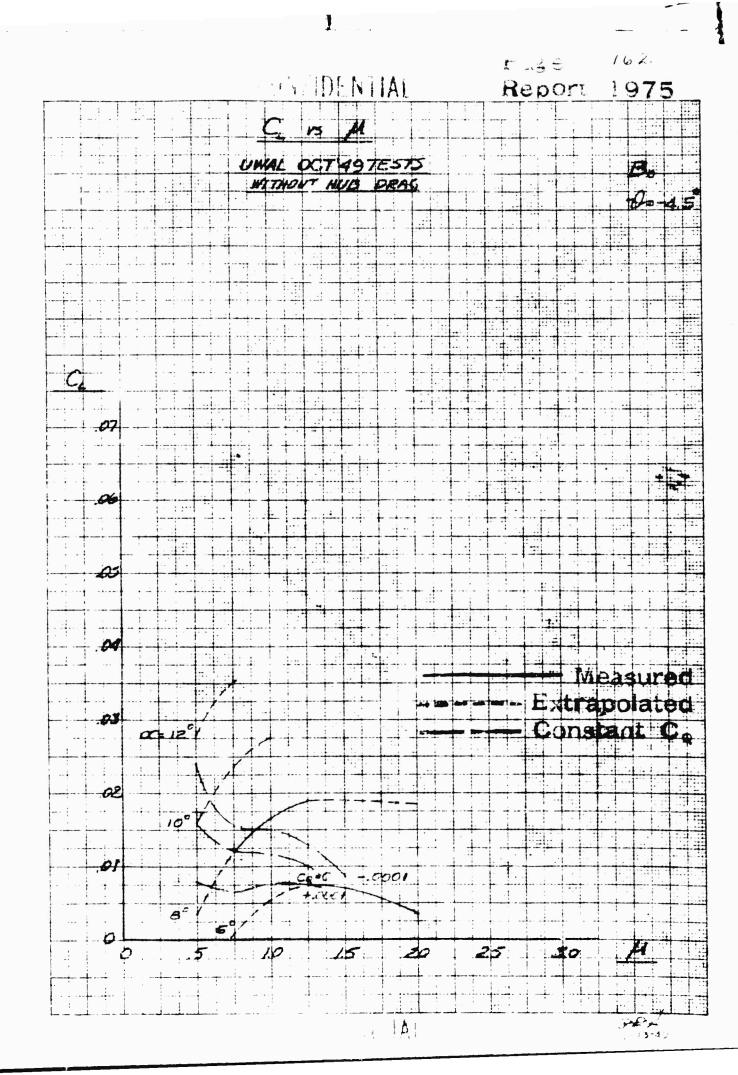
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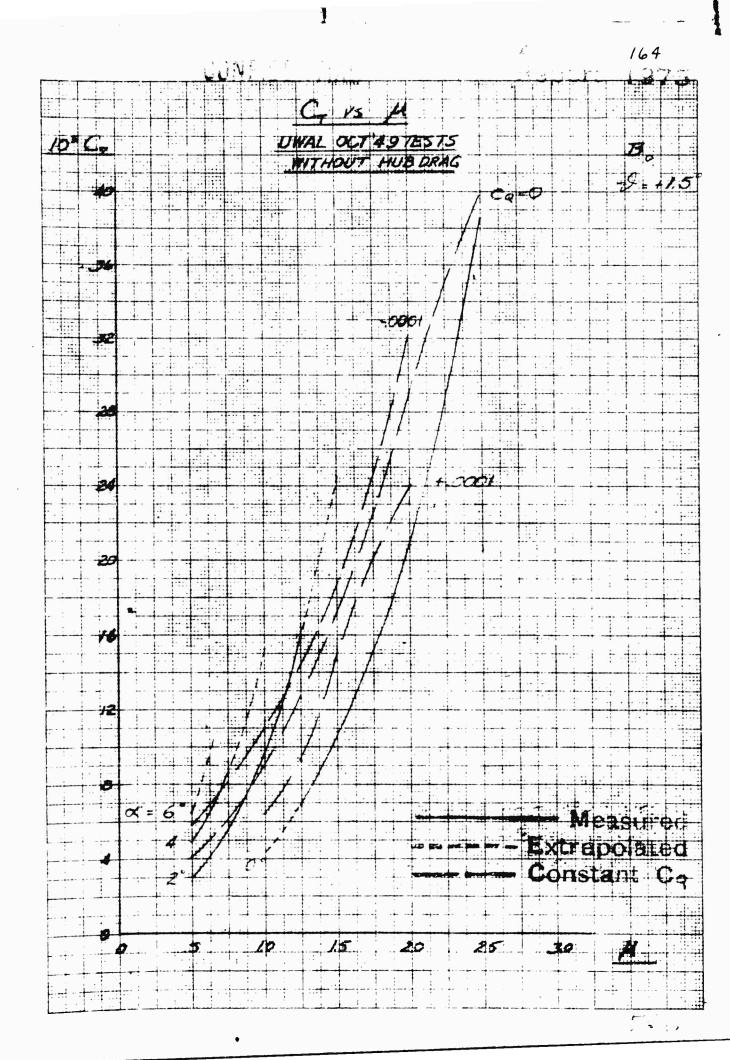
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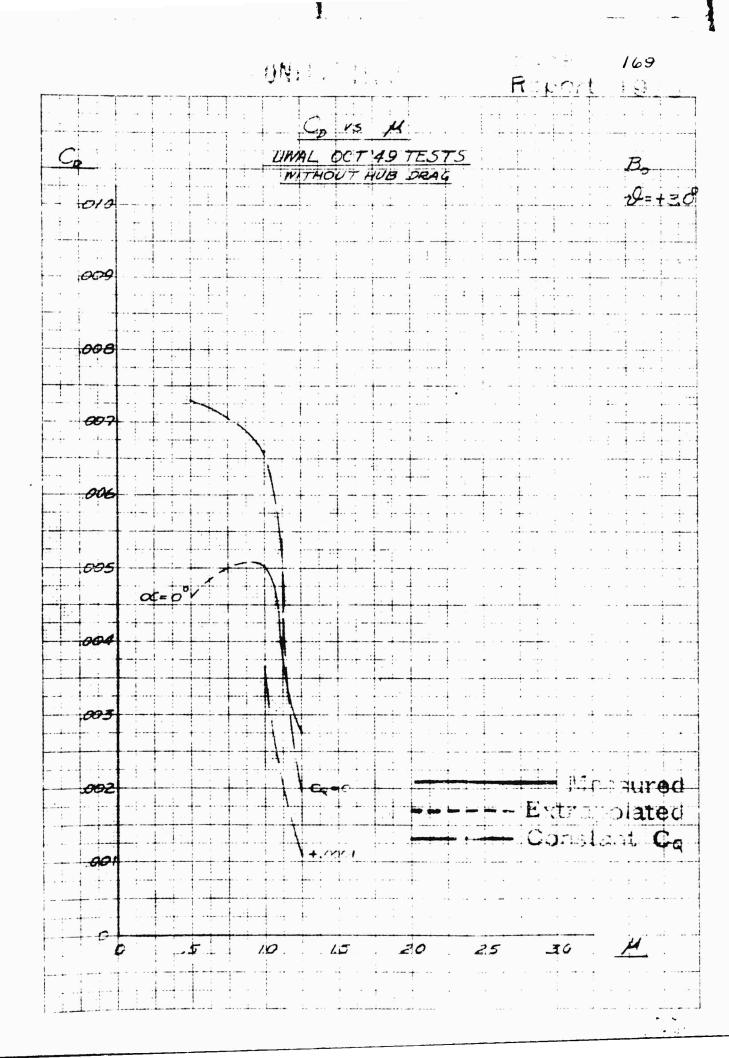


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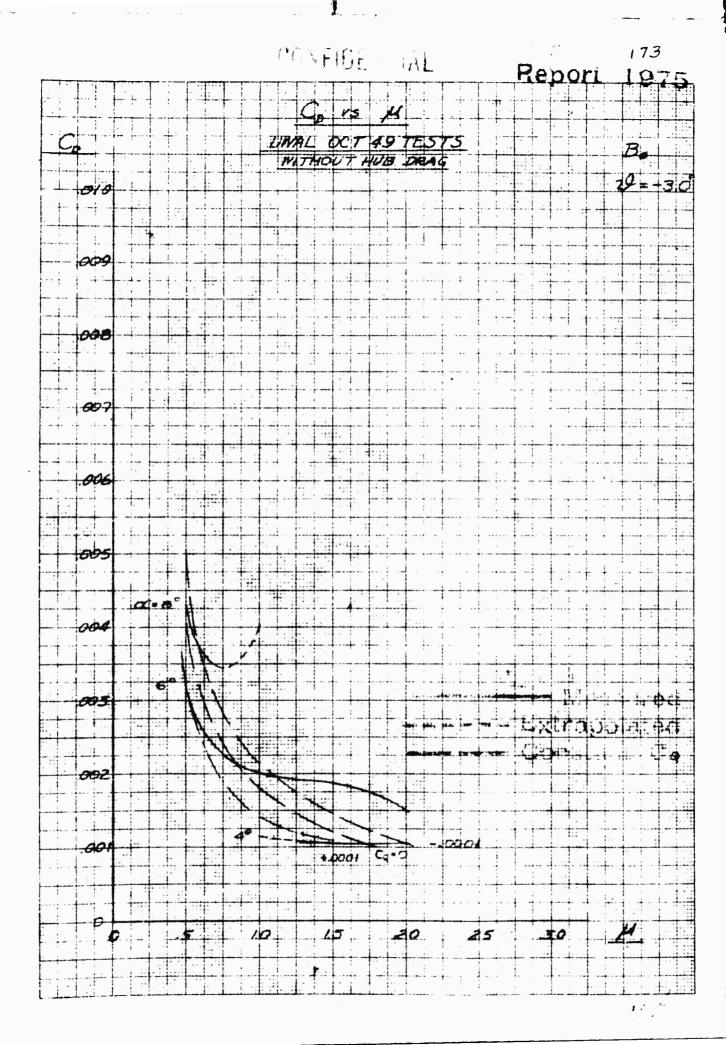
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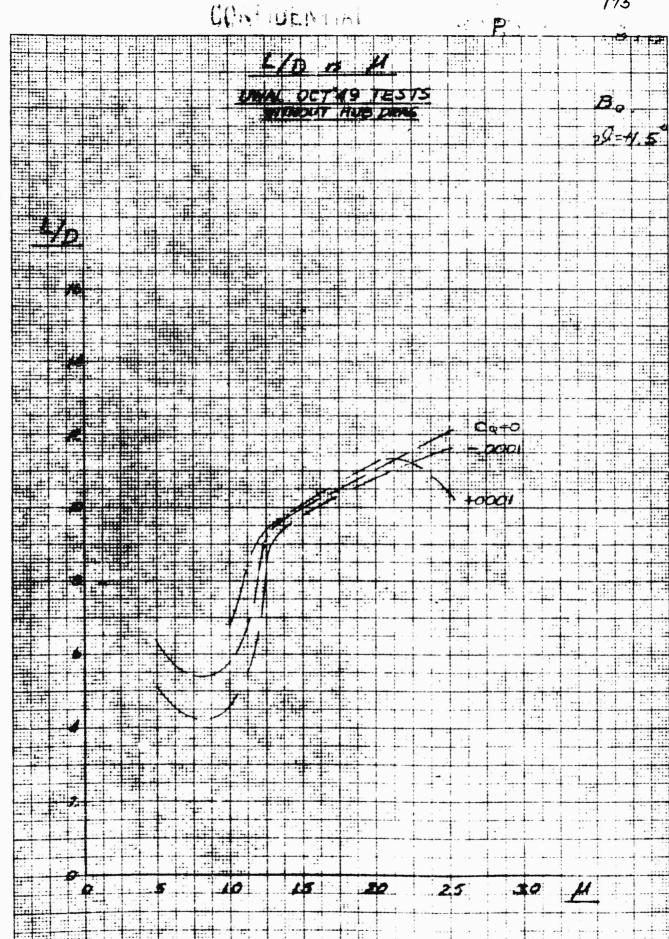
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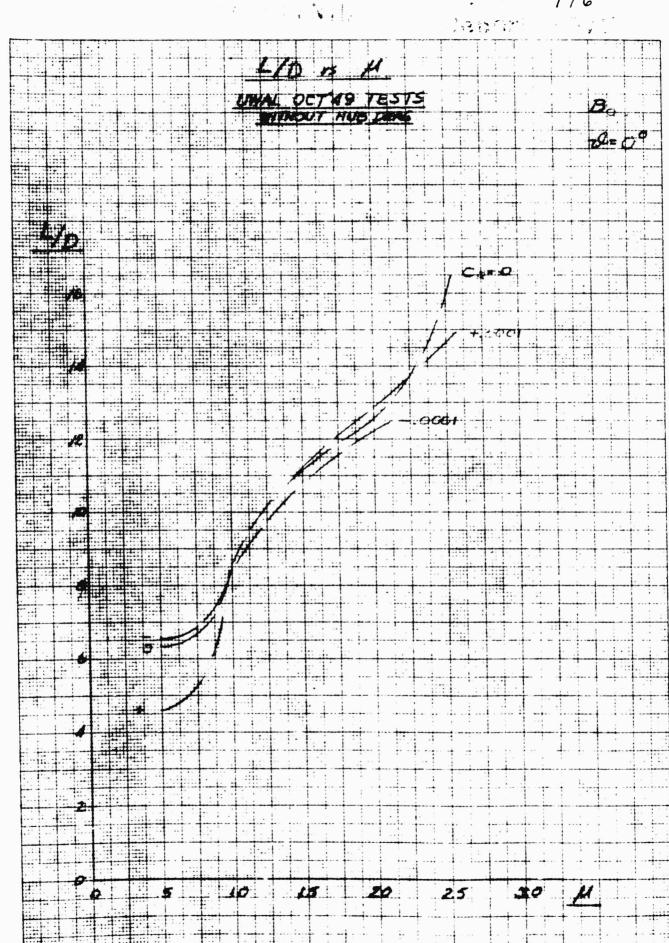
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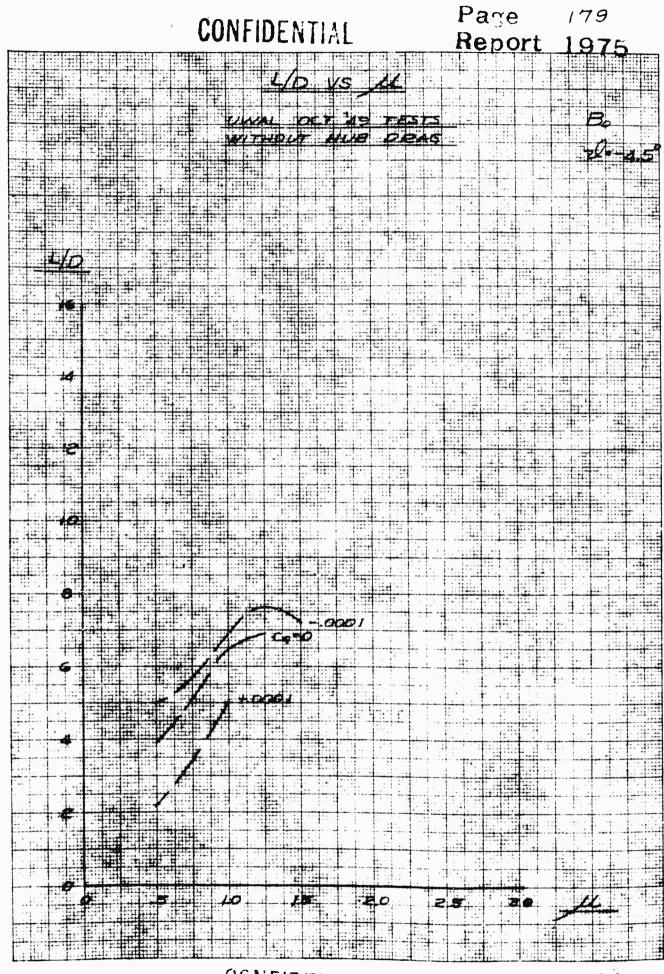
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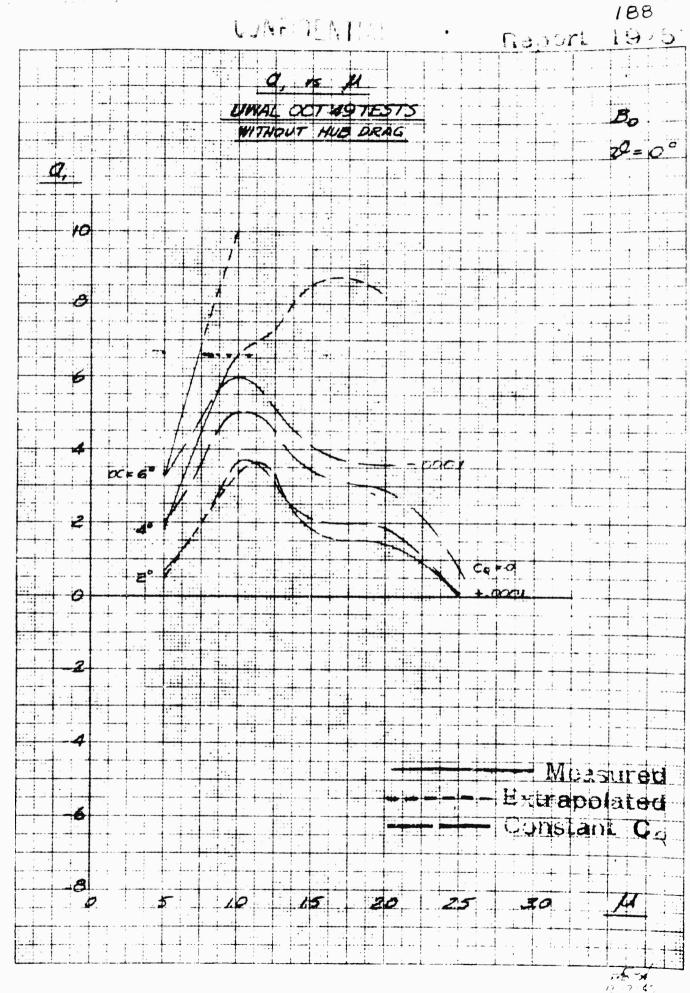
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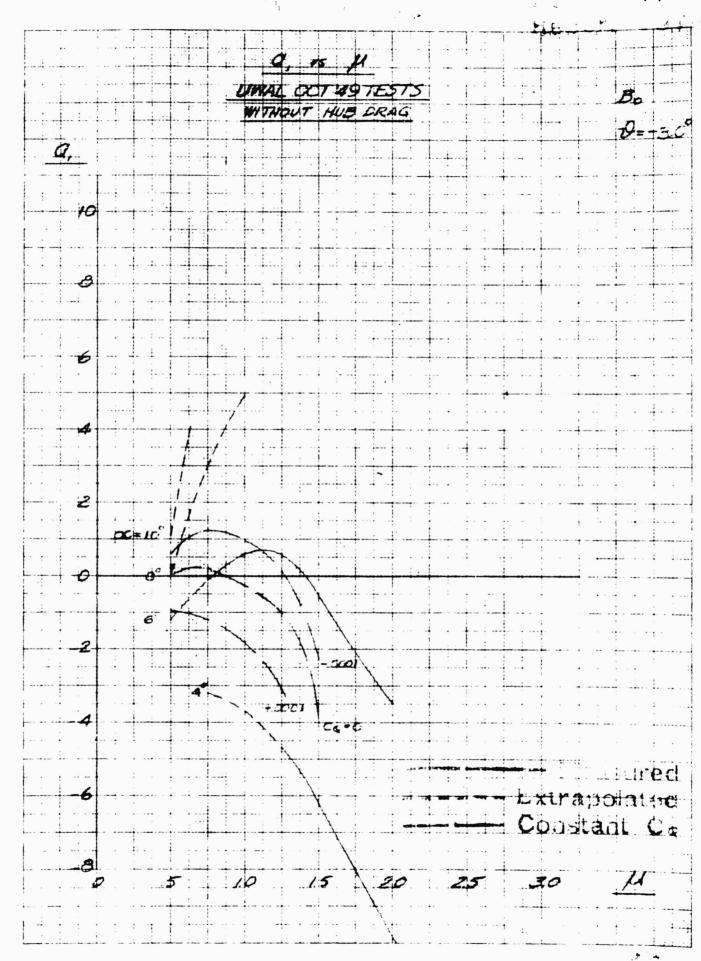
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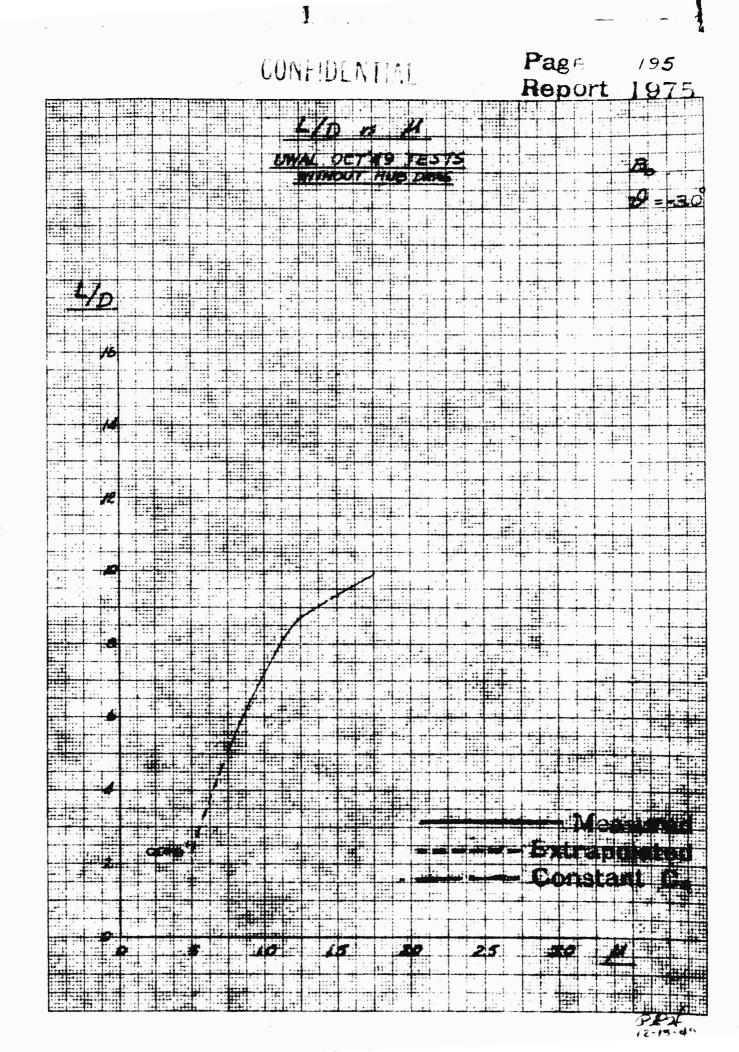
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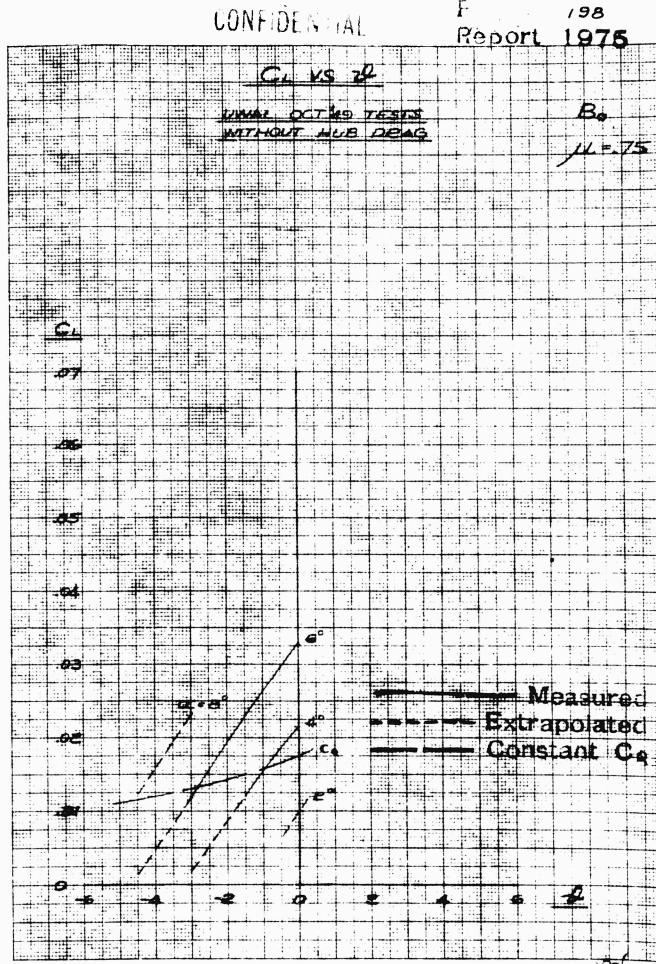
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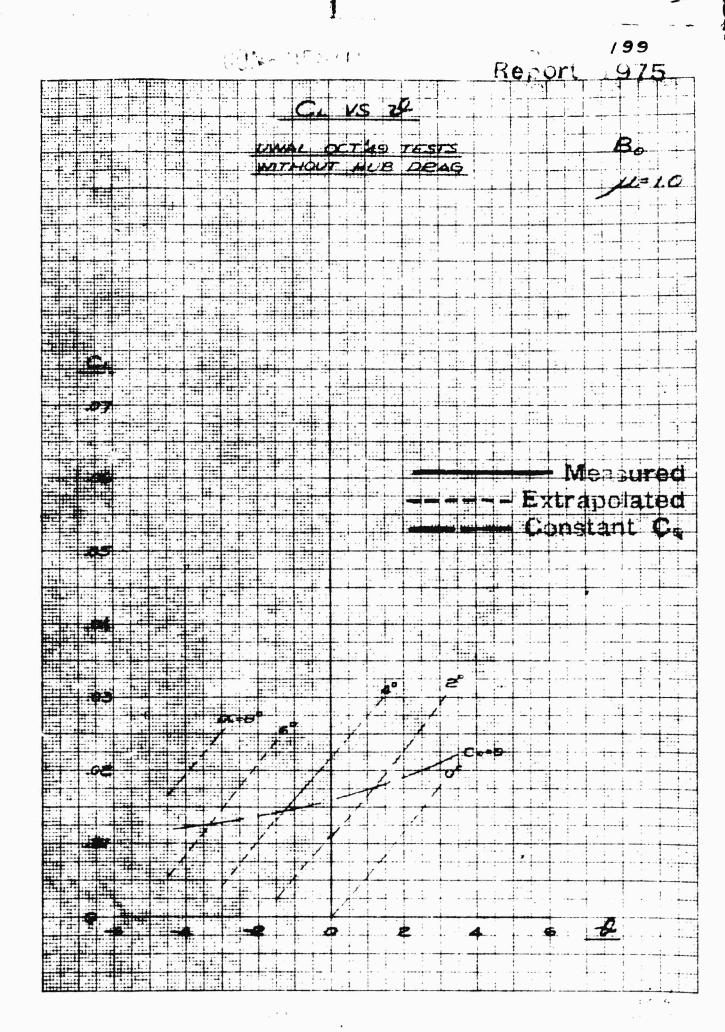
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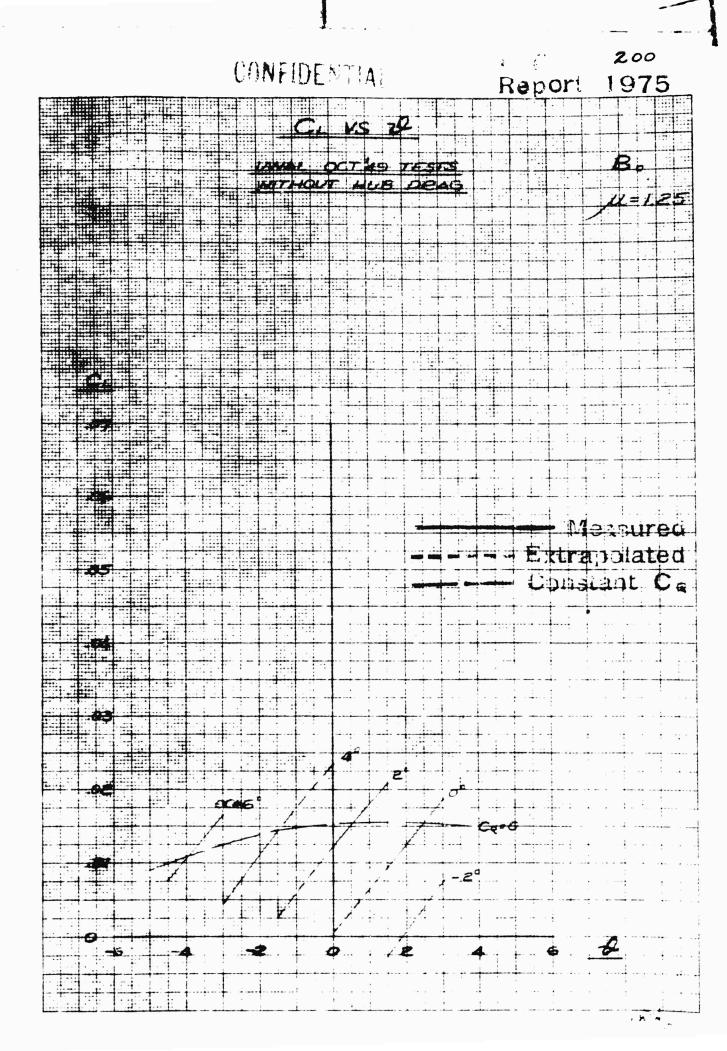
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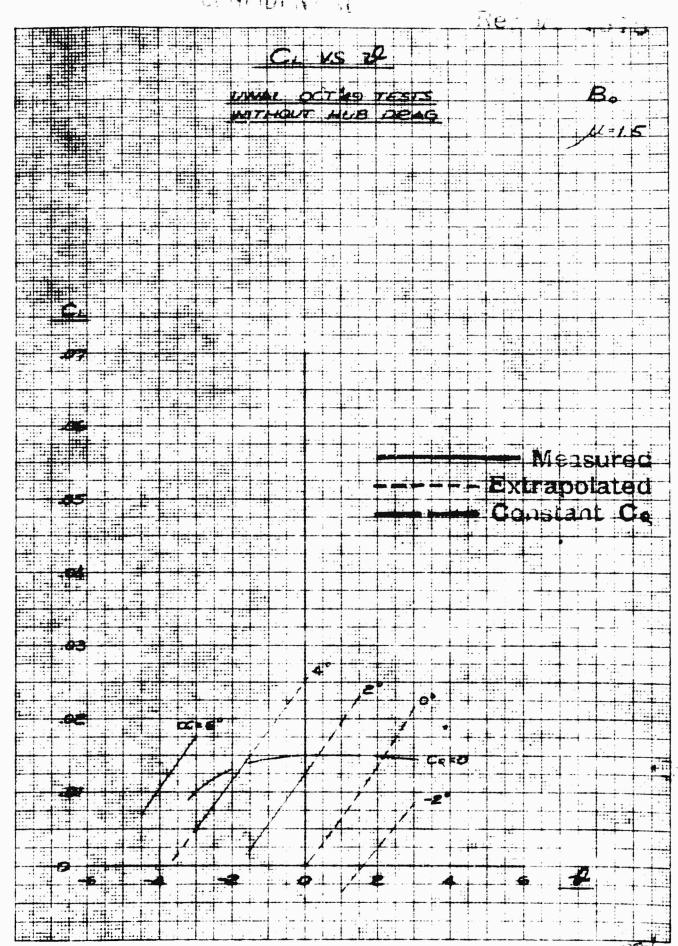


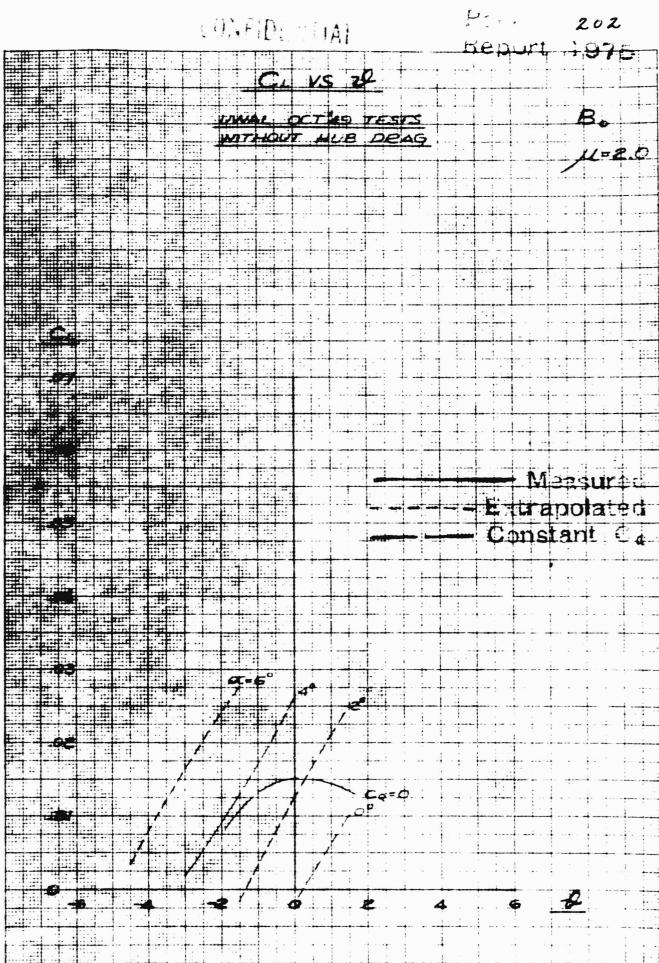
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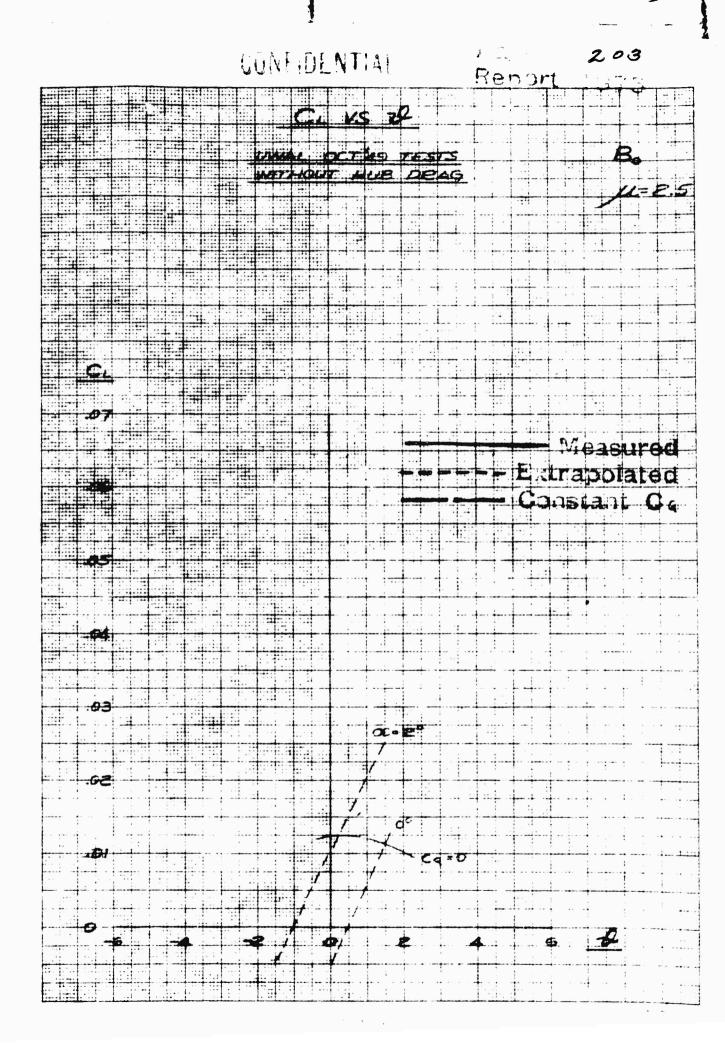












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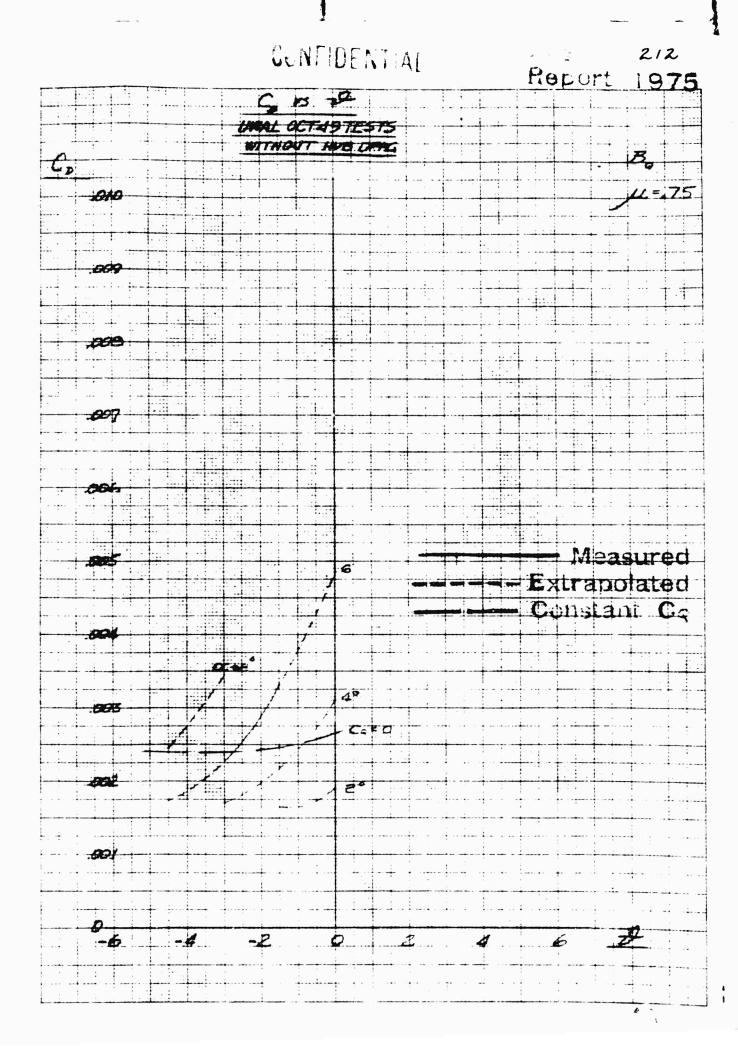
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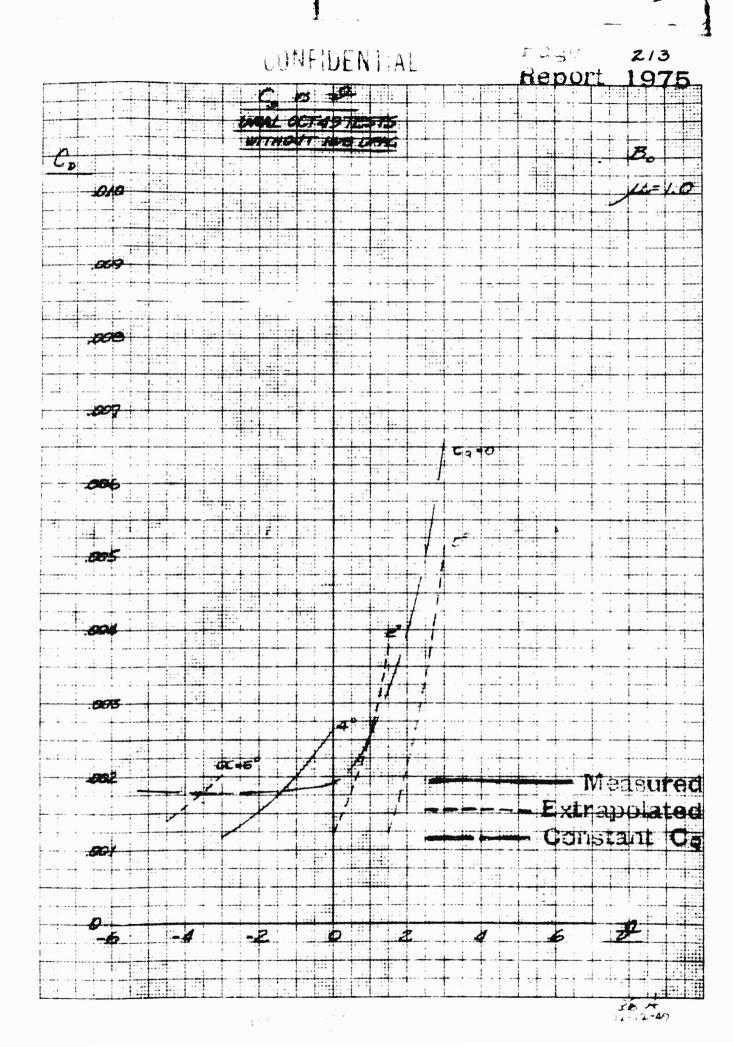
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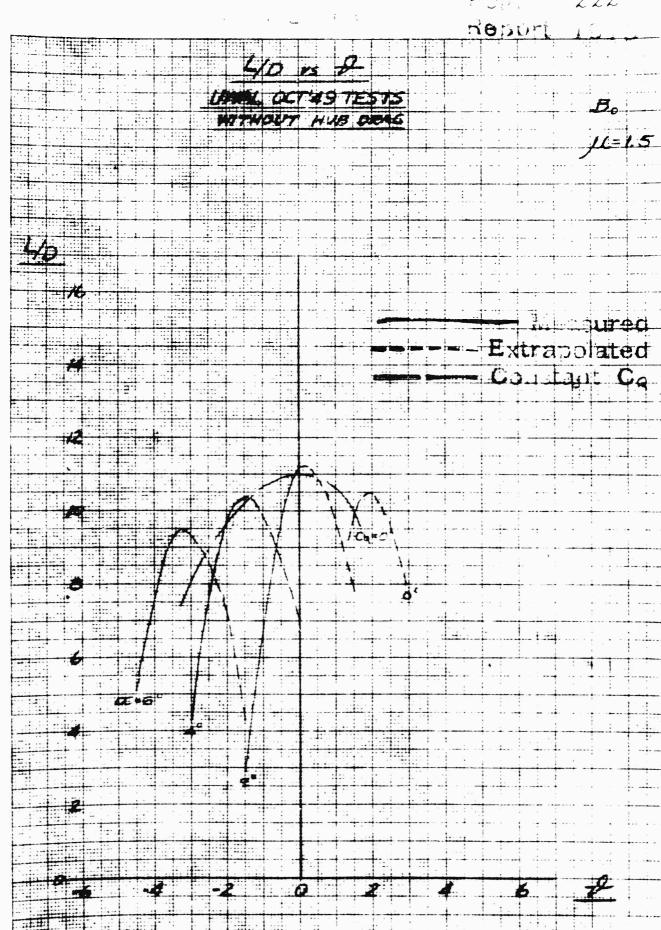
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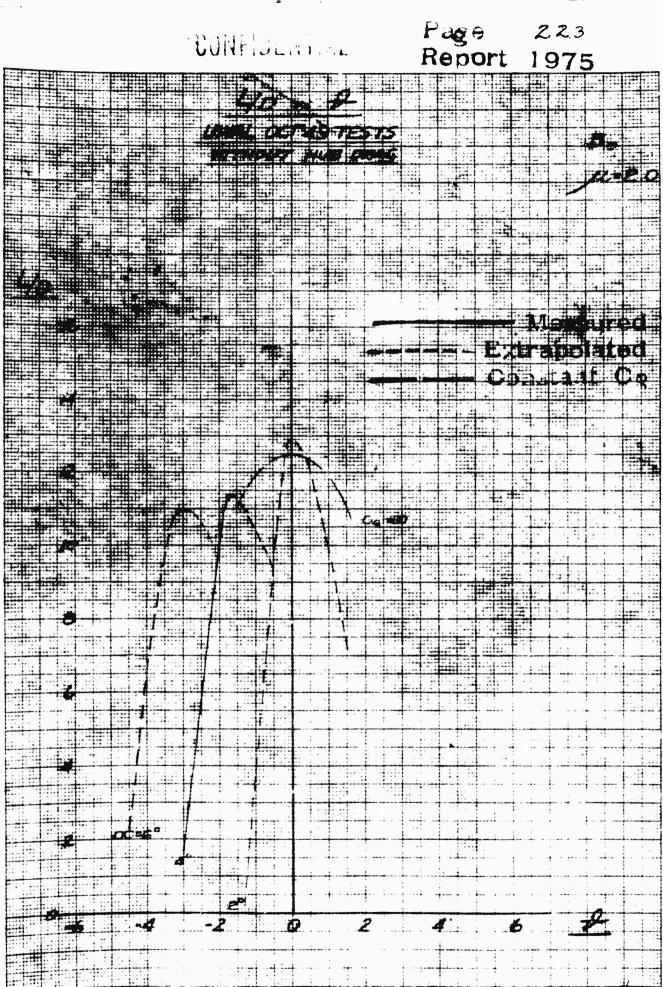
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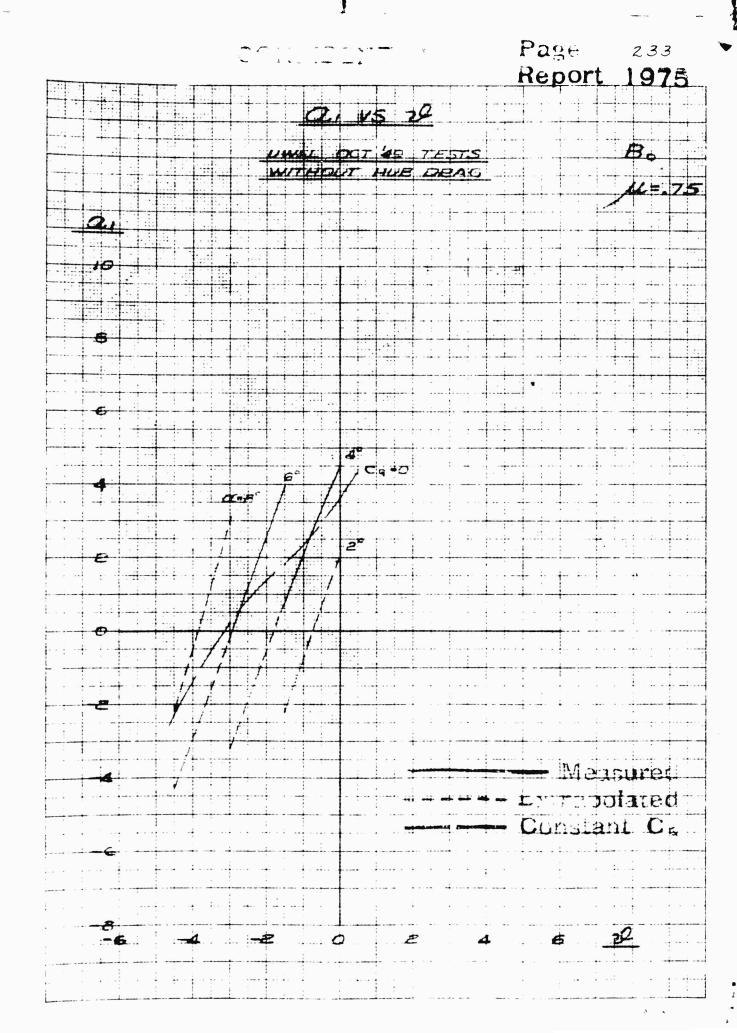
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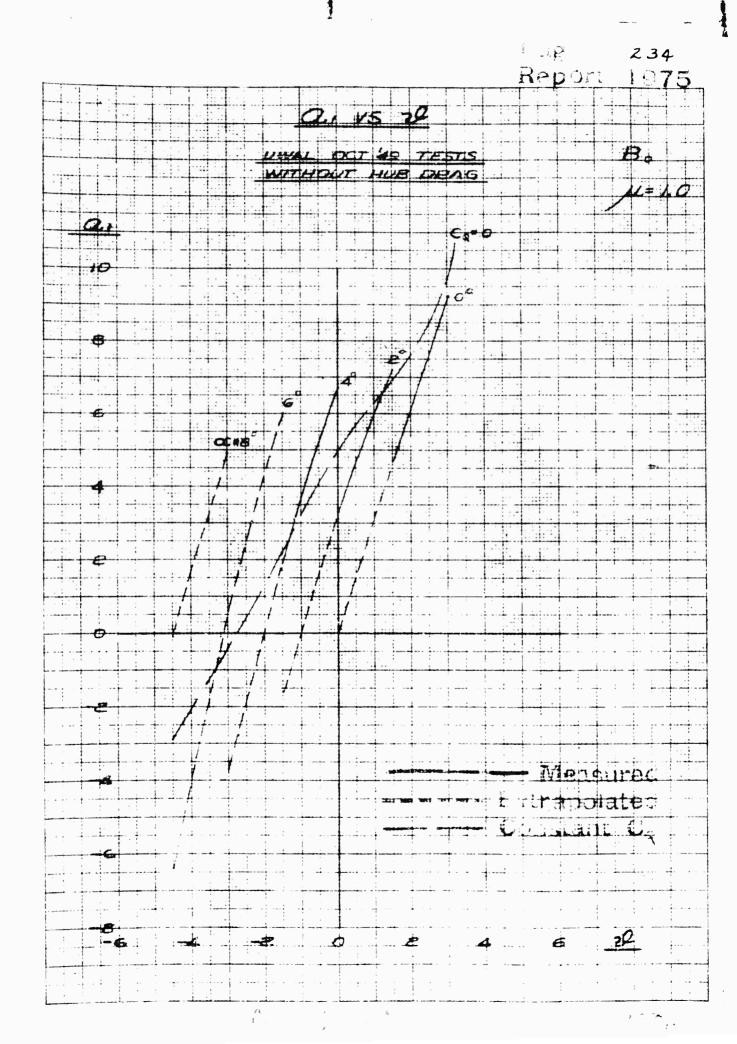
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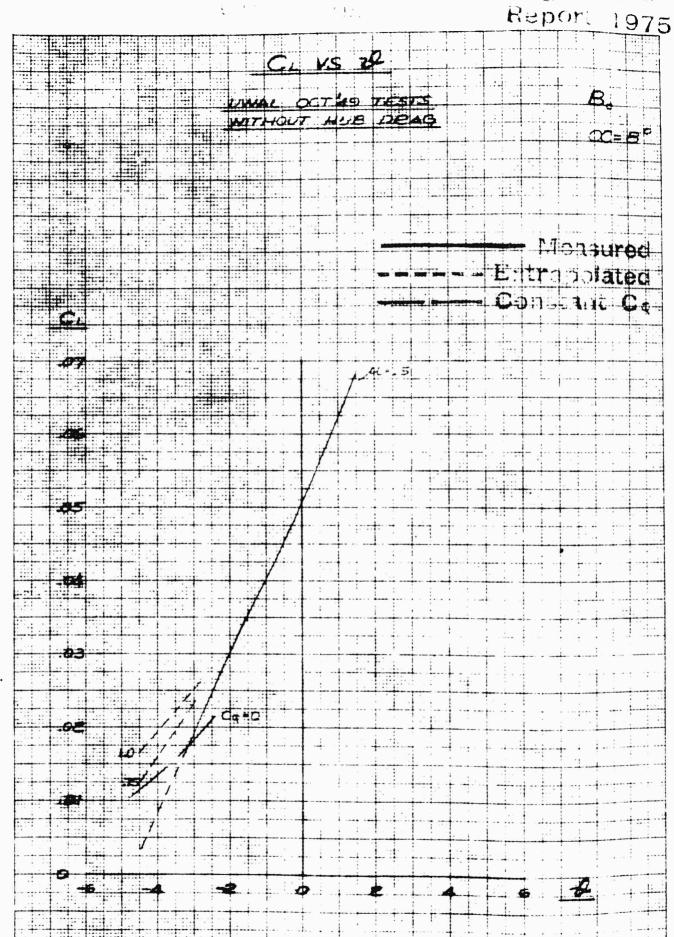
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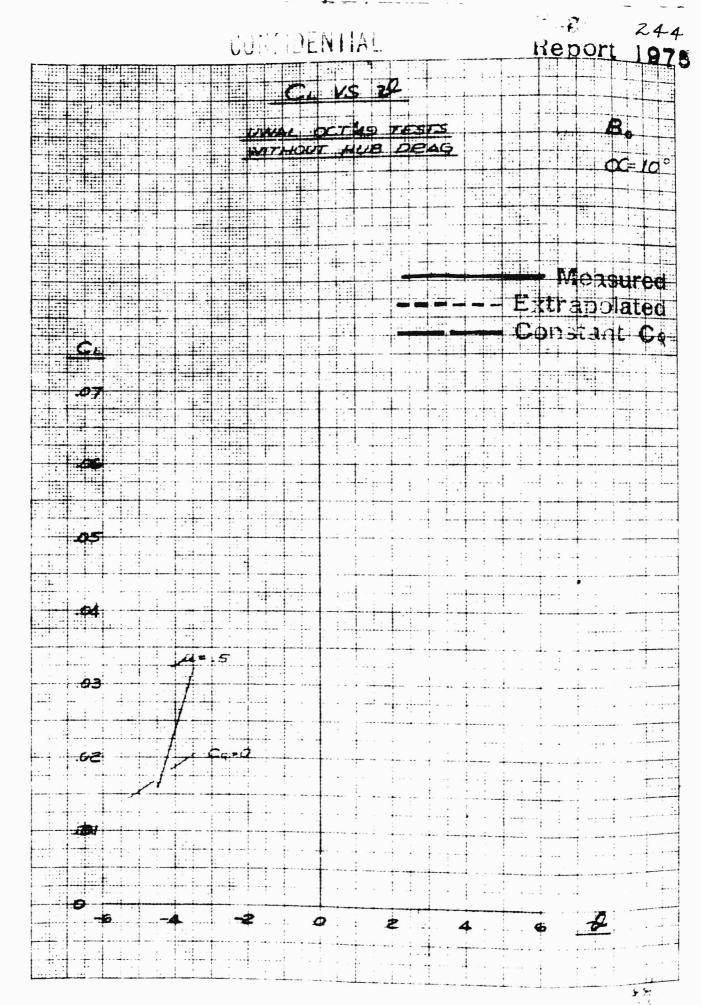
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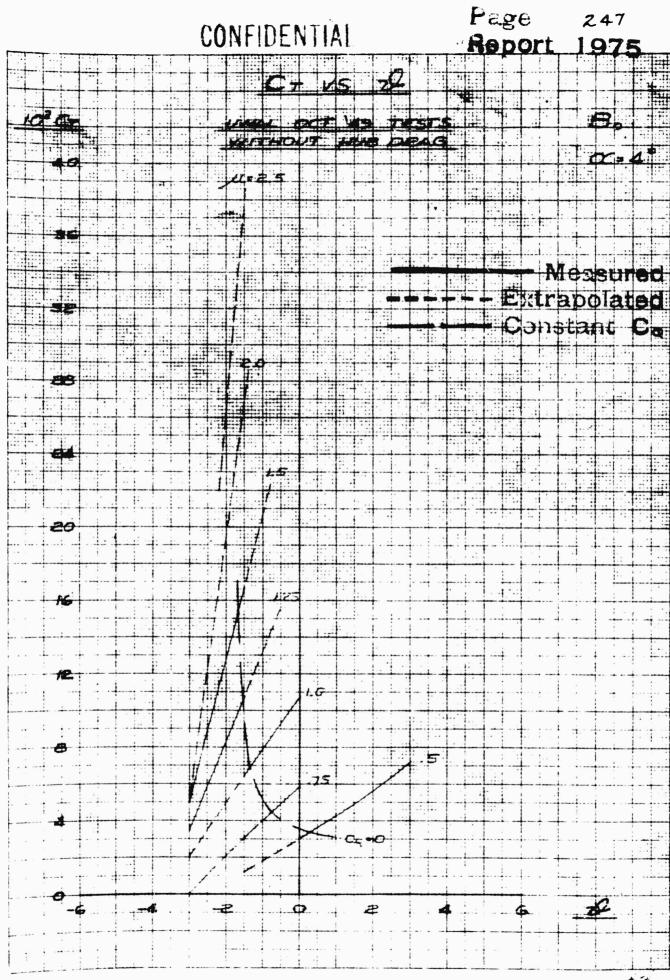


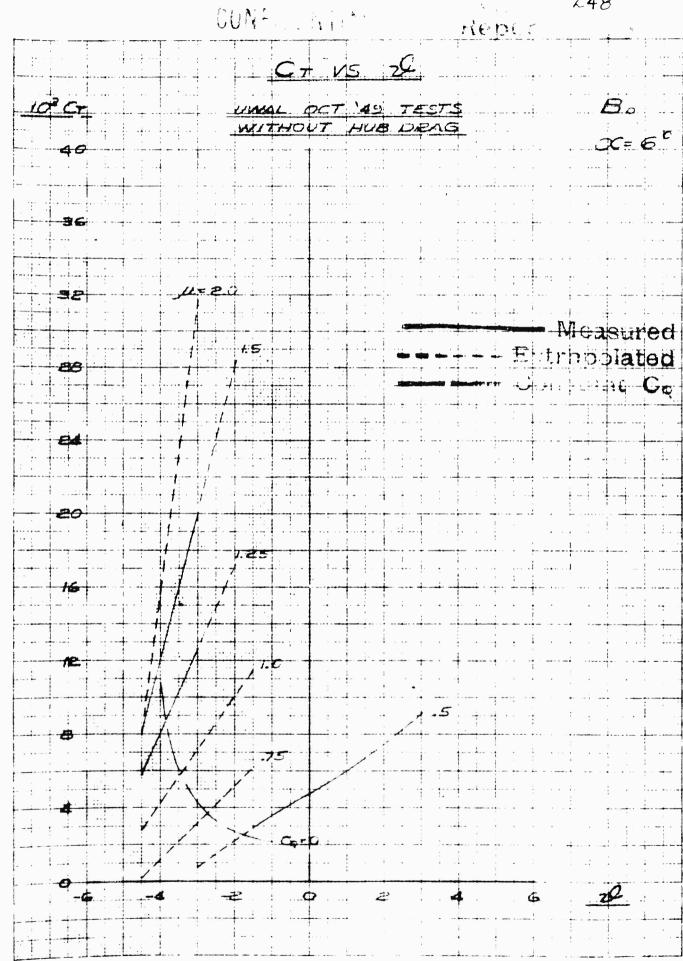
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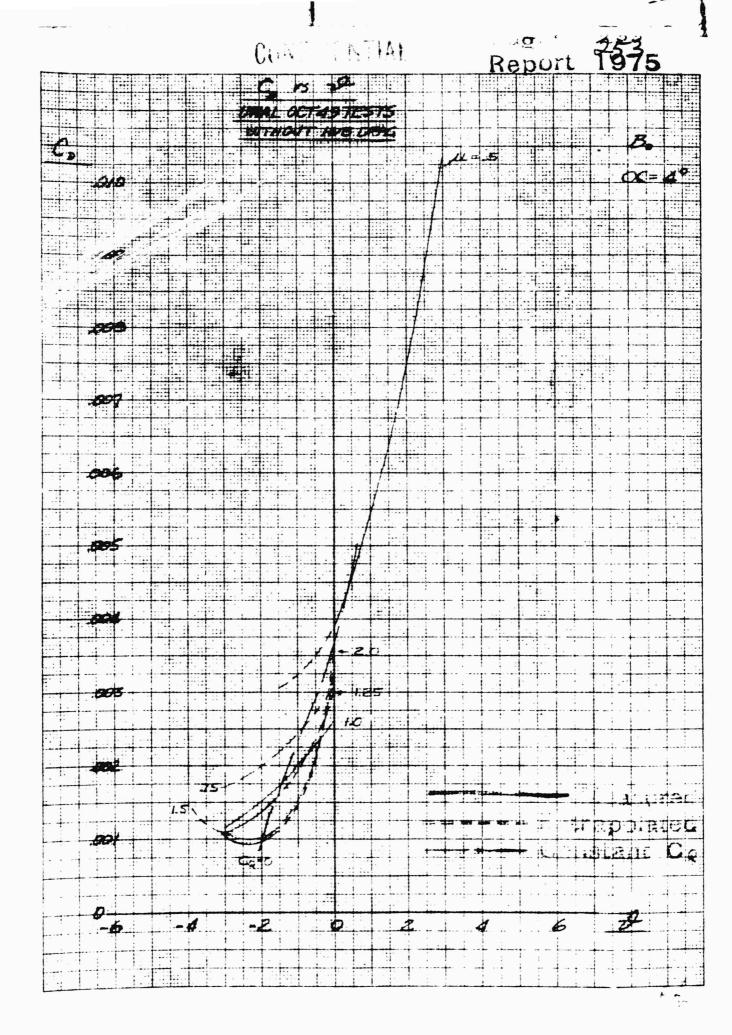
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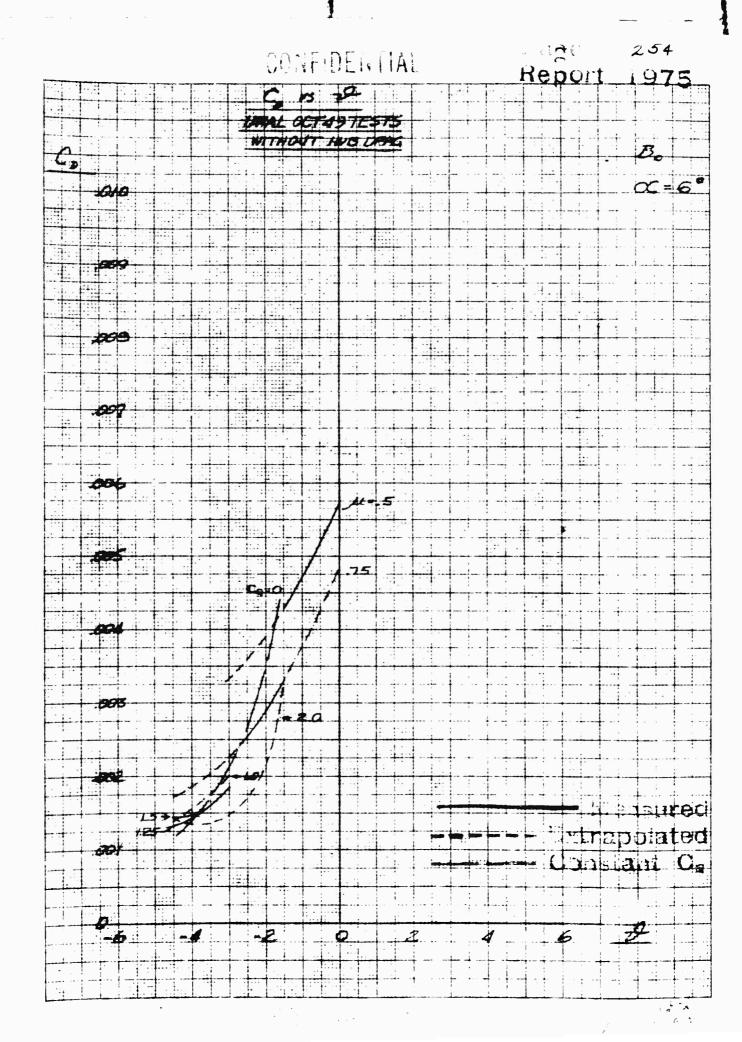
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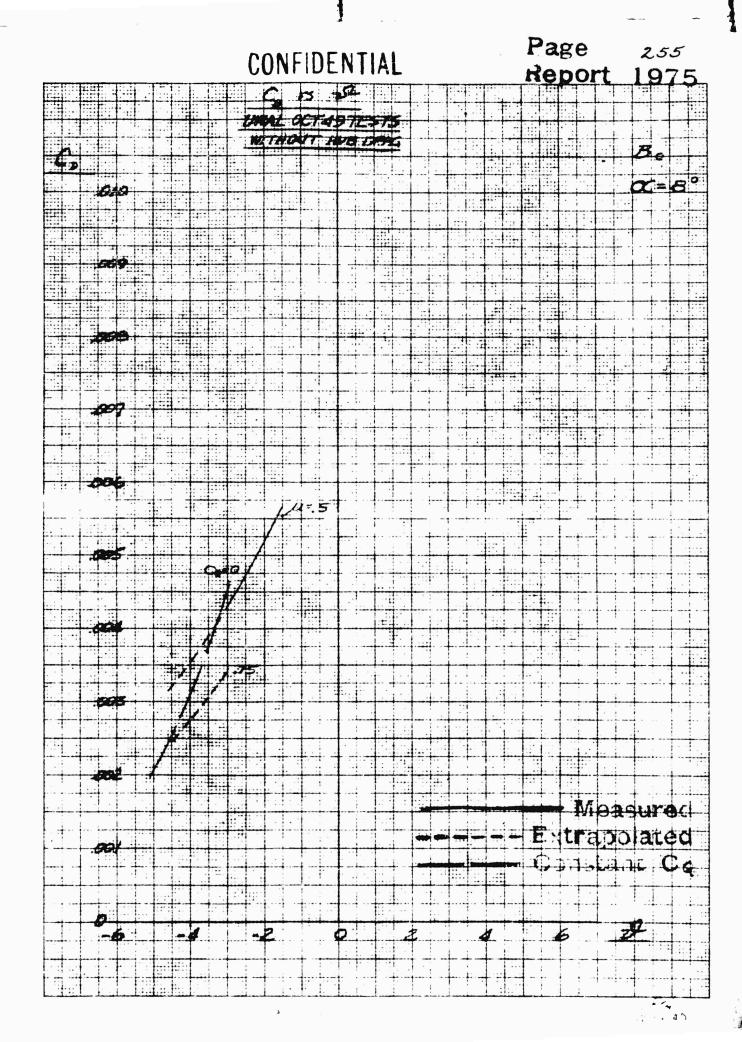
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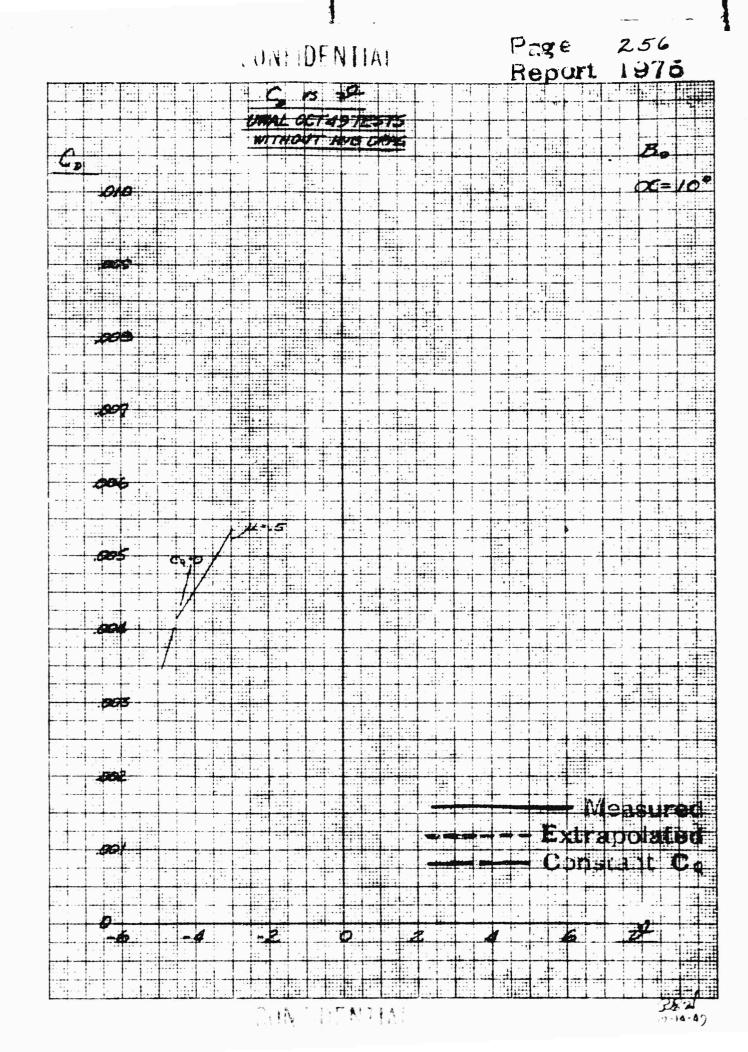
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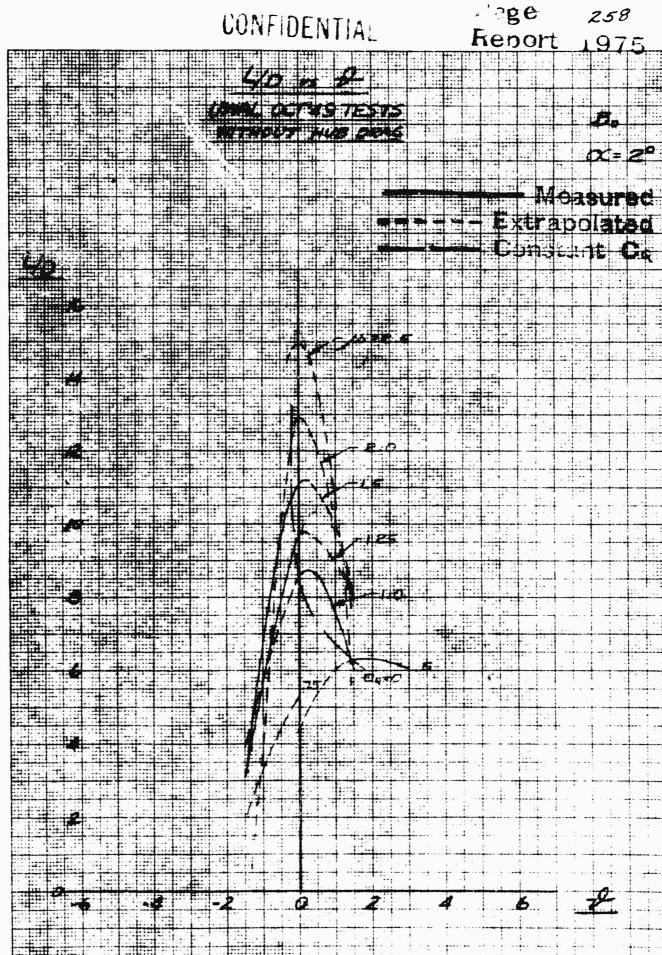


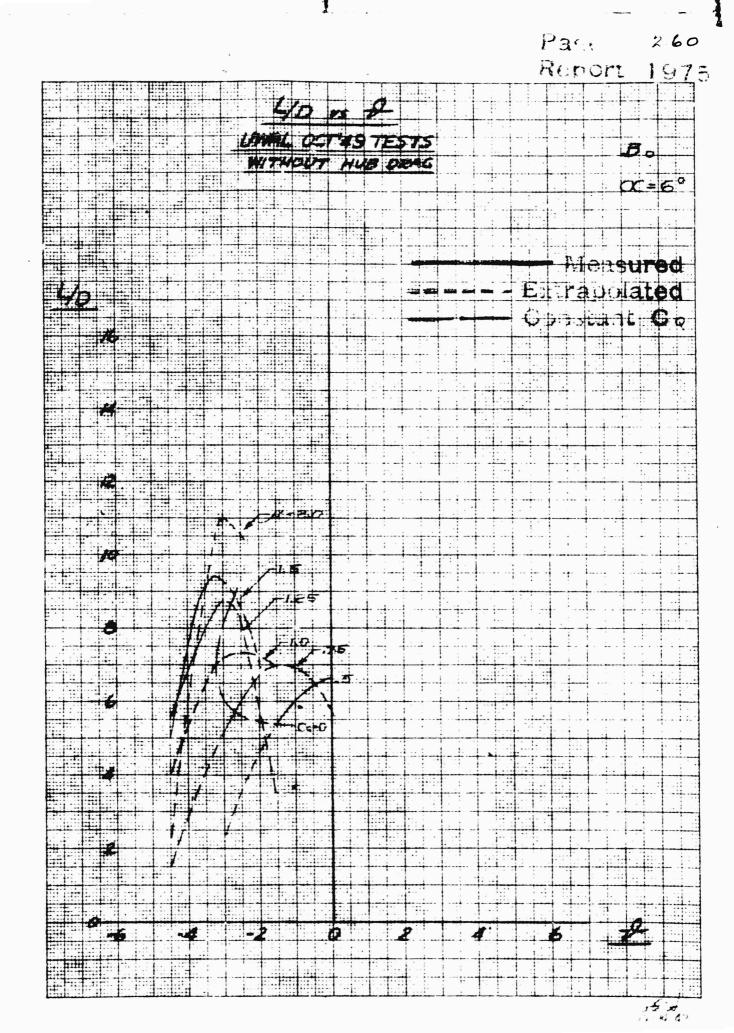


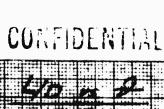
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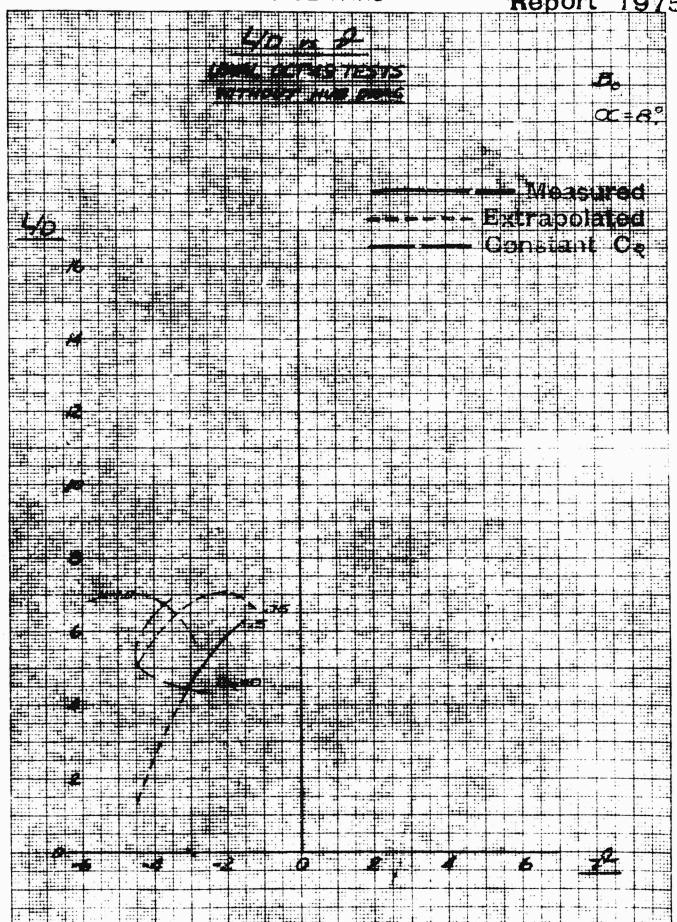


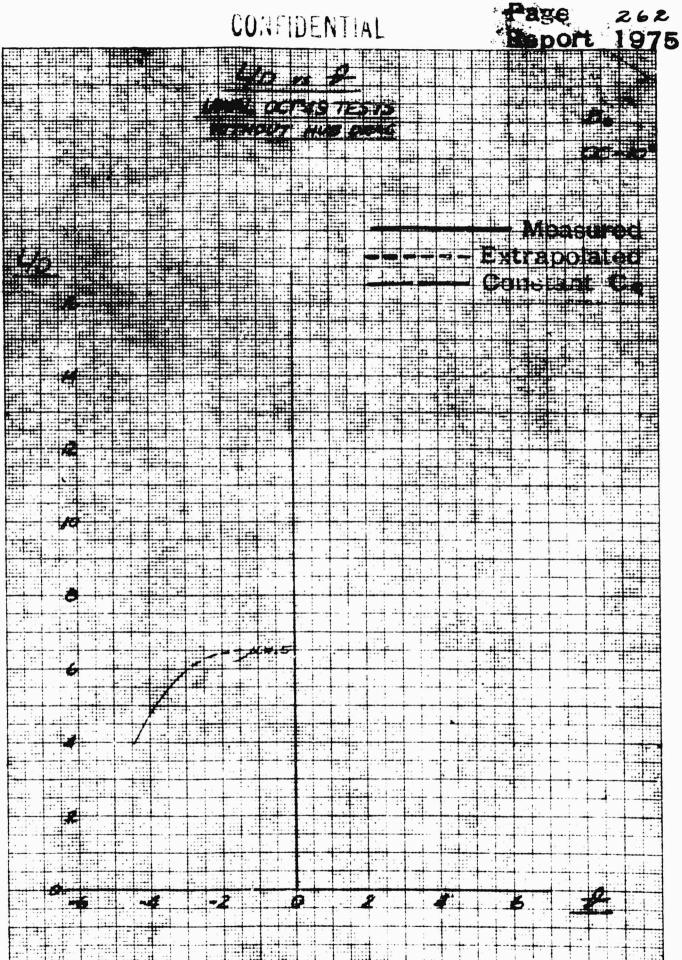






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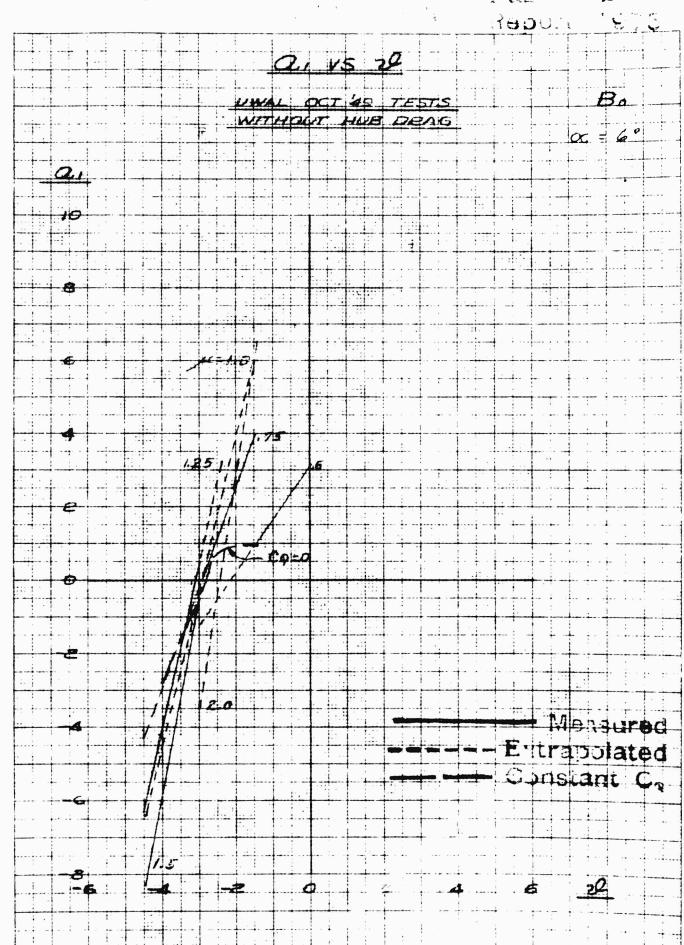
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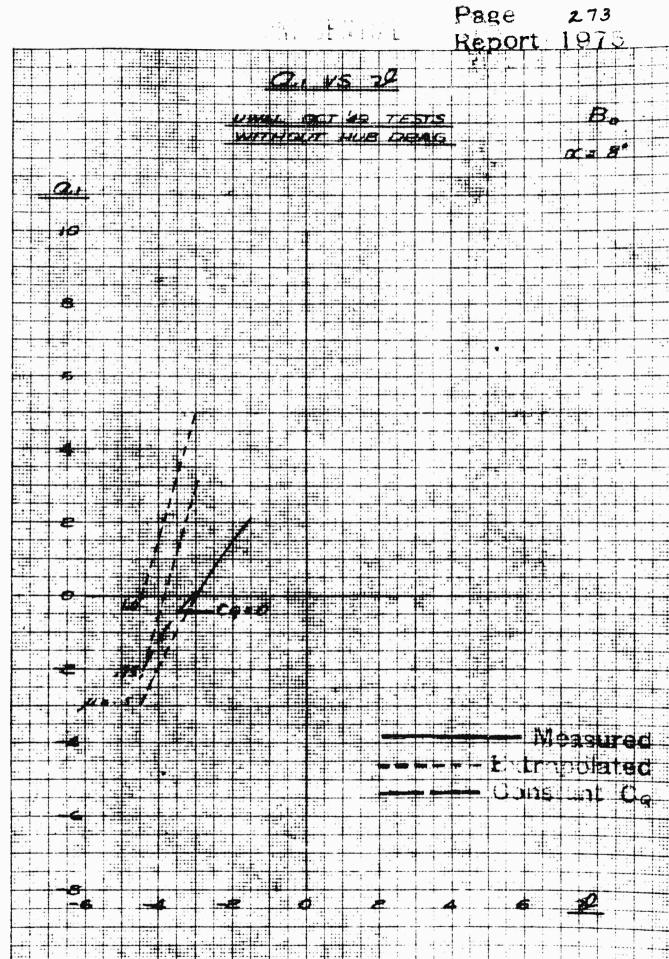
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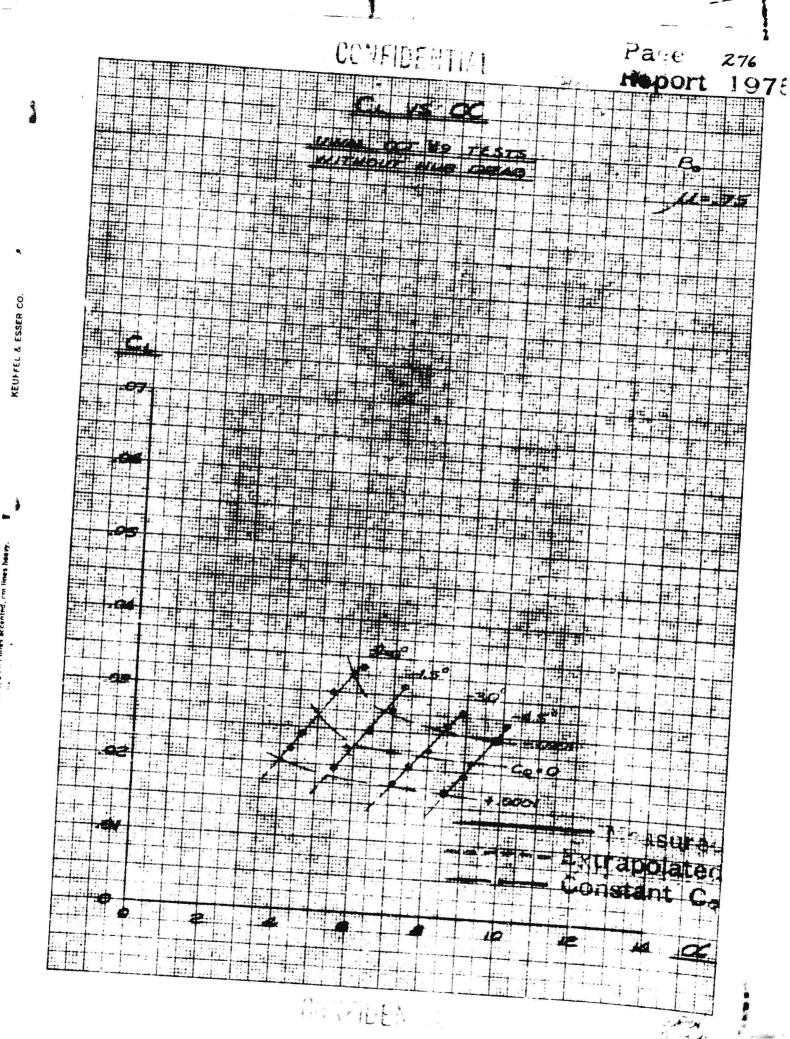
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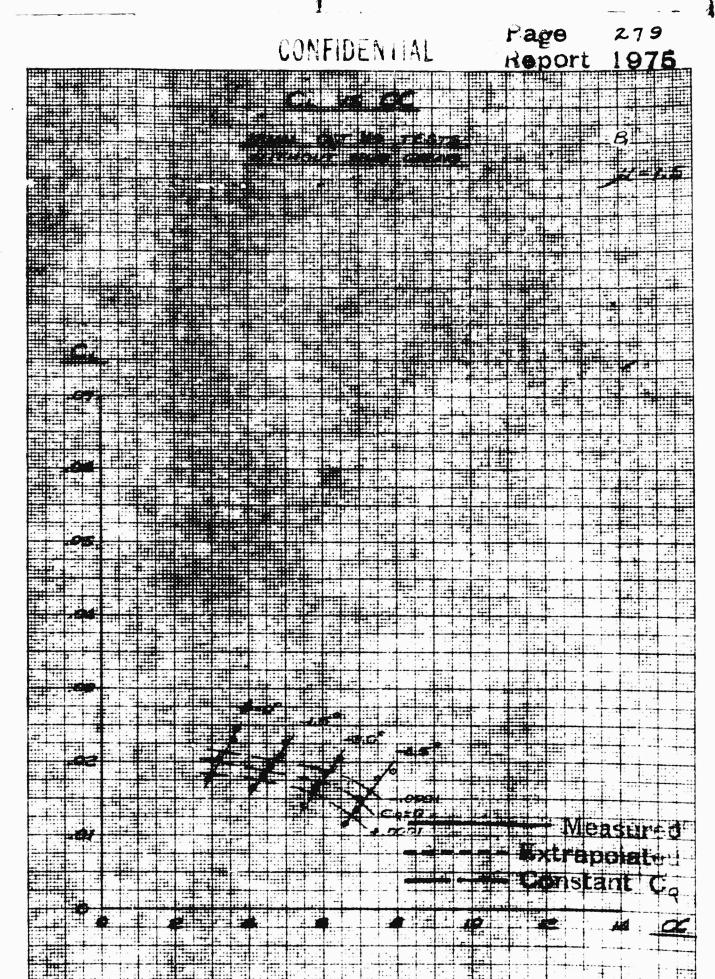
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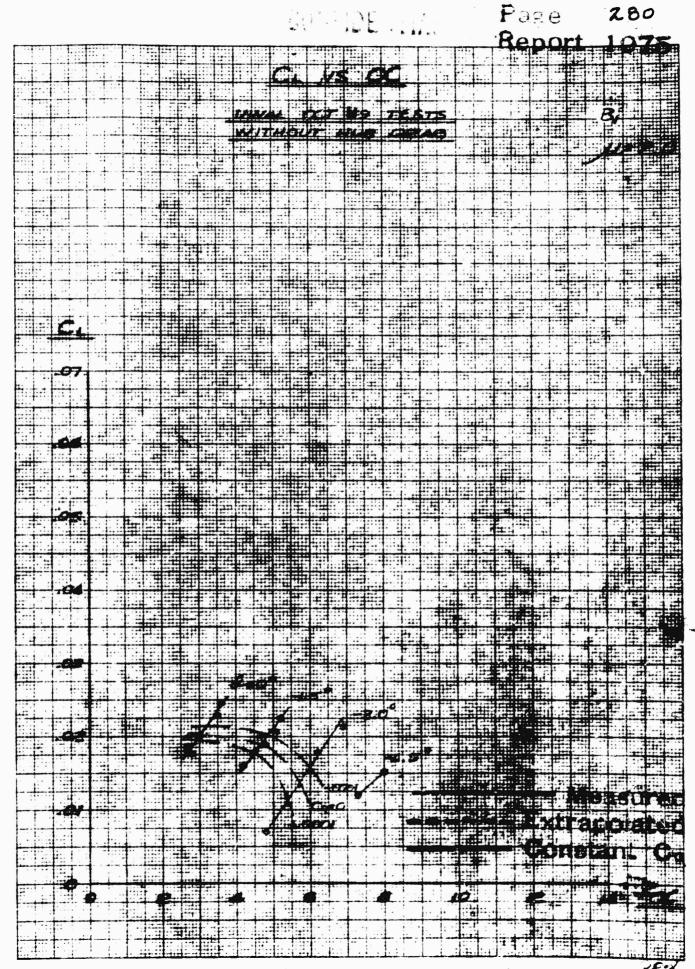
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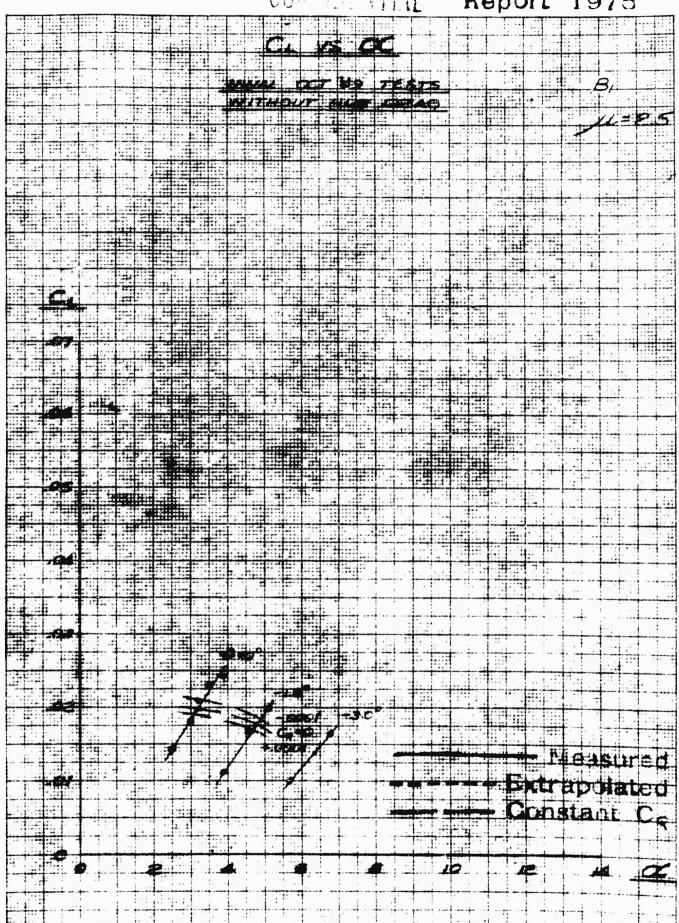


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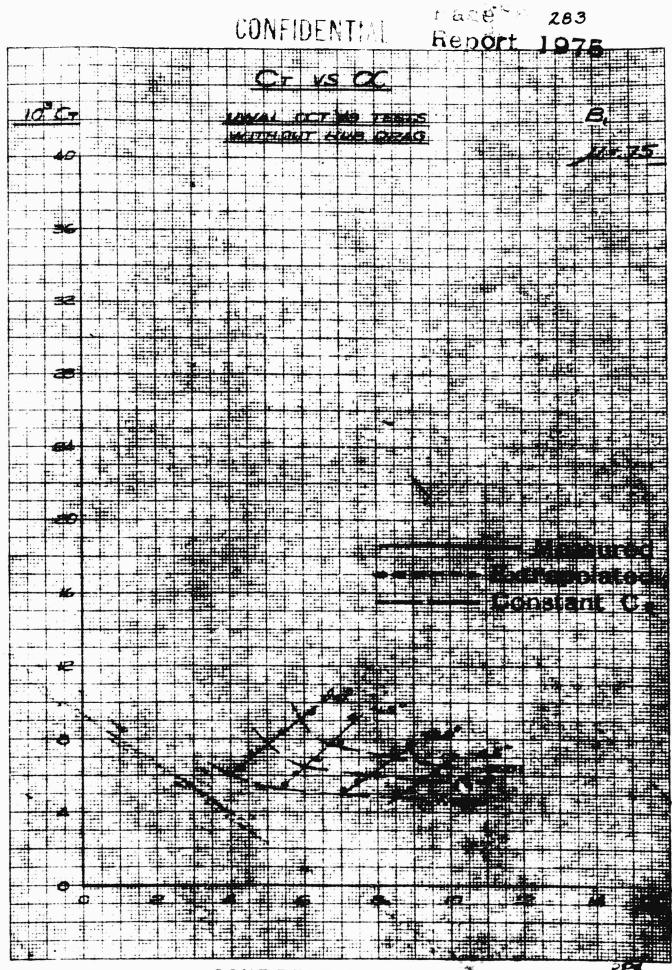
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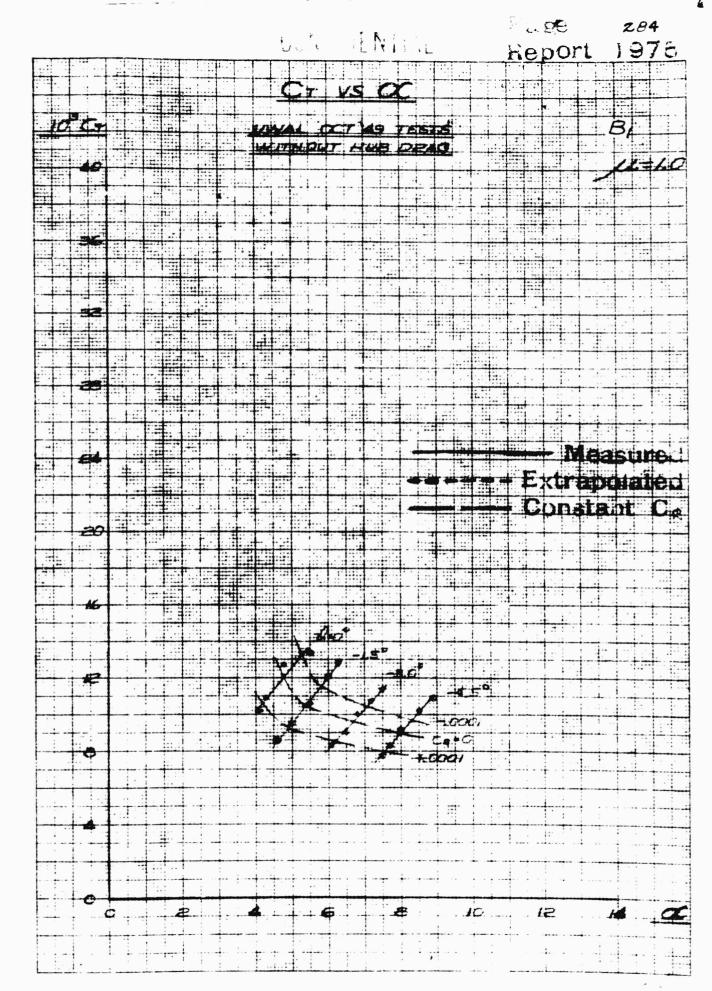
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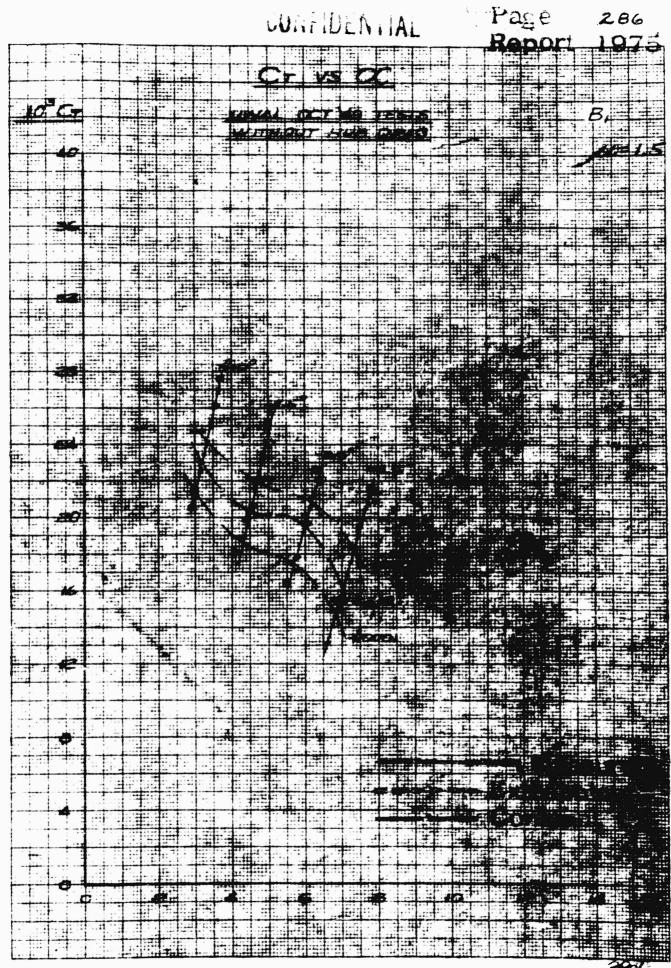


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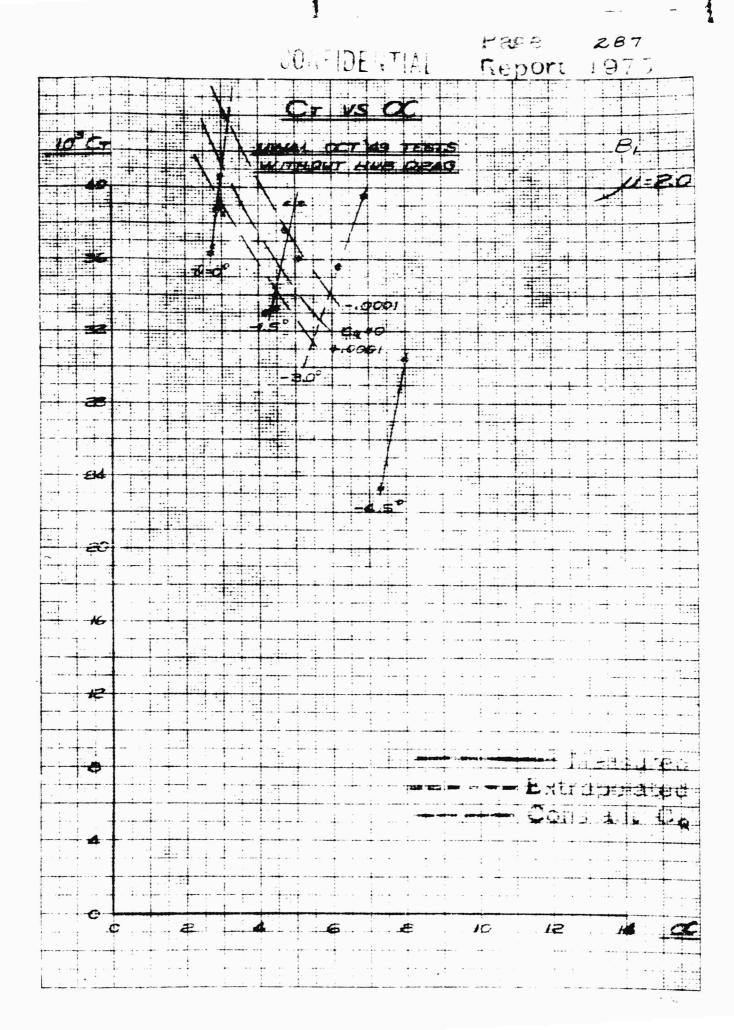
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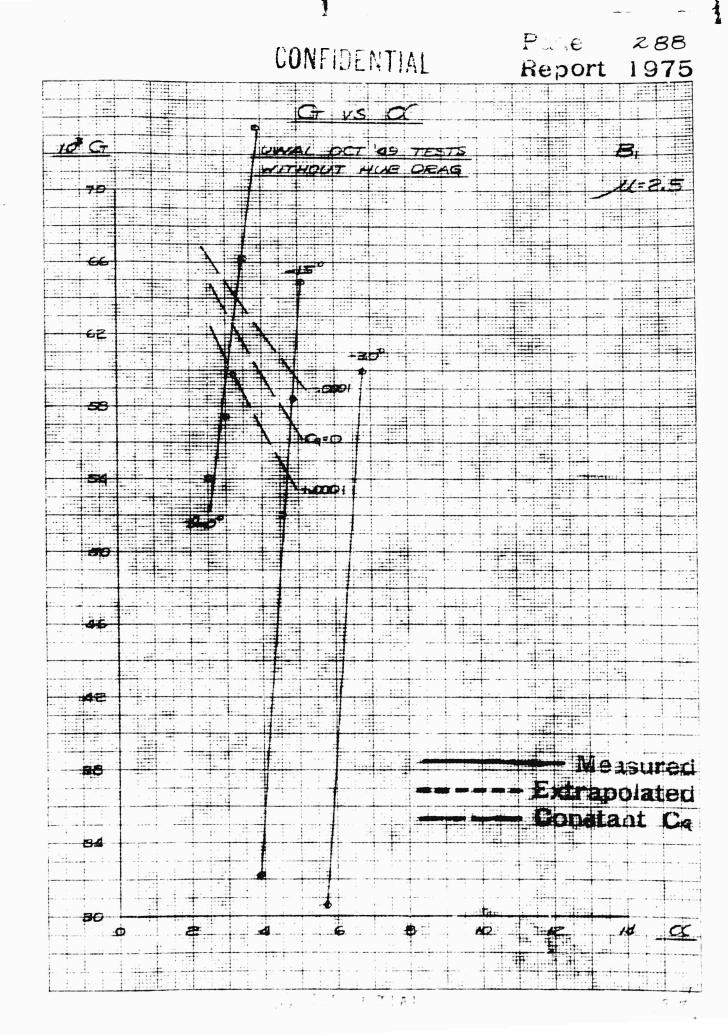


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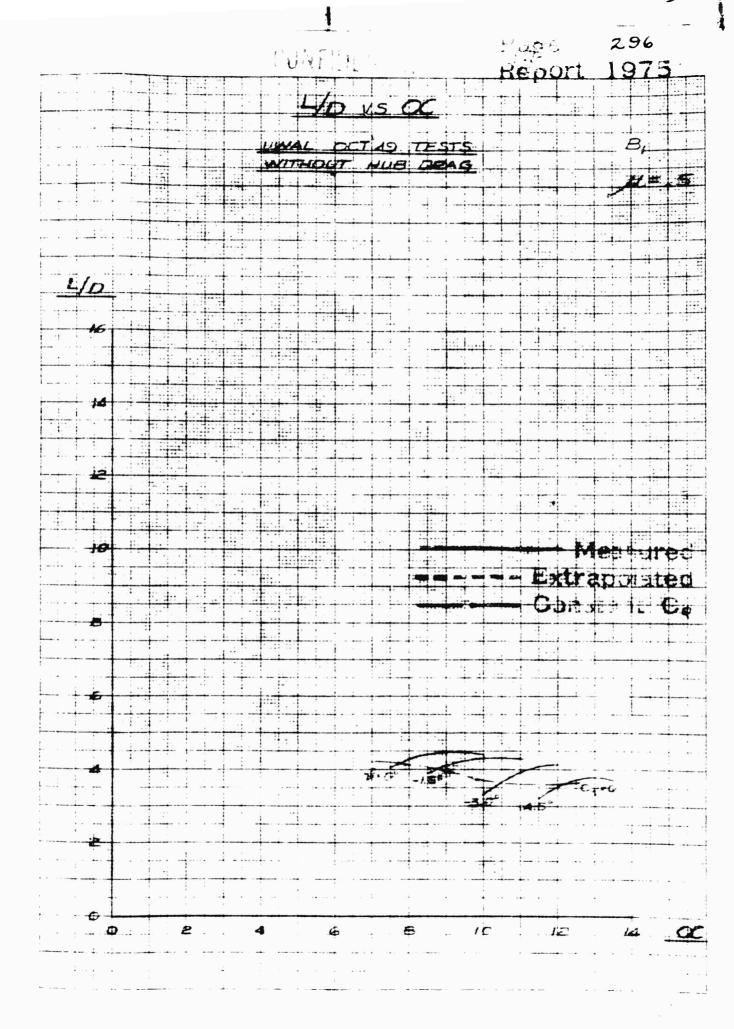
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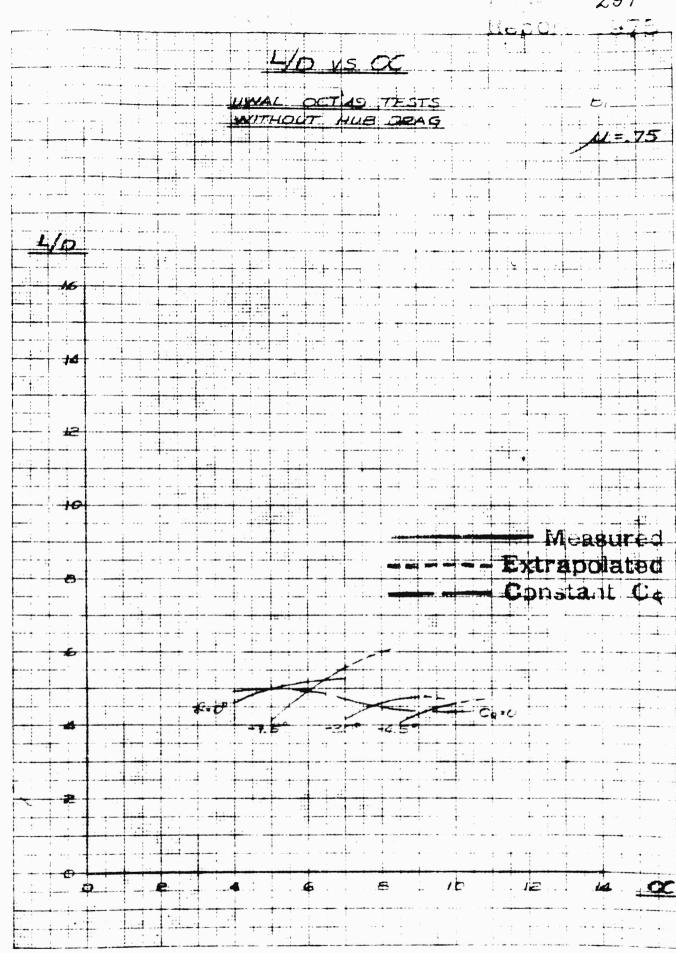
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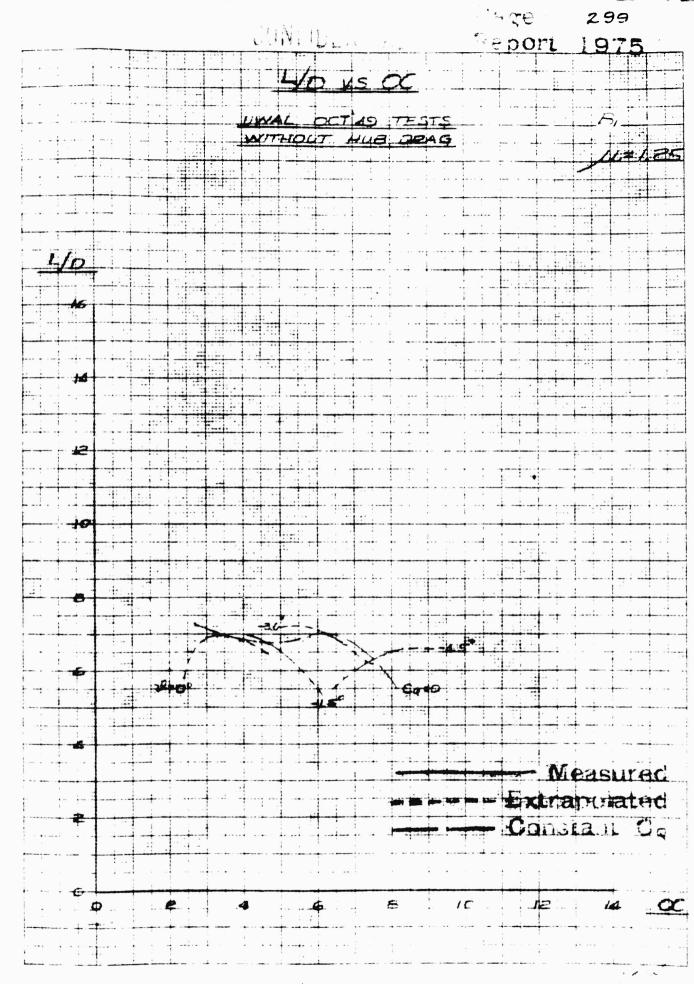
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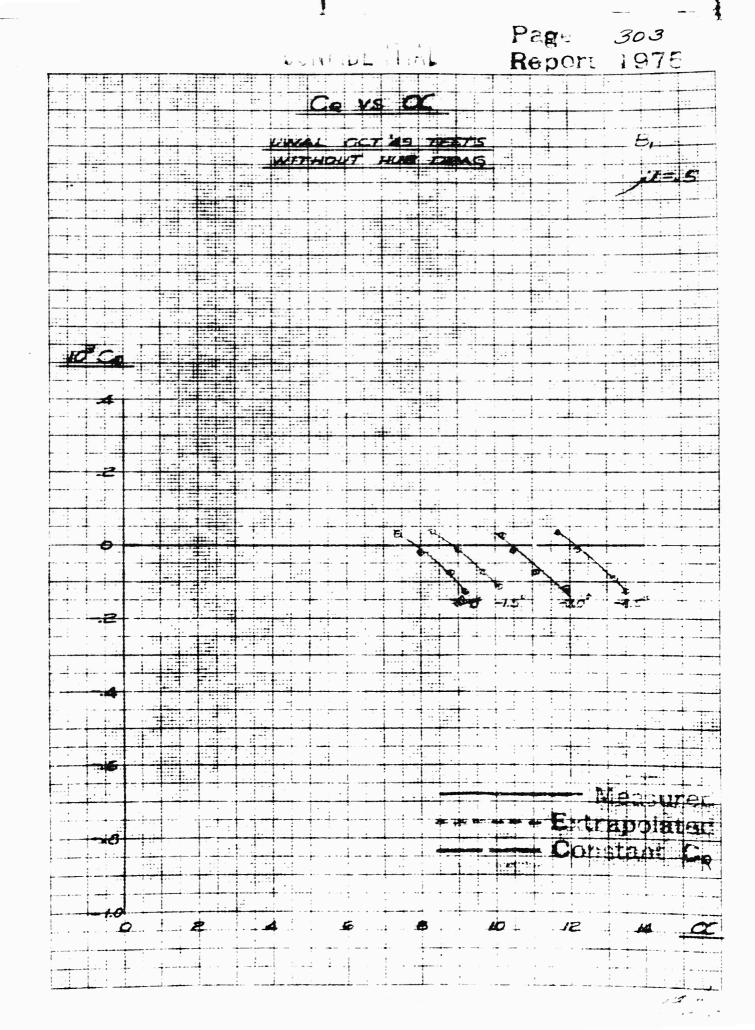
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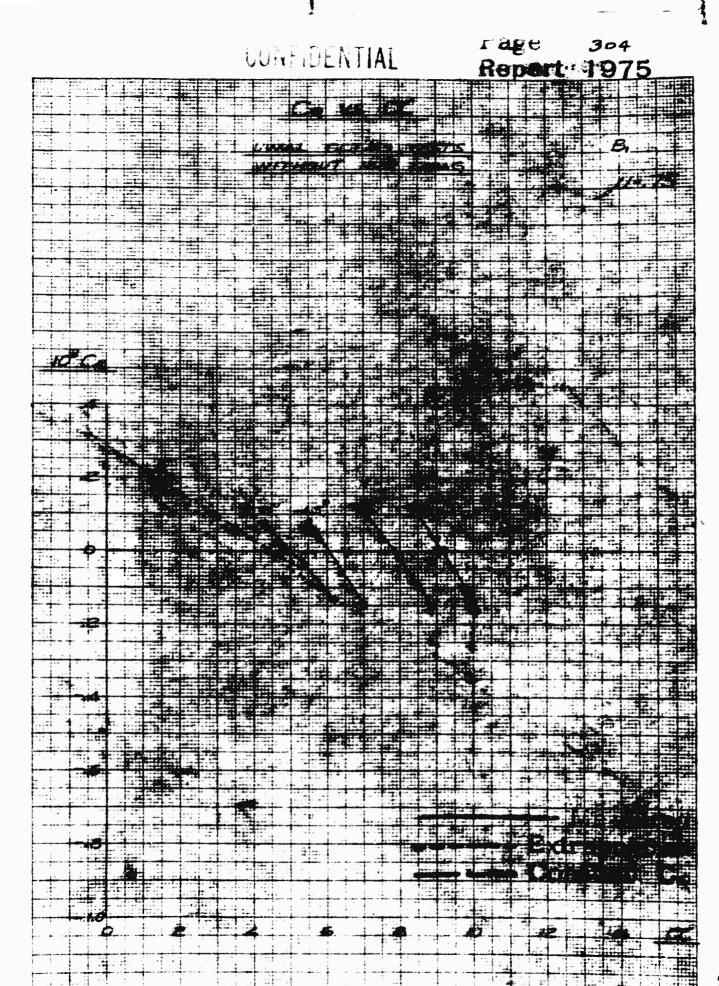
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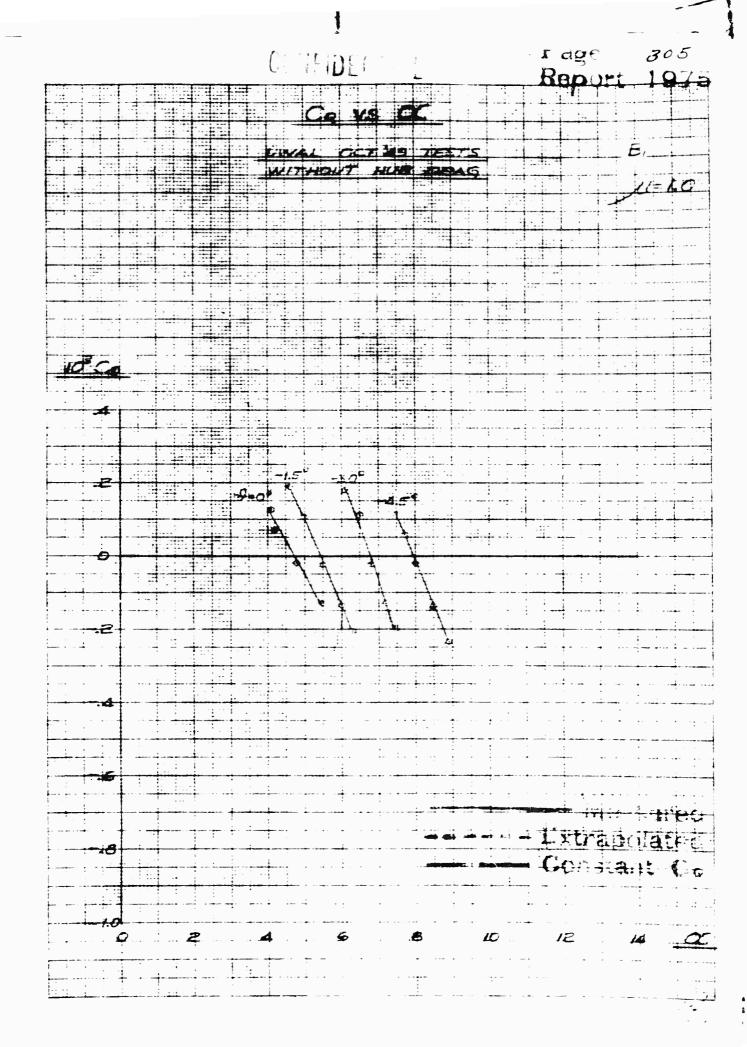
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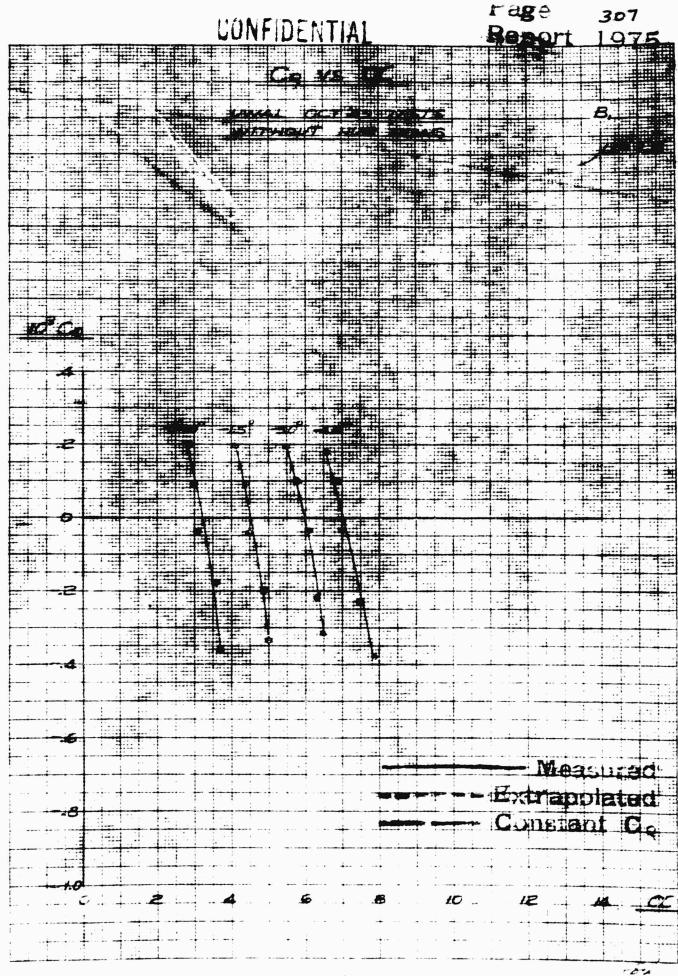


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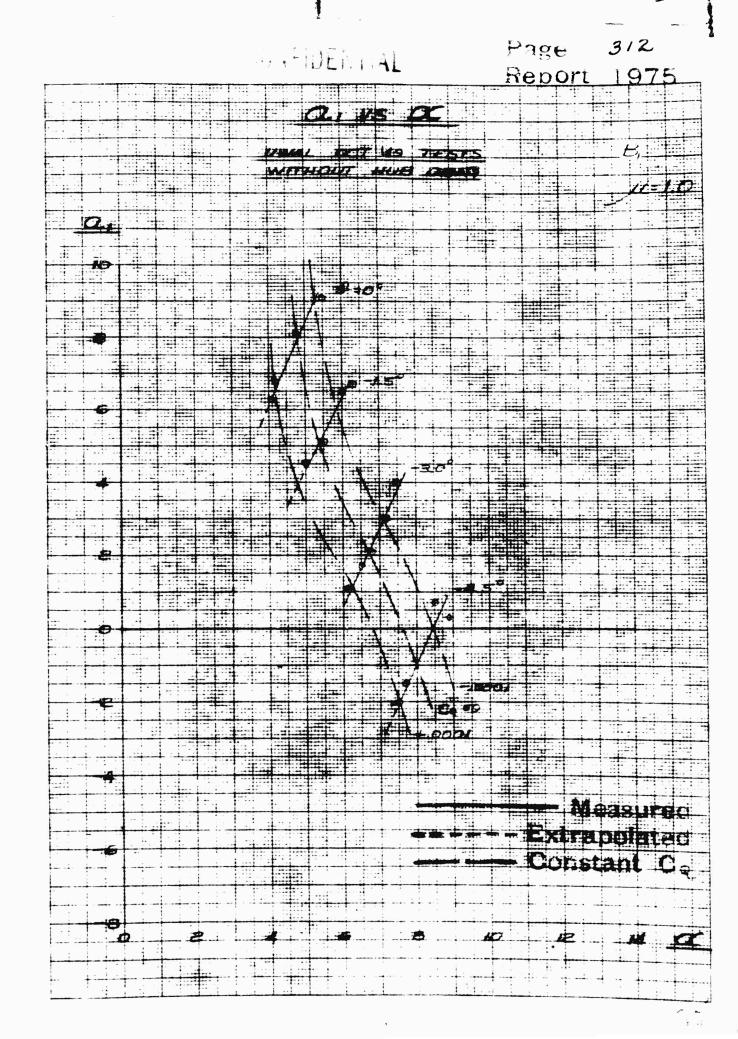
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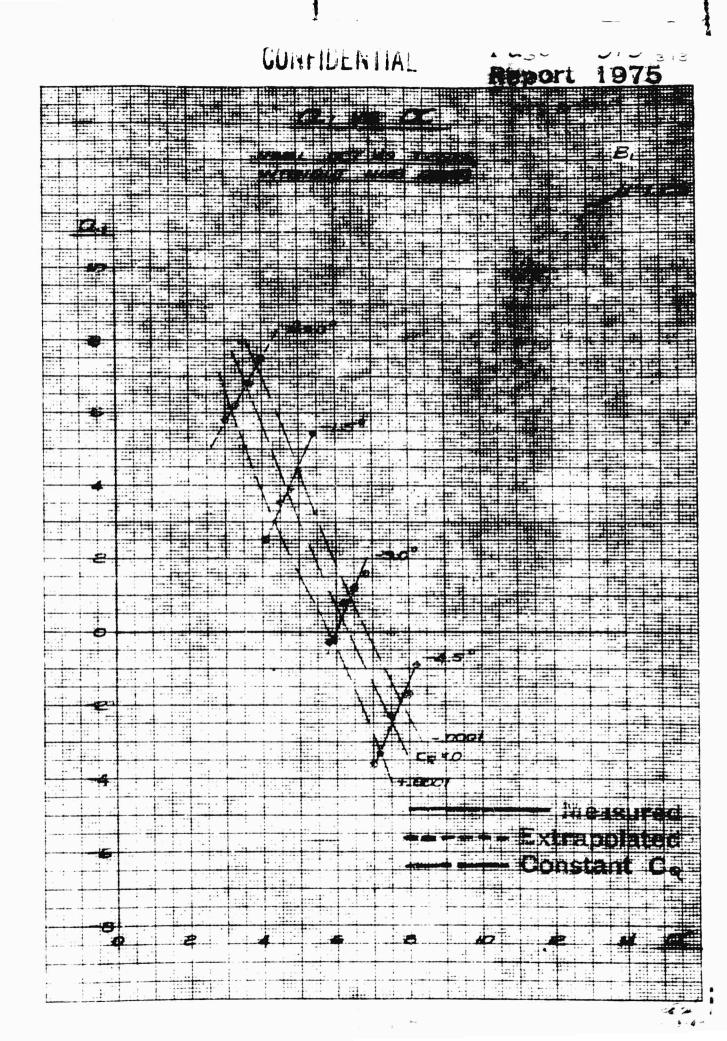
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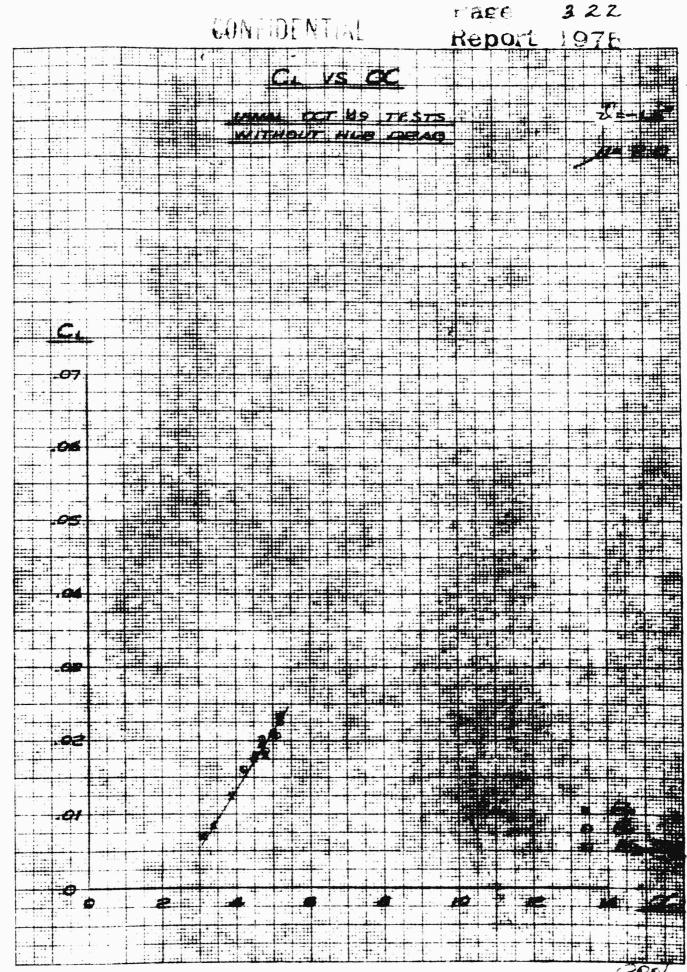
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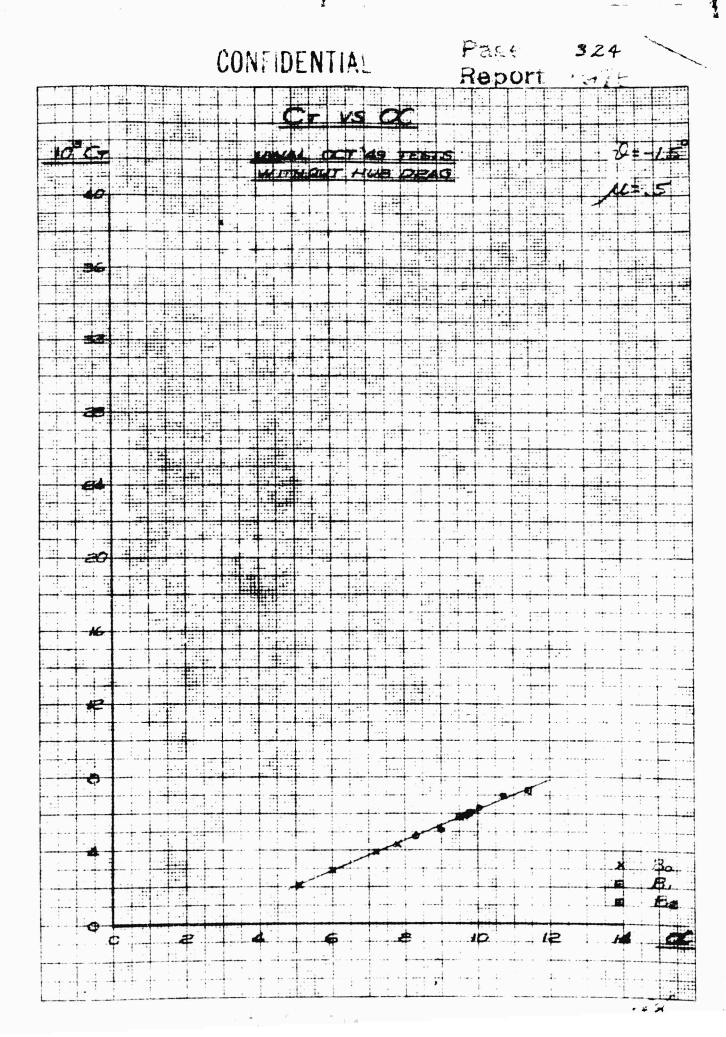
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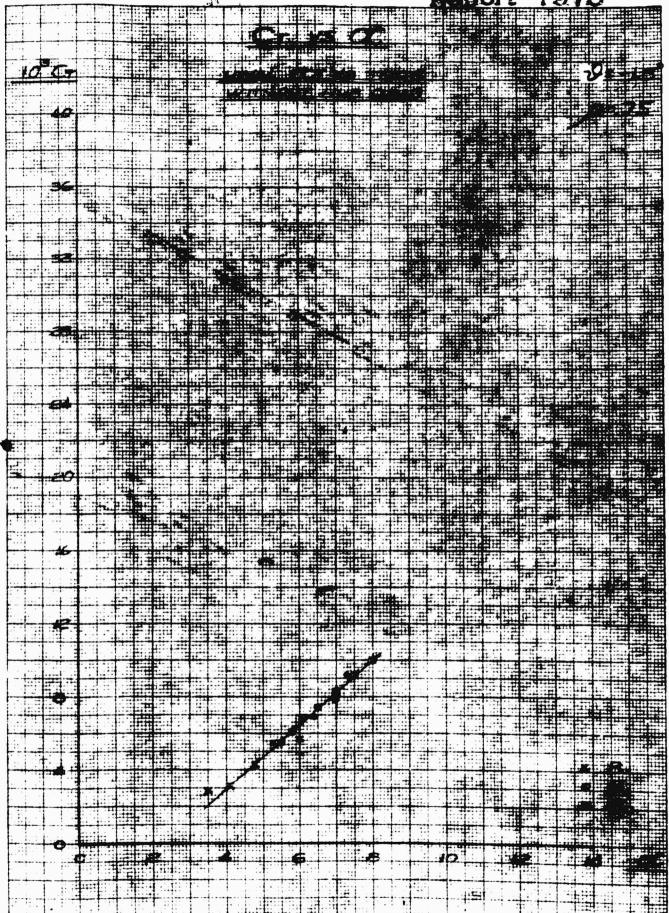
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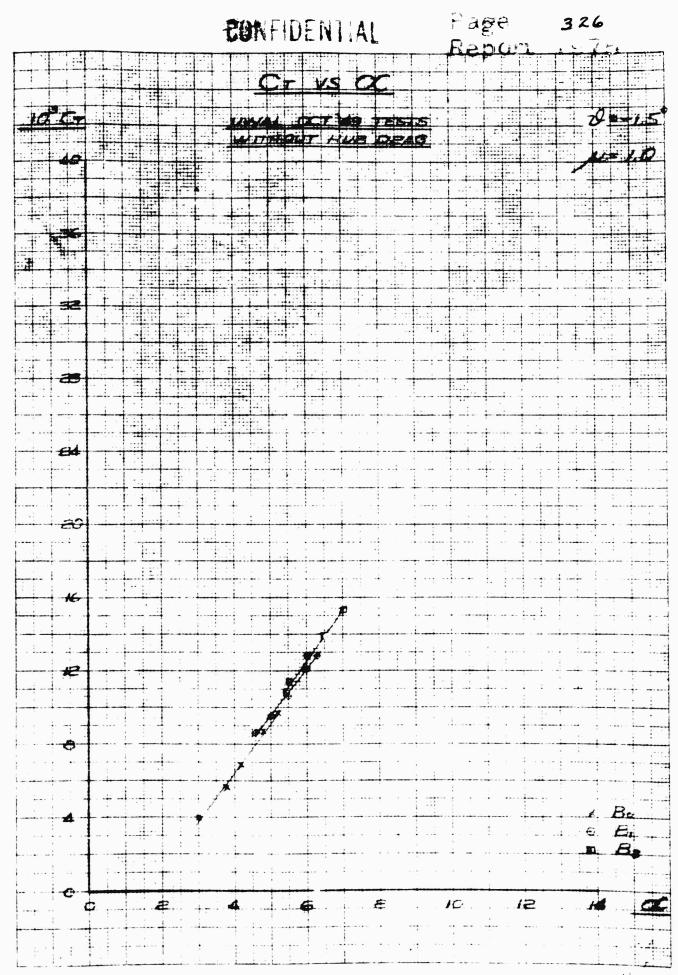
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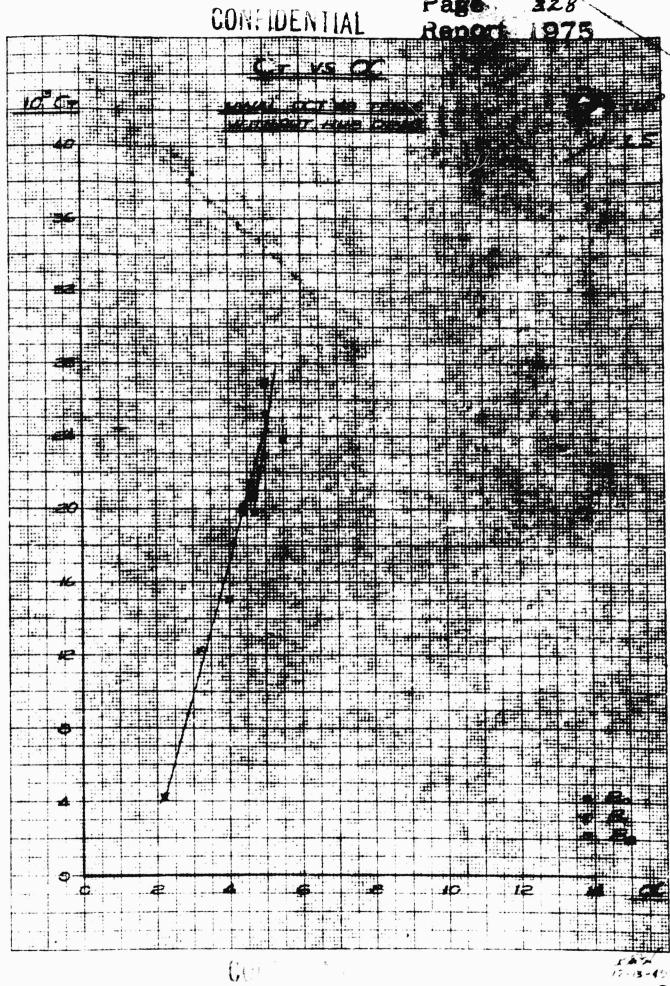
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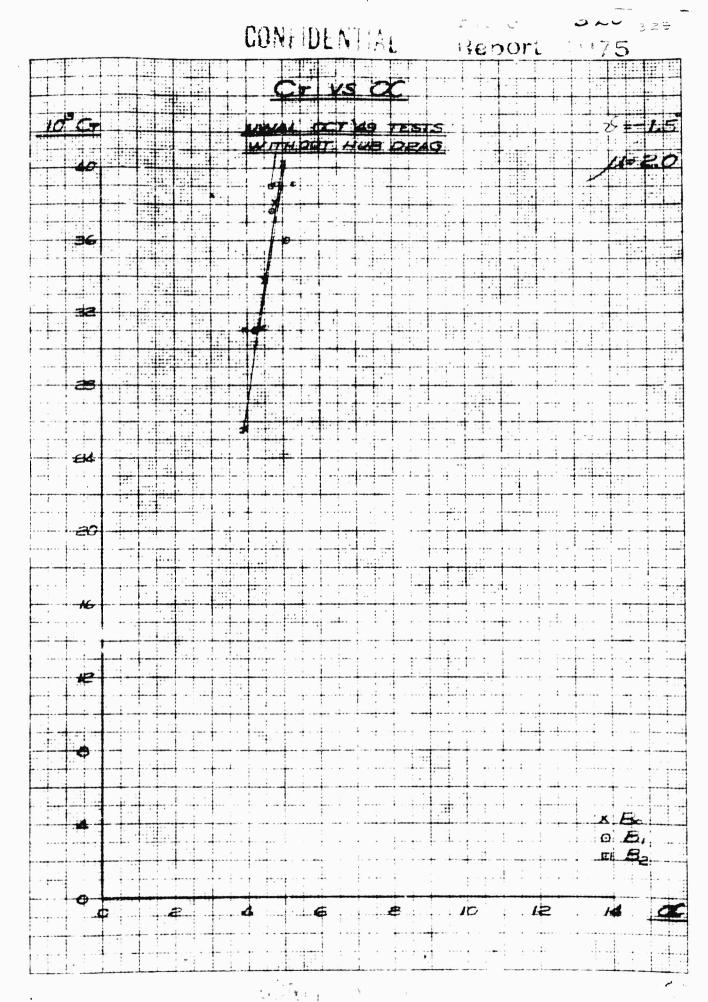
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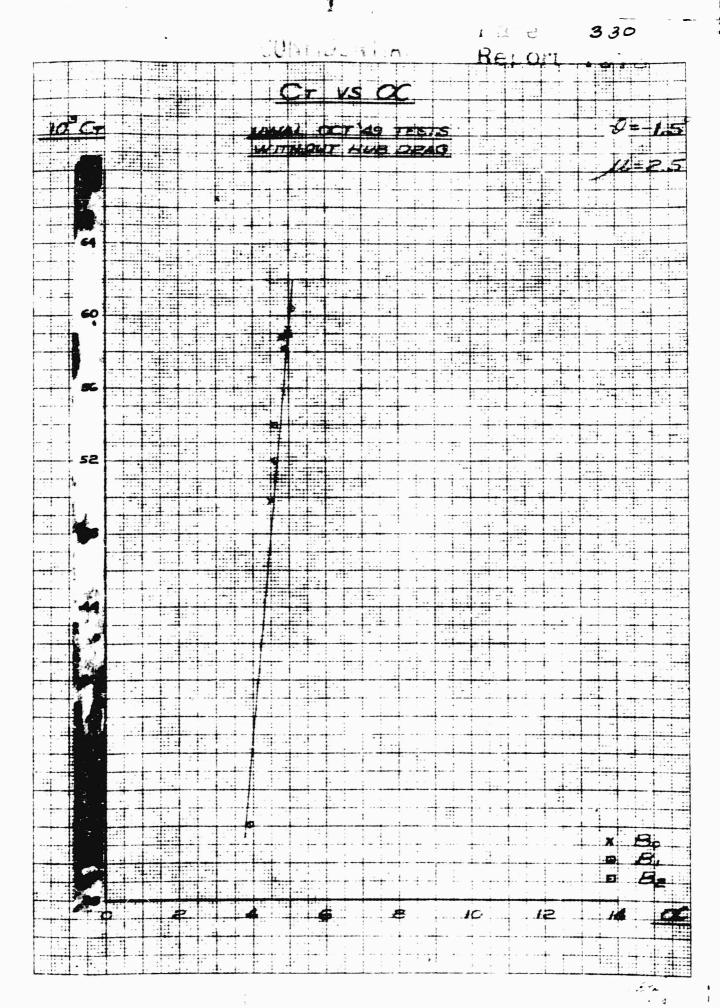




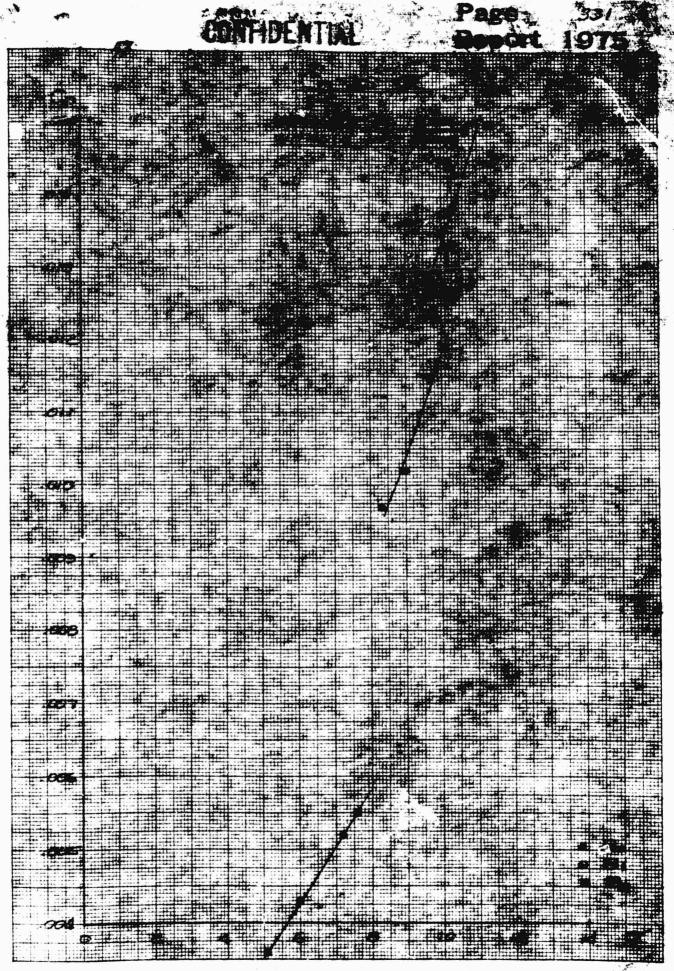
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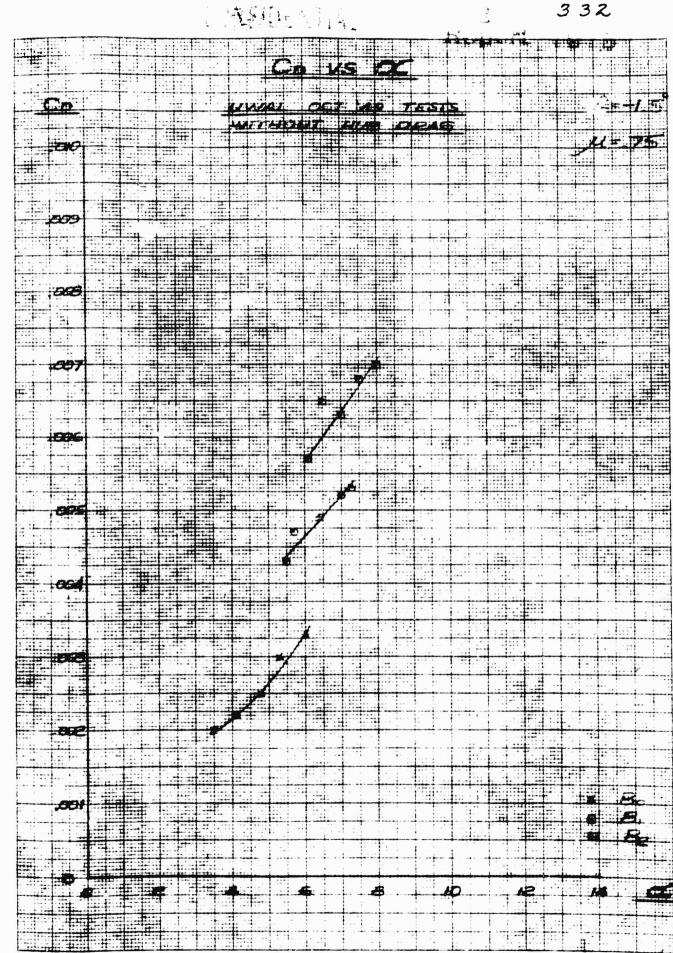




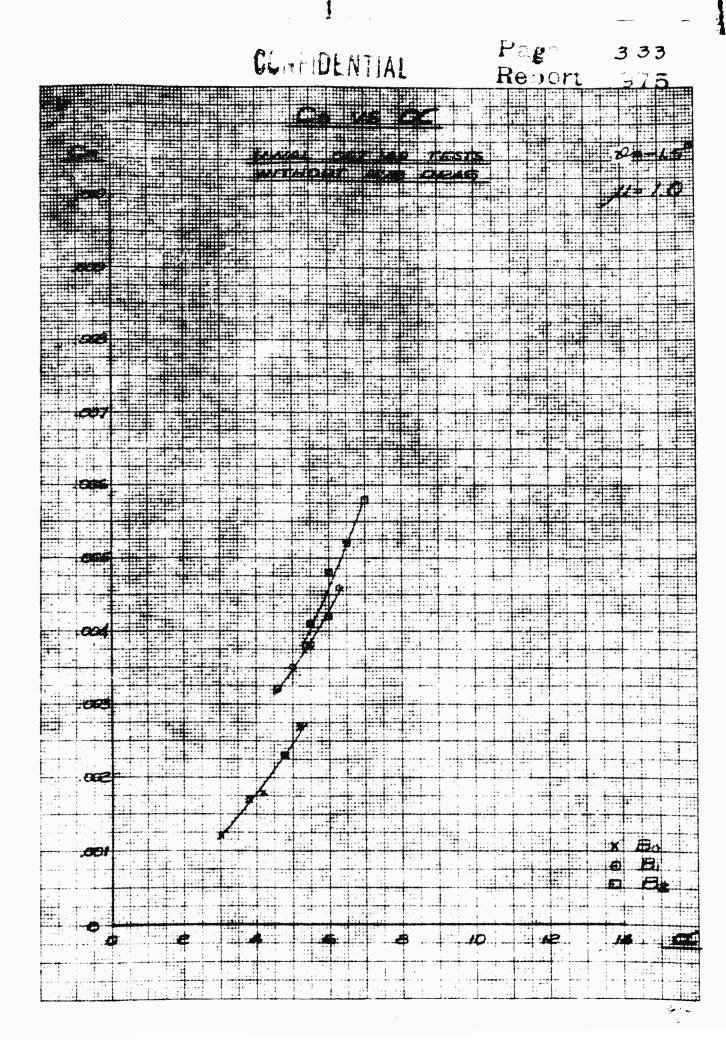
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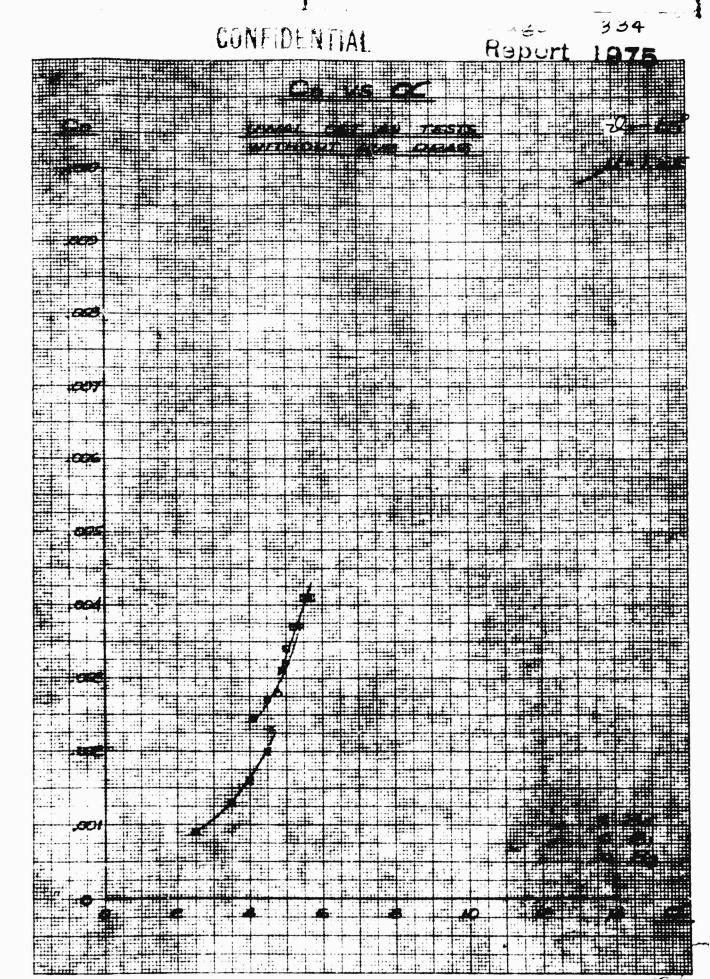


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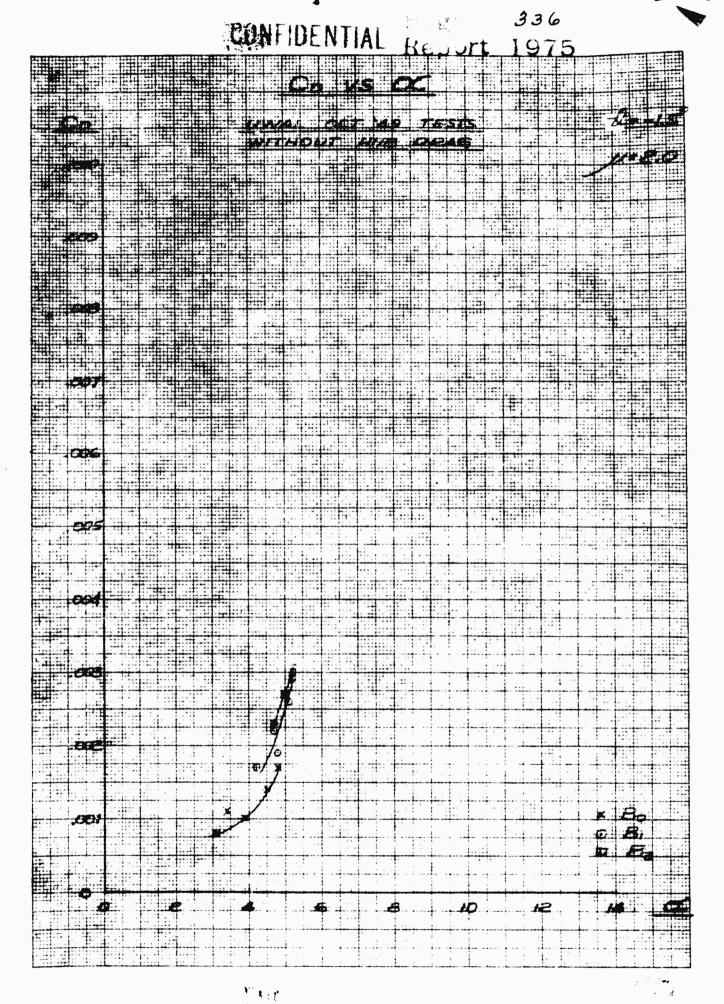




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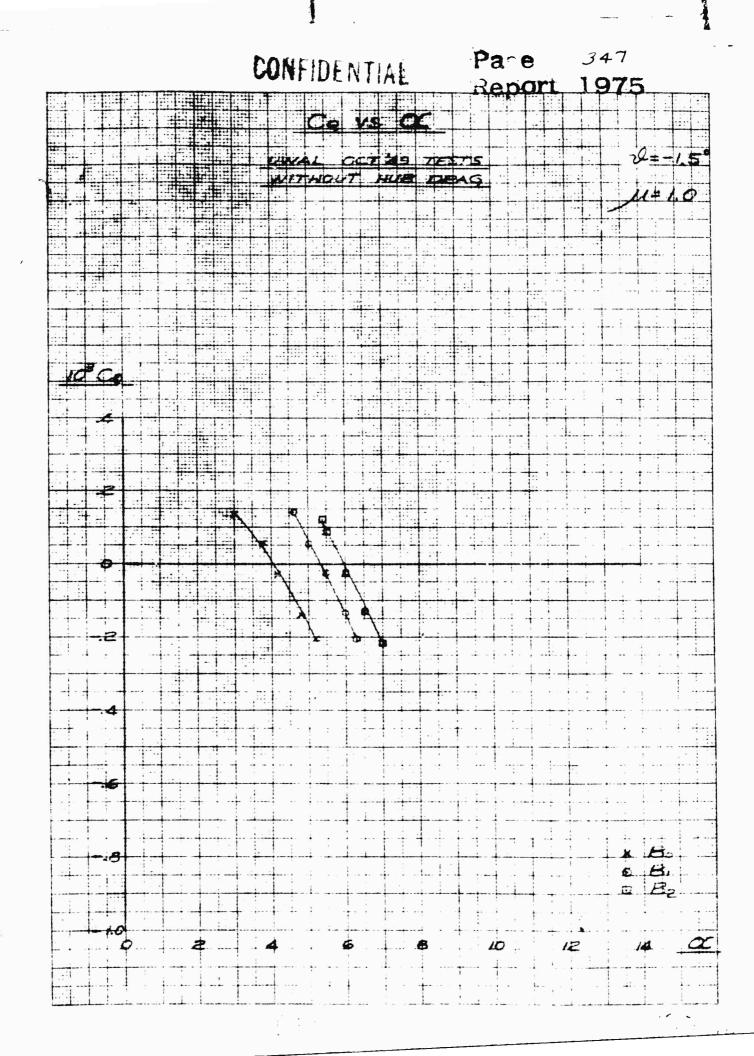
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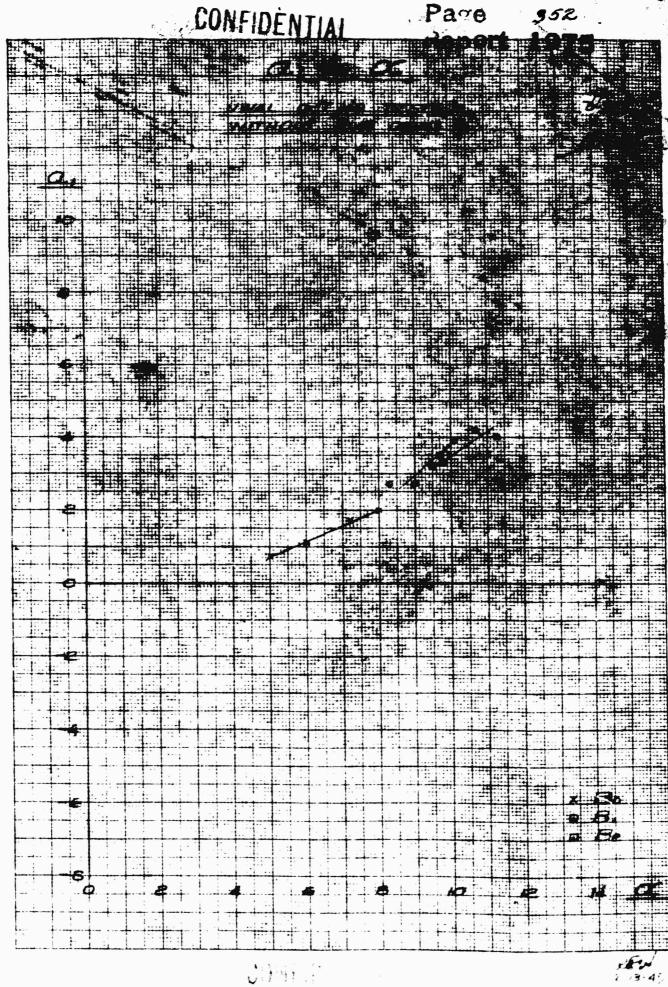
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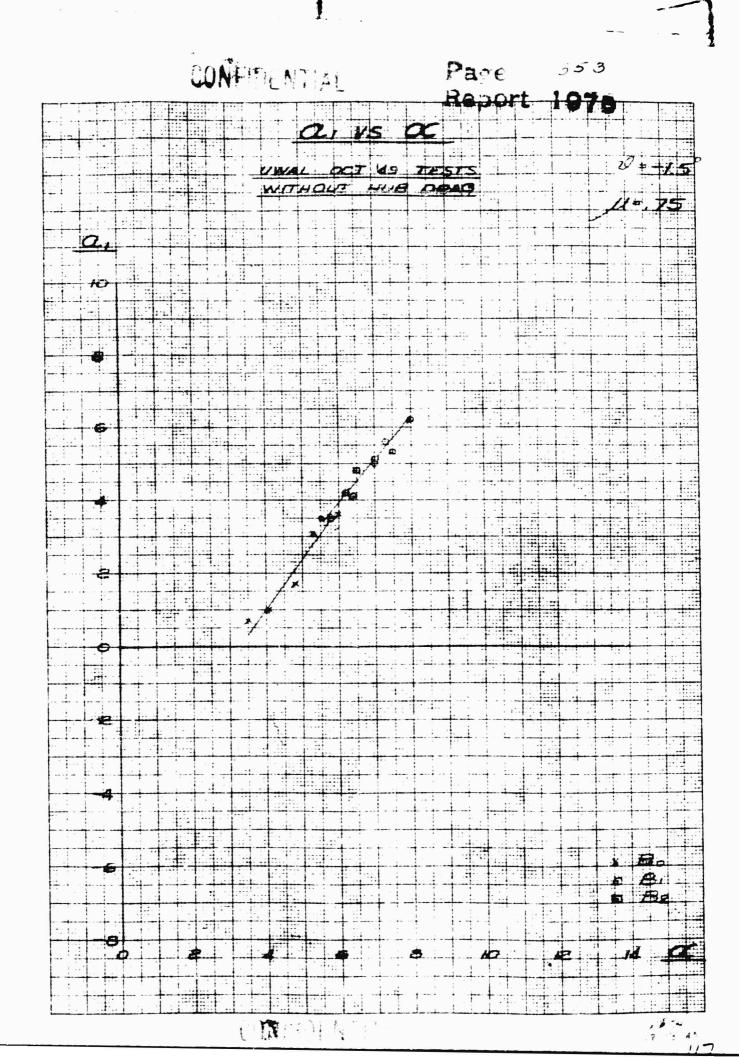
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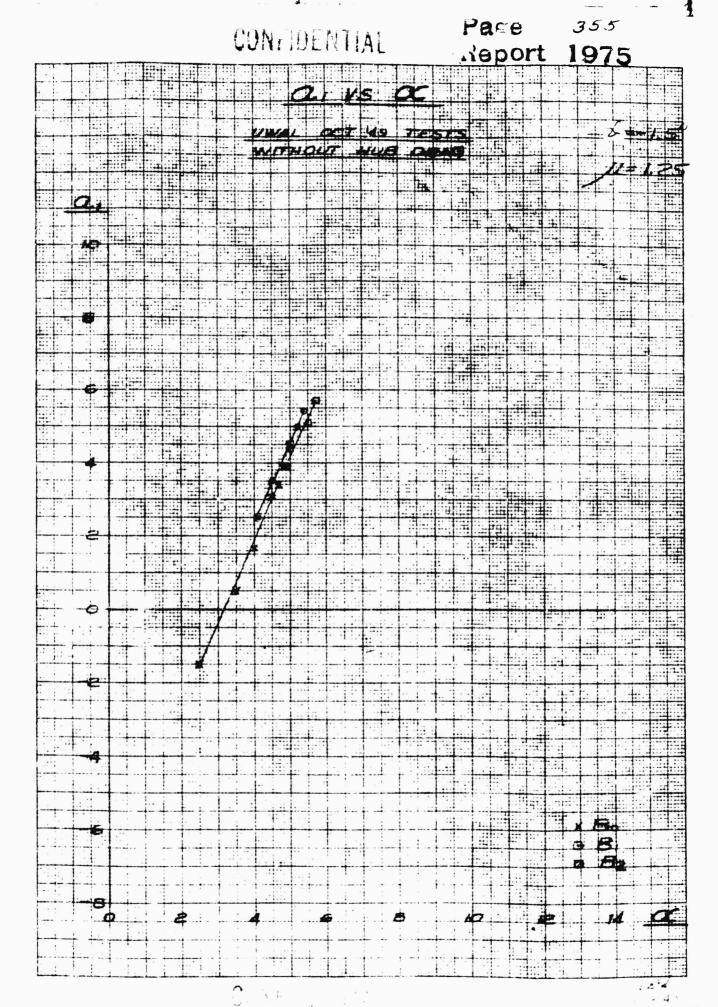
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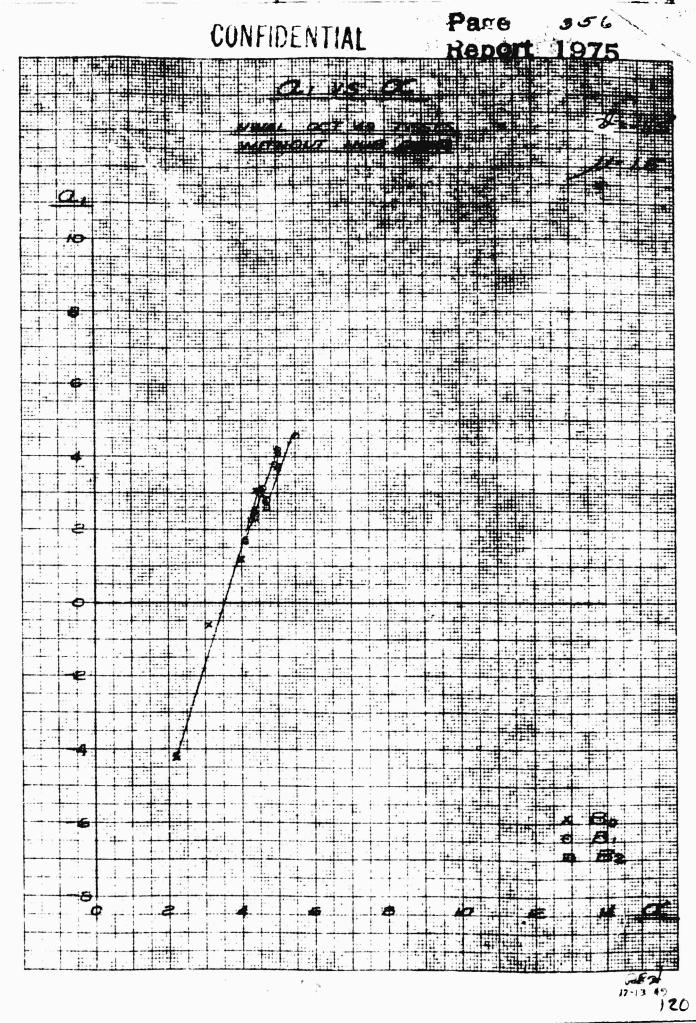
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